Optimal Quantum Sample Complexity of Learning Algorithms

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Abstract

In learning theory, the VC dimension of a concept class \( C \) is the most common way to measure its "richness." A fundamental result says that the number of examples needed to learn an unknown target concept \( c \in C \) under an unknown distribution \( D \), is tightly determined by the VC dimension \( d \) of the concept class \( C \). Specifically, in the PAC model

\[
\Theta\left(\frac{d}{\varepsilon} + \frac{\log(1/\delta)}{\varepsilon}\right)
\]

elements are necessary and sufficient for a learner to output, with probability \( 1 - \delta \), a hypothesis \( h \in C \) that is \( \varepsilon \)-close to the target concept \( c \) (measured under \( D \)). In the related agnostic model, where the samples need not come from a \( c \in C \), we know that

\[
\Theta\left(\frac{d}{\varepsilon^2} + \frac{\log(1/\delta)}{\varepsilon^2}\right)
\]

elements are necessary and sufficient to output an hypothesis \( h \in C \) that is \( \varepsilon \)-close to the best concept in \( C \).

Here we analyze quantum sample complexity, where each example is a coherent quantum state. This model was introduced by Bshouty and Jackson [BJ99], who showed that quantum examples are more powerful than classical examples in some fixed-distribution settings. However, Atıcı and Servedio [AS05], improved by Zhang [Zha10], showed that in the PAC setting (where the learner has to succeed for every distribution), quantum examples cannot be much more powerful: the required number of quantum examples is

\[
\Omega\left(\frac{d^{1-\eta}}{\varepsilon} + d + \frac{\log(1/\delta)}{\varepsilon}\right)
\]

for arbitrarily small constant \( \eta > 0 \).

Our main result is that quantum and classical sample complexity are in fact equal up to constant factors in both the PAC and agnostic models. We give two approaches. The first is a fairly simple information-theoretic argument that yields the above two classical bounds and yields the same bounds for quantum sample complexity up to a \( \log(d/\varepsilon) \) factor. We then give a second approach that avoids the log-factor loss, based on analyzing the behavior of the “Pretty Good Measurement” on the quantum state identification problems that correspond to learning. This shows classical and quantum sample complexity are equal up to constant factors.

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1 Introduction

1.1 Sample complexity and VC dimension

Machine learning is one of the most successful parts of AI, with impressive practical applications in areas ranging from image processing, speech recognition, to even beating Go champions. Its theoretical aspects have been deeply studied, revealing beautiful structure and mathematical characterizations of when (efficient) learning is or is not possible in various settings.

1.1.1 The PAC setting

Valiant’s Probably Approximately Correct (PAC) model [Val84] gives a precise complexity-theoretic definition of what it means for a concept class to be (efficiently) learnable. For simplicity we will (without loss of generality) focus on concepts that are Boolean functions, \( c : \{0, 1\}^n \rightarrow \{0, 1\} \). Equivalently, a concept \( c \) is a subset of \( \{0, 1\}^n \), namely \( \{ x : c(x) = 1 \} \).

Let \( C \subseteq \{ f : \{0, 1\}^n \rightarrow \{0, 1\} \} \) be a concept class. The goal of a learning algorithm (the learner) is to probably approximate some unknown target concept \( c \in C \) from random labeled examples. Each labeled example is of the form \((x, c(x))\) where \( x \) is distributed according to some unknown distribution \( D \) over \( \{0, 1\}^n \). After processing a number of such examples (hopefully not too many), the learner outputs some hypothesis \( h \in C \). We say that \( h \) is \( \epsilon \)-approximately correct (w.r.t. the target concept \( c \)) if its error probability under \( D \) is at most \( \epsilon \): \( \Pr_{x \sim D}[h(x) \neq c(x)] \leq \epsilon \). Note that the learning phase and the evaluation phase (i.e., whether a hypothesis is approximately correct) are according to the same distribution \( D \)—as if the learner is taught and then tested by the same teacher. An \((\epsilon, \delta)\)-learner for the concept class \( C \) is one whose hypothesis is probably approximately correct:

\[
\Pr[\text{the learner’s output } h \in C \text{ is } \epsilon\text{-approximately correct}] \geq 1 - \delta,
\]

where the probability is over the sequence of examples and the learner’s internal randomness.

Of course, we want the learner to be as efficient as possible. Its sample complexity is the worst-case number of examples it uses, and its time complexity is the worst-case running time of the learner. In this paper we focus on sample complexity. This allows us to ignore technical issues of how the runtime of an algorithm is measured, and in what form the hypothesis \( h \) is given as output by the learner.

The sample complexity of a concept class \( C \) is the sample complexity of the most efficient learner for \( C \). It is a function of \( \epsilon, \delta \), and of course of \( C \) itself. One of the most fundamental results in learning theory is that the sample complexity of \( C \) is tightly determined by a combinatorial parameter called the VC dimension of \( C \), due to and named after Vapnik and Chervonenkis [VC71]. The VC dimension of \( C \) is the size of the biggest \( S \subseteq \{0, 1\}^n \) that can be labeled in all \( 2^{|S|} \) possible ways by concepts from \( C \): for each sequence of \( |S| \) binary labels for the elements of \( S \), there is a \( c \in C \) that has that labeling.\(^1\) Knowing just this VC dimension already tells us the sample complexity of \( C \) up to constant factors. Blumer et al. [BEHW89] proved that the sample complexity of \( C \) is lower bounded by \( \Omega(d/\epsilon + \log(1/\delta)/\epsilon) \), and they proved an upper bound that was worse by only a logarithmic factor. In very recent work, Hanneke [Han15] (improving on Simon [Sim15]) got rid of this logarithmic factor, showing that the lower bound of Blumer et al. is in fact optimal: the sample complexity of \( C \) in the PAC setting is

\[
\Theta\left( \frac{d}{\epsilon} + \frac{\log(1/\delta)}{\epsilon} \right).
\]

\(^1\)Such an \( S \) is said to be shattered by \( C \).
1.1.2 The agnostic setting

The PAC model assumes that the labeled examples are generated according to a target concept \( c \in \mathcal{C} \). However, in many learning situations that is not a realistic assumption, for example when the examples are noisy in some way or when we have no reason to believe there is an underlying target concept at all. The agnostic model of learning, introduced by Haussler [Hau92] and Kearns et al. [KSS94], takes this into account. Here, the examples are generated according to a distribution \( D \) on \( \{0,1\}^{n+1} \). The error of a specific concept \( c : \{0,1\}^n \to \{0,1\} \) is defined to be \( \text{Pr}_{(x,b) \sim D}[c(x) \neq b] \), and the “Bayes classifier” is the concept \( c^* \in \mathcal{C} \) that minimizes that error under the distribution \( D \). When we are restricted to hypotheses in \( \mathcal{C} \), the Bayes classifier is the best we can do. However, it may require very many example before we can identify \( c^* \) exactly. In the spirit of the PAC model, the goal of the learner is now to output an \( h \in \mathcal{C} \) that approximates \( c^* \): an \( h \in \mathcal{C} \) whose error is at most an additive \( \epsilon \) worse than that of \( c^* \). Like in the PAC model, the optimal sample complexity of such learners is known, and tightly determined by the VC dimension of \( \mathcal{C} \): it is

\[
\Theta\left( \frac{d}{\epsilon^2} + \frac{\log(1/\delta)}{\epsilon^2} \right),
\]

where the lower bound was proven by Vapnik and Chervonenkis [VC74] (see also Simon [Sim96]), and the upper bound was proven by Talagrand [Tal94]. Shalev-Shwartz and Ben-David [SB14, Section 6.4] call Eq. (1) and Eq. (2) the “Fundamental Theorem of PAC learning.”

1.2 Our results

In this paper we are interested in quantum sample complexity. Here a quantum example for some concept \( c : \{0,1\}^n \to \{0,1\} \), according to some distribution \( D \), corresponds to an \( (n+1) \)-qubit state

\[
\sum_{x \in \{0,1\}^n} \sqrt{D(x)} |x, c(x)\rangle.
\]

In other words, instead of a random labeled example, an example is now given by a coherent quantum superposition where the square-roots of the probabilities become the amplitudes.\(^2\) This model was introduced by Bshouty and Jackson [BJ99], who showed that DNF formulas are learnable in polynomial time from quantum examples when \( D \) is uniform. For learning DNF under the uniform distribution from classical examples, the best upper bound is quasipolynomial time [Ver90]. With the added power of “membership queries,” where the learner can actively ask for the label of any \( x \) of his choice, DNF formulas are known to be learnable in polynomial time under uniform \( D \) [Jac97], but without membership queries polynomial-time learnability is a longstanding open problem (see [DS16] for a recent hardness result).

How reasonable are examples that are given as a coherent superposition rather than as a random sample? They may seem unreasonable a priori because quantum superpositions seem very fragile and are easily collapsed by measurement, but if we accept the “church of the larger Hilbert space” view on quantum mechanics, where the universe just evolves unitarily without any collapses, then they may become more palatable. It is also possible that the quantum examples are generated by some coherent quantum process that acts like the teacher.

\(^2\)We could allow more general quantum examples \( \sum_{x \in \{0,1\}^n} \alpha_x |x, c(x)\rangle \), where we only require \( |\alpha_x|^2 = D(x) \). However, that will not affect our results since our lower bounds already apply to quantum examples where we know the amplitudes are square-rooted probabilities. Adding more degrees of freedom to quantum examples does not make learning easier.
How many quantum examples are needed to learn a concept class $C$ of VC dimension $d$? Since a learner can just measure a quantum example in order to obtain a classical example, the upper bounds on classical sample complexity trivially imply the same upper bounds on quantum sample complexity. But what about the lower bounds? Are there situations where quantum examples are more powerful than classical? Indeed there are. We already mentioned the results of Bshouty and Jackson [BJ99] for learning DNF under the uniform distribution without membership queries. Another good example is the learnability of the concept class of linear functions over $\mathbb{F}_2$, $C = \{c(x) = a \cdot x : a \in \{0, 1\}^n\}$, again under the uniform distribution $D$. It is easy to see that a classical learner needs about $n$ examples to learn an unknown $c \in C$ under this $D$. However, if we are given one quantum example

$$\sum_{x \in \{0, 1\}^n} \sqrt{D(x)}|x, c(x)\rangle = \frac{1}{\sqrt{2^n}} \sum_{x \in \{0, 1\}^n} |x, a \cdot x\rangle,$$

then a small modification of the Bernstein-Vazirani algorithm [BV97] can recover $a$ (and hence $c$) with probability 1/2. Hence $O(1)$ quantum examples suffice to learn $c$ exactly, with high probability, under the uniform distribution. Atıcı and Servedio [AS09] used similar ideas to learning $k$-juntas (concepts depending on only $k$ of their $n$ variables) from quantum examples under the uniform distribution. However, PAC learning requires a learner to learn $c$ under all possible distributions $D$, not just the uniform one. The success probability of the Bernstein-Vazirani algorithm deteriorates sharply when $D$ is far from uniform. Still, this does not rule out some other quantum learner that uses $o(n)$ quantum examples and that works for all $D$.

Our main result in this paper is that quantum examples are not actually more powerful than classical labeled examples in the PAC model and in the agnostic model: we prove that the lower bounds on classical sample complexity of Eq. (1) and Eq. (2) hold for quantum examples as well. Accordingly, despite several distribution-specific speedups, sample complexity does not go down if we require our quantum learner to work for all distributions $D$. This should be contrasted with the situation when considering the time complexity of learning. Servedio and Gortler [SG04] considered a concept class (already known in the literature [KV94a, Chapter 6]) that can be PAC-learned in polynomial time by a quantum computer, even with only classical examples, but that cannot be PAC-learned in polynomial time by a classical learner unless Blum integers can be factored in polynomial time (which is widely believed to be false).

Earlier work on sample complexity had already gotten close to extending the lower bound of Eq. (1) to PAC learning from quantum examples. Atıcı and Servedio [AS05] first proved a lower bound of $\Omega(\sqrt{d}/\varepsilon + d + \log(1/\delta)/\varepsilon)$, which was subsequently improved by Zhang [Zha10] to

$$\Omega\left(\frac{d^{1-\eta}}{\varepsilon} + d + \frac{\log(1/\delta)}{\varepsilon}\right)$$

for arbitrarily small constant $\eta > 0$. (3)

Here we optimize these bounds, removing the $\eta$ and achieving the optimal lower bound for quantum sample complexity in the PAC model (Eq. (1)). We also show that the lower bound (Eq. (2)) for the agnostic model extends to quantum examples. As far as we know, in contrast to the PAC model, no earlier results were known for quantum sample complexity in the agnostic model.

We have two different proof approaches, which we sketch below.

1.2.1 An information-theoretic argument

In Section 3 we give a fairly intuitive information-theoretic argument that gives optimal lower bounds for classical sample complexity, and that gives nearly-optimal lower bounds for quantum sample complexity. Let us first see how we can prove the classical PAC lower bound of Eq. (1).
Suppose $S = \{s_0, s_1, \ldots, s_d\}$ is shattered by $C$ (we now assume VC dimension $d+1$ for ease of notation). Then we can consider a distribution $D$ that puts probability $1 - 4\epsilon$ on $s_0$ and probability $4\epsilon/d$ on each of $s_1, \ldots, s_d$. For every possible labeling $(\ell_1 \ldots \ell_d) \in \{0, 1\}^d$ of $s_1, \ldots, s_d$ there will be a concept $c \in C$ that labels $s_0$ with 0 and labels $s_i$ with $\ell_i$. Under $D$, most examples will be $(s_0, 0)$ and hence give us no information when we are learning one of those $2^d$ concepts. Suppose we have a learner that $\epsilon$-approximates $c$ with high probability under this $D$ using $T$ examples. Informally, our information-theoretic argument has the following three steps:

1. In order to $\epsilon$-approximate $c$, the learner has to learn the $c$-labels of most of the $s_1, \ldots, s_d$ (since together these have $4\epsilon$ of the $D$-weight, and we want an $\epsilon$-approximation). As all $2^d$ labelings are possible, the $T$ examples together contain $\Omega(d)$ bits of information about $c$.

2. $T$ examples give at most $T$ times as much information about $c$ as one example.

3. One example gives only $O(\epsilon)$ bits of information about $c$, because it will tell us one of the labels of $s_1, \ldots, s_d$ only with probability $4\epsilon$.

Putting these steps together implies $T = \Omega(d/\epsilon)$. This argument for the PAC setting is similar to an algorithmic-information argument of Apolloni and Gentile [AG98] and an information-theoretic argument for variants of the PAC model with noisy examples of Gentile and Helmbold [GH01].

As far as we know, this type of reasoning has not yet been applied to the sample complexity of agnostic learning. To get good lower bounds there, we consider a set of distributions $D_a$, indexed by $d$-bit string $a$. These distributions still have the property that if a learner gets $\epsilon$-close to the minimal error, then it will have to learn $\Omega(d)$ bits of information about the distribution (i.e., about $a$). Hence the first step of the argument remains the same. The second step of our argument also remains the same, and the third step shows an upper bound of $O(\epsilon^2)$ on the amount of information that the learner can get from one example. This then implies $T = \Omega(d/\epsilon^2)$. We can also reformulate this for the case where we want the expected additional error of the hypothesis over the Bayes classifier to be at most $\epsilon$, which is how lower bounds are often stated in learning theory. We emphasize that our information-theoretic proof is simpler than the proofs in [AB09, Aud09, SB14].

This information-theoretic approach recovers the optimal classical bounds on sample complexity, but also generalizes readily to the quantum case where the learner gets $T$ quantum examples. To obtain lower bounds on quantum sample complexity we use the same distributions $D$ (now given as a coherent quantum state) and basically just need to re-analyze the third step of the argument. In the PAC setting we show that one quantum example gives at most $O(\epsilon \log(d/\epsilon))$ bits of information about $c$, and in the agnostic setting it gives $O(\epsilon^2 \log(d/\epsilon))$ bits. This implies lower bounds on sample complexity that are only a logarithmic factor worse than the optimal classical bounds for the PAC setting (Eq. (1)) and the agnostic setting (Eq. (2)). This is not quite optimal yet, but already better than the previous best known lower bound (Eq. (3)). The logarithmic loss in step 3 is actually inherent in this information-theoretic argument: in some cases a quantum example can give roughly $\epsilon \log d$ bits of information about $c$, for example when $c$ comes from the concept class of linear functions.

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3We remark that the distributions used here and later in the agnostic setting for proving lower bounds on quantum sample complexity have been used in the literature before for analyzing classical sample complexity.

4The other part of the lower bound of Eq. (1) does not depend on $d$ and is fairly easy to prove.
1.2.2 A state-identification argument

In order to get rid of the logarithmic factor we then try another proof approach, which views learning from quantum examples as a quantum state identification problem: we are given \( T \) copies of the quantum example for some concept \( c \) and need to \( \epsilon \)-approximate \( c \) from this. In order to render \( \epsilon \)-approximation of \( c \) equivalent to exact identification of \( c \), we use good linear error-correcting codes, restricting to concepts whose \( d \)-bit labeling of the elements of the shattered set \( s_1,\ldots,s_d \) corresponds to a codeword. We then have \( 2^{\Omega(d)} \) possible concepts, one for each codeword, and need to identify the target concept from a quantum state that is the tensor product of \( T \) identical quantum examples.

State-identification problems have been well studied, and many tools are available for analyzing them. In particular, the so-called “Pretty Good Measurement” (PGM, also known as “square root measurement” [EF01]) is a specific measurement that one can always use for state identification, and whose success probability is no more than quadratically worse than that of the very best measurement (even better, in our application the PGM is the optimal measurement). In Section 4 we use Fourier analysis to give an exact analysis of the average success probability of the PGM on the state-identification problems that come from both the PAC and the agnostic model. This analysis could be useful in other settings as well. Here it implies that the number of quantum examples, \( T \), is lower bounded by Eq. (1) in the PAC setting, and by Eq. (2) in the agnostic setting.

Using the Pretty Good Measurement, we are also able to prove lower bounds for PAC learning under random classification noise, which models the real-world situation that the learning data can have some errors. Classically in the random classification noise model (introduced by Angluin and Laird [AL88]), instead of obtaining labeled examples \( (x,c(x)) \) for some unknown \( c \in \mathcal{C} \), the learner obtains noisy examples \( (x,b_x) \) where \( b_x = c(x) \) with probability \( 1-\eta \) and \( b_x = 1-c(x) \) with probability \( \eta \), for some noise rate \( \eta \in (0,1/2] \). Naturally, when \( \eta = 1/2 \), the learner obtains uniformly random bits of information about the target concept and cannot hope to recover \( c \) from any number of labeled examples. Similarly, in the quantum learning model we could naturally define a noisy quantum example as an \((n+1)\)-qubit state

\[
\sum_{x \in \{0,1\}^n} \sqrt{(1-\eta)D(x)|x,c(x)\rangle + \eta D(x)|x,1-c(x)\rangle}.
\]

Using the PGM, we are able to show that the quantum sample complexity of PAC learning a concept class \( \mathcal{C} \) under random classification noise model (with noise rate \( \eta \in (0,1/2] \)) is:

\[
\Omega\left(\frac{d}{(1-2\eta)^2\epsilon} + \frac{\log(1/\delta)}{(1-2\eta)^2\epsilon}\right).
\]

We remark here that the best known classical sample complexity lower bound (see [Sim96]) under the random classification noise (with noise rate \( \eta \)) is equal to the quantum sample complexity lower bound proven in Eq. (4).

1.3 Related work

In this paper we focus on sample complexity, which is a fundamental information-theoretic quantity. Sample complexity concerns a form of passive, or “supervised” learning: the learner gets a number of examples at the start of the process, and then has to extract enough information about the target concept from these. We may also consider more active, “unsupervised” learning settings, in particular ones where the learner can make membership queries (i.e., learn the label
Servedio and Gortler [SG04] showed that in this setting, classical and quantum complexity are polynomially related. They also exhibit an example of a factor-$n$ speed-up from quantum membership queries using the Bernstein-Vazirani algorithm. Jackson et al. [JTY02] showed how quantum membership queries can improve Jackson’s classical algorithm for learning DNF with membership queries under the uniform distribution [Jac97].

For quantum exact learning (which is also referred to as the oracle identification problem in the quantum literature), Kothari [Kot14] resolved a conjecture of Hunziker et al. [HMP+10], that states that for any concept class $C$, the number of quantum membership queries required to exactly identify a concept $c \in C$ is $O\left(\frac{\log |C|}{\sqrt{\gamma_C}}\right)$, where $\gamma_C$ is a combinatorial parameter of the concept class $C$ which we shall not define here (see [AS05] for a precise definition). Montanaro [Mon12] showed how low-degree polynomials over a finite field can be identified more efficiently using quantum algorithms.

In many ways the time complexity of learning is at least as important as the sample complexity. We already mentioned that Servedio and Gortler [SG04] exhibited a concept class based on factoring Blum integers that can be learned in quantum polynomial time but not in classical polynomial time, unless Blum integers can be factored efficiently. Under the weaker (but still widely believed) assumption that one-way functions exist, they exhibited a concept class that can be learned exactly in polynomial time using quantum membership queries, but takes superpolynomial time to learn from classical membership queries. Gavinsky [Gav12] introduced a model of learning called “Predictive Quantum” (PQ), a variation of quantum PAC learning, and exhibited a relational concept class that is polynomial-time learnable in PQ, while any “reasonable” classical model requires an exponential number of classical examples to learn the concept class.

Aïmeur et al. [ABG06, ABG13] consider a number of quantum algorithms in learning contexts such as clustering via minimum spanning tree, divisive clustering, and $k$-medians, using variants of Grover’s algorithm [Gro96] to improve the time complexity of the analogous classical algorithms. Recently, there have been some quantum machine learning algorithms based on the HHL algorithm [HHL09] for solving (in a weak sense) very well-behaved linear systems. However, these algorithms often come with some fine print that limits their applicability, and their advantage over classical is not always clear. We refer to Aaronson [Aar15] for references and caveats. There has also been some work on quantum training of neural networks [WKS14, WKS16].

In addition to learning classical objects such as Boolean functions, one may also study the learnability of quantum objects. In particular, Aaronson [Aar07] studied how well $n$-qubit quantum states can be learned from measurement results. In general, an $n$-qubit state $\rho$ is specified by $\exp(n)$ many parameters, and $\exp(n)$ measurement results on equally many copies of $\rho$ are needed to learn a good approximation of $\rho$ (say, in trace distance). However, Aaronson showed an interesting and surprisingly efficient PAC-like result: from $O(n)$ measurement results, with measurements chosen i.i.d. according to an unknown distribution $D$ on the set of all possible two-outcome measurements, we can learn an $n$-qubit quantum state $\tilde{\rho}$ that has roughly the same expectation value as $\rho$ for “most” possible two-outcome measurements. In the latter, “most” is again measured under $D$, just like in the usual PAC learning error of the learner’s hypothesis is evaluated under the same distribution $D$ that generated the learner’s examples. Accordingly, $O(n)$ rather than $\exp(n)$ measurement results suffice to approximately learn an $n$-qubit state for most practical purposes.

The use of Fourier analysis in analyzing the success probability of the Pretty Good Measurement in quantum state identification appears in a number of earlier works. By considering the dihedral hidden subgroup problem (DHSP) as a state identification problem, Bacon et al. [BCD06] show that the PGM is the optimal measurement for DHSP and prove a lower bound on the sample
complexity of $\Omega(\log|G|)$ for a dihedral group $G$ using Fourier analysis. Ambainis and Montano [AM14] view the “search with wildcard” problem as a state identification problem. Using ideas similar to ours, they show that the $(x, y)$-th entry of the Gram matrix for the ensemble only depends on the Hamming distance between $x$ and $y$, which allows them to use Fourier analysis to obtain an upper bound on the success probability of the state identification problem using the PGM.

1.4 Organization

In Section 2 we formally define the classical and quantum learning models and introduce the Wrong Good Measurement. In Section 3 we prove our information-theoretic lower bounds both for classical and quantum learning. In Section 4 we prove an optimal quantum lower bound for PAC and agnostic learning by viewing the learning process as a state identification problem. We conclude in Section 5 with a conclusion of the results and some open questions for further work.

2 Preliminaries

2.1 Notation

Let $[n] = \{1, \ldots, n\}$. For $x, y \in \{0, 1\}^d$, the bit-wise sum $x + y$ is over $\mathbb{F}_2$, the Hamming distance $d_H(x, y)$ is the number of indices on which $x$ and $y$ differ, $|x + y|$ is the Hamming weight of the string $x + y$ (which equals $d_H(x, y)$), and $x \cdot y = \sum_i x_i y_i$ (where the sum is over $\mathbb{F}_2$). For an $n$-dimensional vector space, the standard basis is denoted by $[e_i \in \{0, 1\}^n : i \in [n]]$, where $e_i$ is the vector with a 1 in the $i$-th coordinate and 0’s elsewhere. We write log for logarithm to base 2, and ln for base $e$. We will often use the bijection between the sets $[0, 1]^k$ and $[2^k]$ throughout this paper. Let $1_{[A]}$ be the indicator for an event $A$, and let $\delta_{x,y} = 1_{[x=y]}$. We denote random variables in bold, such as $\mathbf{A}, \mathbf{B}$.

For a Boolean function $f : \{0, 1\}^n \rightarrow \{0, 1\}$ and $M \in \mathbb{F}_2^{m \times k}$, we define $f \circ M : \{0, 1\}^k \rightarrow \{0, 1\}$ as $(f \circ M)(x) := f(Mx)$ (where the matrix-vector product is over $\mathbb{F}_2$) for all $x \in \{0, 1\}^k$. For a distribution $D : \{0, 1\}^n \rightarrow \{0, 1\}$, let $\text{supp}(D) = \{x \in [0, 1]^n : D(x) \neq 0\}$. By $x \sim D$, we mean $x$ is sampled according to the distribution $D$, i.e., $\Pr[X = x] = D(x)$.

If $M$ is a positive semidefinite (psd) matrix, we define $\sqrt{M}$ as the unique psd matrix that satisfies $\sqrt{M} \cdot \sqrt{M} = M$, and $\sqrt{M(i,j)}$ as the $(i,j)$-th entry of $\sqrt{M}$. For a matrix $A \in \mathbb{R}^{m \times n}$, we denote the singular values of $A$ by $\sigma_1(A) \geq \sigma_2(A) \geq \cdots \geq \sigma_{\min[m,n]}(A) \geq 0$. The spectral norm of $A$ is $\|A\| = \max_{x \in \mathbb{R}^n, \|x\| = 1} \|Ax\| = \sigma_1$. Given a set of $d$-dimensional vectors $U = \{u_1, \ldots, u_n\} \in \mathbb{R}^d$, the Gram matrix $V$ (corresponding to the set $U$) is the $n \times n$ psd matrix defined as $V(i,j) = u_i^* u_j$ for $i, j \in [n]$.

A technical tool used in the analysis in state identification problem is Fourier analysis on the Boolean cube. We will just introduce the basics of Fourier analysis here, referring to [O’D14] for more. Define the inner product between functions $f, g : \{0, 1\}^n \rightarrow \mathbb{R}$ as

$$\langle f, g \rangle_x = \mathbb{E}_x[f(x) \cdot g(x)]$$

where the expectation is uniform over $x \in \{0, 1\}^n$. For $S \subseteq [n]$ (equivalently $S \subseteq [0, 1]^n$, let $\chi_S(x) := (-1)^{S \cdot x}$ denote the parity of the variables (of $x$) indexed by the set $S$. It is easy to see that the set of functions $\{\chi_S \mid S \subseteq [n]\}$ forms an orthonormal basis for the space of real-valued functions over the Boolean cube. Hence every $f$ can be decomposed as

$$f(x) = \sum_{S \subseteq [n]} \hat{f}(S)(-1)^{S \cdot x} \quad \text{for all } x \in \{0, 1\}^n,$$

where $\hat{f}(S) = \langle f, \chi_S \rangle = \mathbb{E}_x[f(x) \cdot \chi_S(x)]$ is called a Fourier coefficient of $f$. 
2.2 Learning in general

In machine learning, a concept class \( \mathcal{C} \) over \([0,1]^n\) is a set of concepts \( c : [0,1]^n \rightarrow [0,1] \). We refer to a concept class \( \mathcal{C} \) as being trivial if either \( \mathcal{C} \) contains only one concept, or \( \mathcal{C} \) contains two concepts \( c_0, c_1 \) with \( c_0(x) = 1 - c_1(x) \) for every \( x \in [0,1]^n \). For \( c : [0,1]^n \rightarrow [0,1] \), we will often refer to the tuple \((x, c(x)) \in [0,1]^{n+1}\) as a labeled example. In a labeled example, \( c(x) \) as a label, where \( c \) is referred to as the labeling function that classifies an \( x \) by the label \( c(x) \).

A central combinatorial concept in learning is the Vapnik and Chervonenkis (VC) dimension [VC71]. Fix a concept class \( \mathcal{C} \) over \([0,1]^n\). A set \( S = \{s_1, \ldots, s_t\} \subseteq [0,1]^n \) is said to be shattered by a concept class \( \mathcal{C} \) if \( \{c(s_1) \cdots c(s_t) : c \in \mathcal{C}\} = \{0,1\}^t \) (for every \( y \in \{0,1\}^t \), there exists a \( c \in \mathcal{C} \) such that when we restrict our attention to the set of inputs \( \{s_1, \ldots, s_t\} \), then \( c(s_1) \cdots c(s_t) = y \)). The VC dimension of a concept class \( \mathcal{C} \) is the size of the largest \( S \subseteq [0,1]^n \) that is shattered by \( \mathcal{C} \).

2.3 Classical learning models

In this paper we will be concerned mainly with the PAC (Probably Approximately Correct) model of learning introduced by Valiant [Val84] and agnostic learning introduced by Haussler [Hau92] and Kearns et al. [KSS94]. For further reading, see standard textbooks in computational learning theory such as [KV94b, AB09, SB14].

In the classical PAC model, a learner \( \mathcal{A} \) is given access to a random example oracle \( \text{PEX}(c,D) \) which generates labeled examples of the form \((x, c(x)) \) where \( x \) is drawn from an unknown distribution \( D : [0,1]^n \rightarrow [0,1] \) and \( c \in \mathcal{C} \) is the target concept which \( \mathcal{A} \) is trying to learn. For a concept \( c \in \mathcal{C} \) and hypothesis \( h : [0,1]^n \rightarrow [0,1] \), we define the error of \( h \) compared to the target concept \( c \), under \( D \), as \( \text{err}_D(h,c) = \Pr_{x \sim D}[h(x) \neq c(x)] \). A learning algorithm \( \mathcal{A} \) is an \((\varepsilon, \delta)\)-PAC learner for \( \mathcal{C} \), if the following holds:

For every \( c \in \mathcal{C} \), distribution \( D \), \( \varepsilon, \delta > 0 \), given access to the \( \text{PEX}(c,D) \) oracle:

\[ \mathcal{A} \text{ outputs an } h \in \mathcal{C} \text{ such that } \text{err}_D(h,c) \leq \varepsilon \text{ with probability at least } 1 - \delta. \]

The PAC sample complexity of \( \mathcal{A} \) is the maximum number of invocations of the \( \text{PEX}(c,D) \) oracle which the learner makes, over all concepts \( c \in \mathcal{C} \) and distributions \( D \). The PAC sample complexity of a concept class \( \mathcal{C} \) is the minimum sample complexity over all \((\varepsilon, \delta)\)-PAC learners for \( \mathcal{C} \).

Another well-studied learning model is agnostic learning: for a distribution \( D : [0,1]^{n+1} \rightarrow [0,1] \), a learner \( \mathcal{A} \) is given access to an \( \text{AEX}(D) \) oracle that generates examples of the form \((x, b) \) drawn from the distribution \( D \). For a concept class \( \mathcal{C} \) and \( h : [0,1]^n \rightarrow [0,1] \), we define the error of \( h \) under \( D \) as \( \text{err}_D(h,c) = \Pr_{(x,b) \sim D}[h(x) \neq b] \) and \( \text{opt}_D(\mathcal{C}) = \min_{c \in \mathcal{C}} \{\text{err}_D(c)\} \). For a distribution \( D \), a hypothesis \( c^* \) that minimizes \( \text{opt}_D(\mathcal{C}) \) is called the Bayes classifier and it is not too hard to see that

\[ c^*(x) = \arg\max_{b \in \{0,1\}} \Pr[B = b \mid X = x], \quad \text{for all } x \in [0,1]^n. \]

In agnostic learning, a learner \( \mathcal{A} \) needs to output a hypothesis \( h \) whose error is not much bigger than the error of \( c^* \). A learning algorithm \( \mathcal{A} \) is an \((\varepsilon, \delta)\)-agnostic learner for \( \mathcal{C} \), if the following holds:

For every distribution \( D \), \( \varepsilon, \delta > 0 \), given access to the \( \text{AEX}(D) \) oracle:

\[ \mathcal{A} \text{ outputs an } h \in \mathcal{C} \text{ such that } \text{err}_D(h) \leq \text{opt}_D(\mathcal{C}) + \varepsilon \text{ with probability at least } 1 - \delta. \]

Note that if there is a \( c \in \mathcal{C} \) which perfectly classifies every \( x \) with label \( y \) for \((x,y) \in \text{supp}(D)\), then \( \text{opt}_D(\mathcal{C}) = 0 \) and we are back in the setting of PAC learning. The agnostic sample complexity of \( \mathcal{A} \) is the maximum number of invocations of the \( \text{AEX}(c,D) \) oracle which the learner, over all distributions \( D \). The agnostic sample complexity of a concept class \( \mathcal{C} \) is the minimum sample complexity over all \((\varepsilon, \delta)\)-agnostic learners for \( \mathcal{C} \).
2.4 Quantum information theory

Throughout this paper we will assume the reader is familiar with the following quantum terminology. An $n$-dimensional pure state is $|\psi\rangle = \sum_{i=1}^{n} \alpha_i |i\rangle$, where $|i\rangle$ is the $n$-dimensional unit vector that has a 1 at position $i$, the $\alpha_i$'s are complex numbers called the amplitudes, and $\sum_{i=1}^{n} |\alpha_i|^2 = 1$. An $n$-dimensional mixed state (or density matrix) $\rho = \sum_{i=1}^{n} p_i |\psi_i\rangle \langle \psi_i|$ is a mixture of pure states $|\psi_1\rangle,...,|\psi_n\rangle$ prepared with probabilities $p_1,...,p_n$, respectively. The eigenvalues $\lambda_1,...,\lambda_n$ of $\rho$ are non-negative reals and satisfy $\sum_{i=1}^{n} \lambda_i = 1$. If $\rho$ is pure (i.e., $\rho = |\psi\rangle \langle \psi|$ for some $|\psi\rangle$), then one of the eigenvalues is 1 and the others are 0.

To obtain any classical information from $\rho$, one could apply a POVM (positive-operator-valued measure) to the state $\rho$. An $m$-outcome POVM is specified by a set of positive semidefinite matrices $\{M_i\}_{i \in [m]}$ with the property $\sum_i M_i = \text{Id}$. When this POVM is applied to the mixed state $\rho$, the probability of the $j$-th outcome is given by $\text{Tr}(M_j \rho)$.

For a probability vector $(p_1,...,p_k)$ (where $\sum_{i=1}^{k} p_i = 1$), the entropy function is defined as $H(p_1,...,p_k) = -\sum_{i=1}^{k} p_i \log p_i$. When $k = 2$, with $p_1 = p$ and $p_2 = 1 - p$, we denote the binary entropy function as $H(p)$. For a state $\rho_{AB}$ on the Hilbert space $\mathcal{H}_A \otimes \mathcal{H}_B$, we let $\rho_A$ be the reduced state after taking the partial trace over $\mathcal{H}_B$. The entropy of a quantum state $\rho_A$ is defined as $S(\rho_A) = -\text{Tr}(\rho_A \log \rho_A)$. The mutual information is defined as $I(A:B) = S(\rho_A) + S(\rho_B) - S(\rho_{AB})$, and the conditional entropy is defined as $S(\rho_A|B) = S(\rho_{AB}) - S(B)$. Classical information-theoretic quantities correspond to the special case where $\rho$ is a diagonal matrix whose diagonal corresponds to the probability distribution of the random variable. Writing $\rho_A$ in its eigenbasis, it follows that $S(\rho_A) = H(\lambda_1,...,\lambda_{\text{dim} \rho_A})$, where $\lambda_1,...,\lambda_{\text{dim} \rho_A}$ are the eigenvalues of $\rho$. If $\rho_A$ is a pure state, $S(\rho_A) = 0$.

2.5 Quantum learning models

The quantum PAC learning model was introduced by Bshouty and Jackson in [BJ99]. The quantum PAC model is a generalization of the classical PAC model, instead of having access to examples $(x,c(x))$ from the $\text{PEX}(c,D)$ oracle, the learner obtains a superposition of all examples. For an unknown distribution $D : [0,1]^n \rightarrow [0,1]$ and concept $c \in \mathcal{C}$, a quantum example oracle $\text{QPEX}(c,D)$ acts on $|0^n,0\rangle$ and produces a quantum example $\sum_{x \in [0,1]^n} \sqrt{D(x)} |x,c(x)\rangle$ (we leave it undefined on other basis states). A quantum learner is given access to some copies of the state generated by $\text{QPEX}(c,D)$ and performs a $|\mathcal{C}|$-outcome POVM (where each outcome is associated with a hypothesis). A learning algorithm $A$ is an $(\epsilon,\delta)$-quantum PAC learner for $\mathcal{C}$, if the following holds:

For every $c \in \mathcal{C}$, distribution $D$, $\epsilon,\delta > 0$, given access to the $\text{QPEX}(c,D)$ oracle:

$A$ outputs an $h \in \mathcal{C}$ such that $\text{err}_D(h,c) \leq \epsilon$, with probability at least $1 - \delta$.

The quantum PAC sample complexity of $A$ is the maximum number of invocations of the $\text{QPEX}(c,D)$ oracle when maximized over all $c \in \mathcal{C}$ and distribution $D$. The quantum PAC sample complexity of a concept class $\mathcal{C}$ is the minimum sample complexity over all $(\epsilon,\delta)$-quantum PAC learners for $\mathcal{C}$.

We define quantum agnostic learning now. For a joint distribution $D : [0,1]^{n+1} \rightarrow [0,1]$ over the set of examples, the learner has access to an $\text{QAEX}(D)$ oracle which acts on $|0^n,0\rangle$ and produces a quantum example $\sum_{(x,b) \in [0,1]^n \times [0,1]} \sqrt{D(x,b)} |x,b\rangle$. A learning algorithm $A$ is an $(\epsilon,\delta)$-quantum agnostic learner for $\mathcal{C}$, if the following holds:

For every distribution $D$, $\epsilon,\delta > 0$, given access to the $\text{QAEX}(D)$ oracle:

$A$ outputs an $h \in \mathcal{C}$ such that $\text{err}_D(h) \leq \text{opt}_D(\mathcal{C}) + \epsilon$ with probability at least $1 - \delta$. 

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The quantum agnostic sample complexity of \( A \) is the maximum number of invocations of the QAEX\((D)\) oracle over all distributions \( D \). The quantum agnostic sample complexity of a concept class \( \mathcal{C} \) is the minimum sample complexity over all \((\epsilon,\delta)\)-quantum agnostic learners for \( \mathcal{C} \).

### 2.6 Pretty Good Measurement

Consider an ensemble of \( d \)-dimensional states, \( \mathcal{E} = \{(p_i,|\psi_i\rangle)\}_{i\in [m]} \), where \( \sum_{i\in [m]} p_i = 1 \). Suppose we are given an unknown state \(|\psi\rangle\) sampled according to the probabilities and we are interested in maximizing the average probability of success to identify the state that we are given. For a POVM specified by positive semidefinite matrices \( M = [M_i]_{i\in [m]} \), the probability of obtaining outcome \( j \), given the state \(|\psi_i\rangle\), equals \( \langle \psi|M_i|\psi_i\rangle \). The average success probability is defined as

\[
P_M(\mathcal{E}) = \sum_{i=1}^{m} p_i \langle \psi_i|M_i|\psi_i\rangle.
\]

Let \( P_{\text{opt}}(\mathcal{E}) = \max_M P_M(\mathcal{E}) \) denote the optimal average success probability of \( \mathcal{E} \), where the maximization is over the set of valid \( m \)-outcome POVMs.

For every ensemble \( \mathcal{E} \), the so-called Pretty Good Measurement (PGM) is a specific POVM (depending on the ensemble \( \mathcal{E} \)), which we shall define shortly, that does reasonably well against \( \mathcal{E} \). Suppose \( P_{\text{PGM}}(\mathcal{E}) \) is defined as the average success probability of identifying the states in \( \mathcal{E} \) using the PGM, then we have that

\[
P_{\text{opt}}(\mathcal{E})^2 \leq P_{\text{PGM}}(\mathcal{E}) \leq P_{\text{opt}}(\mathcal{E}),
\]

where the second inequality follows because \( P_{\text{opt}}(\mathcal{E}) \) is a maximization over all valid POVMs and the first inequality was shown by Barnum and Knill [BK02].

For completeness we give a simple proof of \( P_{\text{opt}}(\mathcal{E})^2 \leq P_{\text{PGM}}(\mathcal{E}) \) below (similar to [Mon07]). Let \(|\psi'_i\rangle = \sqrt{p_i}|\psi_i\rangle\), and \( \mathcal{E}' = \{|\psi'_i\rangle : i \in [m]\} \) be the set of states in \( \mathcal{E} \), renormalized to reflect their probabilities. Define \( \rho = \sum_{i\in [m]} |\psi'_i\rangle\langle\psi'_i| \). The PGM is defined as the set of measurement operators \(|\nu_i\rangle\langle\nu_i|\) where \(|\nu_i\rangle = \rho^{-1/2}|\psi'_i\rangle \) (the inverse square root of \( \rho \) is taken over its non-zero eigenvalues). We first verify this is a valid POVM:

\[
\sum_{i=1}^{m} |\nu_i\rangle\langle\nu_i| = \rho^{-1/2} \left( \sum_{i=1}^{m} |\psi'_i\rangle\langle\psi'_i| \right) \rho^{-1/2} = \text{Id}.
\]

Next, we note that \( P_{\text{PGM}}(\mathcal{E}) = \sum_{i\in [m]} (\nu_i|\psi_i\rangle)^2 = \sum_{i\in [m]} (\psi'_i|\rho^{-1/2}\psi'_i\rangle)^2 \). Let \( G \) be the Gram matrix for the set \( \mathcal{E}' \), i.e., \( G(i,j) = \langle \psi'_i|\psi'_j\rangle \) for \( i, j \in [m] \). It can be verified that \( \sqrt{G}(i,j) = \langle \psi'_i|\rho^{-1/2}\psi'_j\rangle \), hence

\[
P_{\text{PGM}}(\mathcal{E}) = \sum_{i\in [m]} \sqrt{G}(i,i)^2.
\]

We now prove \( P_{\text{opt}}(\mathcal{E})^2 \leq P_{\text{PGM}}(\mathcal{E}) \). Suppose \( \mathcal{M} \) is the optimal measurement. Since \( \mathcal{E} \) consists of pure states, by a result of Eldar et al. [EMV03], we can assume without loss of generality that the measurement operators in \( \mathcal{M} \) are rank-1, so \( M_i = |\mu_i\rangle\langle\mu_i| \) for some \( |\mu_i\rangle \). Note that

\[
1 = \text{Tr}(\rho) = \text{Tr} \left( \sum_{i\in [m]} |\mu_i\rangle\langle\mu_i|\rho^{1/2} \sum_{j\in [m]} |\mu_j\rangle\langle\mu_j|\rho^{1/2} \right) = \sum_{i,j\in [m]} |\langle \mu_i|\rho^{1/2}\mu_j\rangle|^2 \geq \sum_{i\in [m]} |\langle \mu_i|\rho^{1/2}\mu_i\rangle|^2.
\]
Then,
\[
\begin{align*}
P_{\text{opt}}(\mathcal{E}) &= \sum_{i \in [m]} |\langle \mu_i | \psi_i' \rangle|^2 = \sum_{i \in [m]} |\langle \mu_i | \rho^{1/2} \rho^{-1/2} | \psi_i' \rangle|^2 \\
&\leq \sqrt{\sum_{i \in [m]} |\langle \mu_i | \rho^{1/2} \rangle|^2 \sum_{i \in [m]} |\langle \psi_i' | \rho^{-1/2} \rangle|^2} \\
&\leq \sqrt{\sum_{i \in [m]} |\langle \mu_i | \rho^{1/2} \rangle|^2 \sum_{i \in [m]} |\langle \psi_i' | \rho^{-1/2} \rangle|^2} \\
&\leq \sqrt{\sum_{i \in [m]} |\langle \psi_i' | \rho^{-1/2} \rangle|^2} = \sqrt{p_{\text{PGM}}(\mathcal{E})},
\end{align*}
\]

where the first and second inequalities use Cauchy-Schwarz.

The above shows that for all ensembles \( \mathcal{E} \), the PGM for that ensemble is not much worse than the optimal measurement. In some cases the PGM is the optimal measurement. In particular, an ensemble \( \mathcal{E} \) is called geometrically uniform if \( \mathcal{E} = \{ U_i | \rho \} : i \in [m] \) for some Abelian group of matrices \( \{ U_i \}_{i \in [m]} \). Eldar and Forney [EF01] showed that \( P_{\text{opt}}(\mathcal{E}) = p_{\text{PGM}}(\mathcal{E}) \) for such ensembles.

2.7 Known results and required claims

The following theorems characterize the sample complexity of classical PAC and agnostic learning.

Theorem 1 ([BEHW89, Han15]). Let \( \mathcal{C} \) be a concept class with \( \text{VC-dim}(\mathcal{C}) = d + 1 \). In the PAC model, \( \Theta \left( \frac{d}{\epsilon^2} + \frac{\log(1/\delta)}{\epsilon} \right) \) examples are necessary and sufficient for a classical \((\epsilon, \delta)\)-PAC learner for \( \mathcal{C} \).

Theorem 2 ([VC74, Sim96, Tal94]). Let \( \mathcal{C} \) be a concept class with \( \text{VC-dim}(\mathcal{C}) = d \). In the agnostic model, \( \Theta \left( \frac{d}{\epsilon^2} + \frac{\log(1/\delta)}{\epsilon} \right) \) examples are necessary and sufficient for a classical \((\epsilon, \delta)\)-agnostic learner for \( \mathcal{C} \).

We will use the following well-known theorem from the theory of error-correcting codes:

Theorem 3. For every sufficiently large integer \( n \), there exists an integer \( k \in [n/4, n] \) and a matrix \( M \in \mathbb{F}_2^{n \times k} \) of rank \( k \), such that the associated \( [n,k,d]_2 \) linear code \( \{ Mx : x \in \{0,1\}^n \} \) has minimal distance \( d \geq n/8 \).

We will need the following claims later

Claim 4. Let \( f : \{0,1\}^m \to \mathbb{R} \) and let \( M \in \mathbb{F}_2^{m \times k} \). Then the Fourier coefficients of \( f \circ M \) are \( \hat{f} \circ M(Q) = \sum_{S \subseteq \{0,1\}^m : M'S = Q} \hat{f}(S) \) for all \( Q \subseteq [k] \) (where \( M^t \) is the transpose of the matrix \( M \)).

Proof. Writing out the Fourier coefficients of \( f \circ M \)
\[
\hat{f} \circ M(Q) = \mathbb{E}_{z \in \{0,1\}^k} [(f \circ M)(z)(-1)^{Q \cdot z}]
\]
\[
= \mathbb{E}_{z \in \{0,1\}^k} \left[ \sum_{S \subseteq \{0,1\}^m} \hat{f}(S)(-1)^{S \cdot (Mz) + Q \cdot z} \right] \quad \text{(Fourier expansion of } f) \\
= \sum_{S \subseteq \{0,1\}^m} \hat{f}(S) \mathbb{E}_{z \in \{0,1\}^k} [(-1)^{(M^tS + Q) \cdot z}] \quad \text{(using } \langle S, Mz \rangle = \langle M^tS, z \rangle \text{)} \\
= \sum_{S : M^tS = Q} \hat{f}(S). \quad \text{(using } \mathbb{E}_{z \in \{0,1\}^k} (-1)^{(z_1 + z_2) \cdot z} = \delta_{z_1,z_2} \text{)}
\]
\[ \square \]
Claim 5. $\max[(c/\sqrt{t})^t : t \in [1,c^2]] = e^{c^2/(2\epsilon)}$.

Proof. The value of $t$ at which the function $(c/\sqrt{t})^t$ is the largest, is obtained by differentiating the function with respect to $t$,

$$\frac{d}{dt}(c/\sqrt{t})^t = (c/\sqrt{t})^t \left( \ln(c/\sqrt{t}) - 1/2 \right).$$

Equating the derivative to zero we obtain the maxima (the second derivative can be checked to be negative) at $t = c^2/\epsilon$. \hfill \Box

Fact 6. For all $\epsilon \in [0,1/2]$ we have $H(\epsilon) \leq O(\epsilon \log(1/\epsilon))$, and (from the Taylor series)

$$1 - H(1/2 + \epsilon) \leq 2\epsilon^2/\ln 2 + O(\epsilon^4).$$

Fact 7. For every positive integer $n$, we have that $\binom{n}{k} \leq 2^{nH(k/n)}$ for all $k \leq n$ and $\sum_{i=0}^{m} \binom{n}{i} \leq 2^{nH(m/n)}$ for all $m \leq n/2$.

The following facts are well-known in quantum information theory.

Fact 8. Let binary random variable $b \in \{0,1\}$ be uniformly distributed. Suppose an algorithm is given $|\psi_b\rangle$ (for unknown $b$) and is required to guess whether $b = 0$ or $b = 1$. It will guess correctly with probability at most $\frac{1}{2} + \frac{1}{2}\sqrt{1 - |\langle\psi_0|\psi_1\rangle|^2}$.

Note that if we can distinguish $|\psi_0\rangle$ and $|\psi_1\rangle$ with probability $\geq 1-\delta$, then $|\langle\psi_0|\psi_1\rangle| \geq 2\sqrt{\delta(1-\delta)}$.

Fact 9. (Subadditivity of quantum entropy): For an arbitrary bipartite state $\rho_{AB}$ on the Hilbert space $\mathcal{H}_A \otimes \mathcal{H}_B$, it holds that $S(\rho_{AB}) \leq S(\rho_A) + S(\rho_B)$.

3 Information-theoretic lower bounds

Upper bounds on sample complexity carry over from classical to quantum PAC learning, because a quantum sample can simulate a classical sample if we just measure it. Our main goal is to show that the lower bounds also carry over. All our lower bounds will involve two terms, one that is independent of $\mathcal{C}$ and one that is dependent on the VC dimension of $\mathcal{C}$. In Section 3.1 we prove the VC-independent part of the lower bounds for the quantum setting (which also is a lower bound for the classical setting), in Section 3.2 we present an information-theoretic lower bound on sample complexity for PAC learning and agnostic learning which yields optimal VC-dependent bounds in the classical case. Using similar ideas, in Section 3.3 we obtain near-optimal bounds in the quantum case.

3.1 VC-independent part of lower bounds

Lemma 10 ([AS05]). For every $\delta \in (0,1/2)$, $\epsilon \in (0,1/4)$, a quantum algorithm which $(\epsilon,\delta)$-learns a non-trivial concept class $\mathcal{C}$ has quantum PAC sample complexity $\Omega(\frac{1}{\epsilon}\log \frac{1}{\delta})$.

Proof. Since $\mathcal{C}$ is non-trivial, we may assume there are two concepts $c_1,c_2 \in \mathcal{C}$ defined on two inputs $\{x_1,x_2\}$ as follows $c_1(x_1) = c_2(x_1) = 0$ and $c_1(x_2) = c_2(x_2) = 1$. Consider the distribution $D(x_1) = 1-\epsilon$ and $D(x_2) = \epsilon$. For $i \in [1,2]$, the state of the algorithm after $T$ queries to $QPEX(c_i,D)$ is $|\psi_i\rangle = (\sqrt{1-\epsilon}|x_1,0\rangle + \sqrt{\epsilon}|x_2,c_i(x_2)\rangle)^{\otimes T}$. It follows that $\langle\psi_1|\psi_2\rangle = (1-\epsilon)^T$. Since the success probability of an $(\epsilon,\delta)$-quantum PAC learner is $\geq 1-\delta$, Fact 8 implies $\langle\psi_1|\psi_2\rangle \leq 2\sqrt{\delta(1-\delta)}$. Hence $T = \Omega(\frac{1}{\epsilon}\log \frac{1}{\delta})$. \hfill \Box
Lemma 11. For every $\delta \in (0, 1/2)$, $\varepsilon \in (0, 1/4)$, a quantum algorithm which $(\varepsilon, \delta)$-learns a non-trivial concept class $\mathcal{C}$ has quantum agnostic sample complexity $\Omega(\frac{1}{\varepsilon^2} \log \frac{1}{\delta})$.

Proof. Since $\mathcal{C}$ is non-trivial, we may assume there are two concepts $c_1, c_2 \in \mathcal{C}$ and there exists an input $x \in \{0, 1\}^n$ such that $c_1(x) \neq c_2(x)$. Consider the two distributions $D_x$ and $D_x$ defined as follows: $D_x(x, c_1(x)) = (1 \pm \varepsilon)/2$ and $D_x(x, c_2(x)) = (1 \mp \varepsilon)/2$. Let $|\psi_+\rangle$ be the state after $T$ queries to QAEX($D_x$), i.e., $|\psi_+\rangle = (\sqrt{(1 + \varepsilon)/2} |x, c_1(x)\rangle + \sqrt{(1 - \varepsilon)/2} |x, c_2(x)\rangle)^\otimes T$. It follows that $\langle \psi_+ | \psi_- \rangle = (1 - \varepsilon^2)^{T/2}$. Since the success probability of an $(\varepsilon, \delta)$-quantum agnostic learner is $\geq 1 - \delta$, Fact 8 implies $\langle \psi_+ | \psi_- \rangle \leq 2\sqrt{\delta(1 - \delta)}$. Hence $T = \Omega(\frac{1}{\varepsilon^2} \log \frac{1}{\delta})$.

3.2 Information-theoretic lower bounds on sample complexity: classical case

3.2.1 Optimal lower bound for classical PAC learning

Theorem 12. Let $\mathcal{C}$ be a concept class with $VC$-dim($\mathcal{C}$) = $d + 1$. Then for every $\delta \in (0, 1/2)$ and $\varepsilon \in (0, 1/4)$, an algorithm which $(\varepsilon, \delta)$-learns $\mathcal{C}$ has PAC sample complexity $\Omega(d + \frac{\log(1/\delta)}{\varepsilon})$.

Proof. Consider an $(\varepsilon, \delta)$-PAC learner for $\mathcal{C}$ that uses $T$ examples. The $d$-independent part of the lower bound, $T = \Omega(\log(1/\delta)/\varepsilon)$, even holds for quantum examples and was proven in Lemma 10. Hence it remains to prove $T = \Omega(d/\varepsilon)$. It suffices to show this for a specific distribution $D$, defined as follows. Let $\mathcal{S} = \{s_0, s_1, \ldots, s_d\} \subseteq \{0, 1\}^d$ be some $(d + 1)$-element set shattered by $\mathcal{C}$. Define $D(s_0) = 1 - 4\varepsilon$ and $D(s_i) = 4\varepsilon/d$ for all $i \in [d]$.

Because $\mathcal{S}$ is shattered by $\mathcal{C}$, for each string $a \in \{0, 1\}^d$, there exists a concept $c_a \in \mathcal{C}$ such that $c_a(s_0) = 0$ and $c_a(s_i) = a_i$ for all $i \in [d]$. We define two correlated random variables $A$ and $B$ corresponding to the concept and to the examples, respectively. Let $A$ be a random variable that is uniformly distributed over $\{0, 1\}^d$; if $A = a$, let $B = B_1 \ldots B_T$ be $T$ i.i.d. examples from $c_a$ according to $D$. We give the following three-step analysis of these random variables:

1. $I(A : B) \geq (1 - \delta)(1 - H(1/4)d - H(\delta)) = \Omega(d)$.

   Proof. Let random variable $h(B) \in \{0, 1\}^d$ be the hypothesis that the learner produces (given the examples in $B$) restricted to the elements $s_1, \ldots, s_d$. Note that the error of the hypothesis $err_D(h(B), c_A)$ equals $d_H(h(B), h(B)) \cdot 4\varepsilon/d$, because each $s_i$ where $A$ and $h(B)$ differ contributes $D(s_i) = 4\varepsilon/d$ to the error. Let $Z$ be the indicator random variable for the event that the error is $\leq \varepsilon$. If $Z = 1$, then $d_H(h(B), h(B)) \leq d/4$. Since we are analyzing an $(\varepsilon, \delta)$-PAC learner, we have $\Pr[Z = 1] \geq 1 - \delta$, and $H(Z) \leq H(\delta)$. Given a string $h(B)$ that is $d/4$-close to $A$, $A$ ranges over a set of only $\sum_{i=0}^{\lfloor d/4 \rfloor} \binom{d}{i} \leq 2H(1/4)^d$ possible $d$-bit strings (using Fact 7), hence $H(A | B, Z = 1) \leq H(A | h(B), Z = 1) \leq H(1/4)d$. We now lower bound $I(A : B)$ as follows:

   \[
   I(A : B) = H(A) - H(A | B) \\
   \geq H(A) - H(A | B, Z) - H(Z) \\
   = H(A) - \Pr[Z = 1] \cdot H(A | B, Z = 1) - \Pr[Z = 0] \cdot H(A | B, Z = 0) - H(Z) \\
   \geq d - (1 - \delta)H(1/4)d - \delta d - H(\delta) \\
   = (1 - \delta)(1 - H(1/4))d - H(\delta).
   \]

2. $I(A : B) \leq T \cdot I(A : B_1)$.

   Proof. This inequality is essentially due to Jain and Zhang [JZ09, Lemma 5], we include the proof for completeness.

   \[
   I(A : B) = H(B) - H(B | A) = H(B) - \sum_{i=1}^{T} H(B_i | A) \leq \sum_{i=1}^{T} H(B_i) - \sum_{i=1}^{T} H(B_i | A) = \sum_{i=1}^{T} I(A : B_i),
   \]
where the second equality used independence of the $B_i$’s conditioned on $A$, and the inequality uses Fact 9. Since $I(A : B_i) = I(A : B_1)$ for all $i$, we get the inequality.

3. $I(A : B_1) = 4\epsilon$.

   **Proof.** View $B_1 = (I, L)$ as consisting of an index $I \in \{0,1,\ldots,d\}$ and a corresponding label $L \in \{0,1\}$. With probability $1 - 4\epsilon$, $(I, L) = (0,0)$. For each $i \in [d]$, with probability $4\epsilon/d$, $(I, L) = (i, A_i)$. Note that $I(A : I) = 0$ because $I$ is independent of $A$; $I(A : L | I = 0) = 0$; and $I(A : L | I = i) = I(A_i : L | I = i) = H(A_i | I = i) - H(A_i | L, I = i) = 1 - 0 = 1$ for all $i \in [d]$. We have

   \[ I(A : B_1) = I(A : I) + I(A : L | I) = \sum_{i=1}^d \Pr[I = i] \cdot I(A : L | I = i) = 4\epsilon. \]

Combining these three steps implies $T = \Omega(d/\epsilon^2)$.

3.2.2 Optimal lower bound for classical agnostic learning

**Theorem 13.** Let $C$ be a concept class with $\text{VC-dim}(C) = d$. Then for every $\delta \in (0,1/2)$ and $\epsilon \in (0,1/4)$, an algorithm which $(\epsilon, \delta)$-learns $C$ has agnostic sample complexity $\Omega \left( \frac{d}{\epsilon^2} + \frac{\log(1/\delta)}{\epsilon^2} \right)$.

**Proof.** The $d$-independent part of the lower bound, $T = \Omega(\log(1/\delta)/\epsilon^2)$, even holds for quantum examples and was proven in Lemma 11. For the other part, the proof is similar to Theorem 12, as follows. Assume an $(\epsilon, \delta)$-agnostic learner for $C$ that uses $T$ examples. We need to prove $T = \Omega(d/\epsilon^2)$. For shattered set $S = \{s_1,\ldots,s_d\} \subseteq \{0,1\}^n$ and $a \in \{0,1\}^d$, define distribution $D_a$ on $[d] \times \{0,1\}$ by $D_a(i,\ell) = (1 + (-1)^{a_\ell} \cdot 4\epsilon)/2d$.

Again let random variable $A \in \{0,1\}^d$ be uniformly random, corresponding to the values of concept $c_a$ on $S$, and $B = B_1 \ldots B_T$ be $T$ i.i.d. samples from $D_a$. Note that $c_a$ is the minimal-error concept from $C$ w.r.t. $D_a$ (i.e., $c_a$ is the Bayes classifier), and concept $c_a$ has additional error $d_H(a,a') \cdot 4\epsilon/d$. Accordingly, an $(\epsilon, \delta)$-agnostic learner has to produce (from $B$) an $h(B) \in \{0,1\}^d$, which, with probability at least $1 - \delta$, is $d/4$-close to $A$. Our three-step analysis is very similar to Theorem 12; only the third step changes:

1. $I(A : B) \geq (1 - \delta)(1 - H(1/4))d - H(\delta) = \Omega(d)$.
2. $I(A : B) \leq T \cdot I(A : B_1)$.
3. $I(A : B_1) = 1 - H(1/2 + 2\epsilon) = O(\epsilon^2)$.

   **Proof.** View the $D_a$-distributed random variable $B_1 = (I, L)$ as index $I \in [d]$ and label $L \in \{0,1\}$. The marginal distribution of $I$ is uniform; conditioned on $I = i$, the bit $L$ equals $A_i$ with probability $1/2 + 2\epsilon$. Hence

   \[ I(A : L | I = i) = I(A_i : L | I = i) = H(A_i | I = i) - H(A_i | L, I = i) = 1 - H(1/2 + 2\epsilon). \]

Using Fact 6, we have

\[ I(A : B_1) = I(A : I) + I(A : L | I) = \sum_{i=1}^d \Pr[I = i] \cdot I(A : L | I = i) = 1 - H(1/2 + 2\epsilon) = O(\epsilon^2). \]

Combining these three steps implies $T = \Omega(d/\epsilon^2)$.
In the theorem below, we optimize the constant in the lower bound of the sample complexity in Theorem 13. In learning theory such lower bounds are often stated slightly differently. In order to compare the lower bounds, we introduce the following. We first define an \( \epsilon \)-average agnostic learner for a concept class \( \mathcal{C} \) as a learner, who given access to \( T \) samples from an AEX\((D)\) oracle (for some unknown distribution \( D \)), needs to output a hypothesis \( h_{XY} \) (where \( (X,Y) \sim D^T \)) that satisfies

\[
\left( \mathbb{E}_{(X,Y) \sim D^T}[err_D(h_{XY})] - opt_D(\mathcal{C}) \right) \leq \epsilon.
\]

Lower bounds on the quantity \( (\mathbb{E}_{(X,Y) \sim D^T}[err_D(h_{XY})] - opt_D(\mathcal{C})) \) are generally referred to as minimax lower bounds in learning theory. For concept class \( \mathcal{C} \), Audibert [Aud08, Aud09] showed that there exists a distribution \( D \), such that if the agnostic learner uses \( T \) samples from AEX\((D)\), then

\[
\left( \mathbb{E}_{(X,Y) \sim D^T}[err_D(h_{XY})] - opt_D(\mathcal{C}) \right) \geq \frac{1}{6} \sqrt{\frac{d}{T}}.
\]

Equivalently, this is a lower bound of \( T \geq \frac{d^2}{36\epsilon^2} \) on the sample complexity of an \( \epsilon \)-average agnostic learner. We obtain a slightly weaker lower bound that is essentially \( T \geq \frac{d^2}{62\epsilon^2} \):

**Theorem 14.** Let \( \mathcal{C} \) be a concept class with VC-dim\((\mathcal{C}) = d \). Then for every \( \epsilon \in (0, 1/10] \), there exists a distribution for which every \( \epsilon \)-average agnostic learner has sample complexity at least \( \frac{d^2}{\epsilon^2} \cdot \left(\frac{1}{62} - \log\left(\frac{2d+2}{4d}\right)\right)\).

**Proof.** The proof is similar to Theorem 13. Assume an \( \epsilon \)-average agnostic learner for \( \mathcal{C} \) that uses \( T \) samples. For shattered set \( S = \{s_1, \ldots, s_d\} \subseteq \{0,1\}^n \) and \( a \in \{0,1\}^d \), define distribution \( D_a \) on \([d] \times \{0,1\}\), for some constant \( \beta \) which we shall pick later.

Again let random variable \( A \in \{0,1\}^d \) be uniformly random, corresponding to the values of concept \( c_a \) on \( S \), and \( B = B_1 \ldots B_T \) be \( T \) i.i.d. samples from \( D_a \). Note that \( c_a \) is the minimal-error concept from \( \mathcal{C} \) w.r.t. \( D_a \), and concept \( c_b \) has additional error \( d_H(a,b) \cdot \beta \epsilon /d \). Accordingly, an \( \epsilon \)-average agnostic learner has to produce \( \epsilon \)-close to \( A \), \( \epsilon \) ranges over a set of only \( \binom{d}{\ell} \leq 2^{H(\ell)/d} \) possible \( d \)-bit strings (using Fact 7), hence \( H(A \mid B,Z = \ell) \leq H(A \mid h(B),Z = \ell) \leq H(\ell/d)d \). We now lower bound \( I(A : B) \)

\[
I(A : B) \geq H(A) - H(A \mid B)
\]

\[
= H(A) - H(A \mid B,Z) - H(Z)
\]

\[
\geq d - \sum_{\ell=0}^{d+1} \Pr[Z = \ell] \cdot H(A \mid B,Z = \ell) - H(Z)
\]

\[
\geq d - \sum_{\ell \in [0, \ldots, d]} \frac{\mathbb{E}[H(\ell/d)]}{d} - \log (d+1) \quad \text{(since } Z \in \{0, \ldots, d\})
\]

\[
\geq d - dH\left(\frac{\mathbb{E}[\ell]}{d}\right) - \log (d+1) \quad \text{(using Jensen’s inequality)}
\]

\[
\geq d - dH(\epsilon) - \log (d+1) \quad \text{(using } \mathbb{E}[Z] \leq d/\beta \}
\]

where in the third inequality we used the concavity of the binary entropy function to conclude \( \mathbb{E}_{\ell}[H(\ell/d)] \leq H(\mathbb{E}[\ell]/d) \).
2. $I(A : B) \leq T \cdot I(A : B_1)$.

3. $I(A : B_1) = 1 - H(1/2 + \beta \epsilon/2)$ \(\text{Fact 6}\) \(\leq \beta^2 \epsilon^2 / \ln 4 + O(\epsilon^4)$.

Combining these three steps implies

$$T \geq \frac{d \ln 4}{\epsilon^2} \cdot \frac{1 - H(1/\beta)}{\beta^2 + O(\epsilon^2)} - \frac{\log(d+1)}{\beta^2 d + O(d \epsilon^2)}.$$  

Using $\epsilon \leq 1/10$ and $\beta = 4$, we obtain a lower bound of $T \geq \frac{d}{\epsilon^2} \cdot \left( \frac{1}{62} - \frac{\log(2d+2)}{4d} \right)$. \(\square\)

### 3.3 Information-theoretic lower bounds on sample complexity: quantum case

Here we will “quantize” the above two classical information-theoretic proofs, yielding lower bounds for quantum sample complexity (in both the PAC and the agnostic setting) that are tight up to a logarithmic factor.

#### 3.3.1 Near-optimal lower bound for quantum PAC learning

**Theorem 15.** Let $\mathcal{C}$ be a concept class with $\text{VC-dim}(\mathcal{C}) = d + 1$. Then for every $\delta \in (0, 1/2)$ and $\epsilon \in (0, 1/4)$, a quantum algorithm which $(\epsilon, \delta)$-learns $\mathcal{C}$ has quantum PAC sample complexity $\Omega\left( \frac{d}{\epsilon} \log(d/\epsilon) + \frac{\log(1/\delta)}{\epsilon} \right)$.

**Proof.** The proof is analogous to Theorem 12. We use the same distribution $D$, with the $B_i$ now being quantum samples: $|\psi_a\rangle = \sum_{i \in [0, 1, \ldots, d]} \sqrt{D(s_i)} |i, c_a(s_i)\rangle$. The first two steps of our argument are identical to Theorem 12. We only need to re-analyze step 3:

1. $I(A : B) \geq (1 - \delta)(1 - H(1/4))d - H(\delta) = \Omega(d)$.

2. $I(A : B) \leq T \cdot I(A : B_1)$.

3. $I(A : B_1) \leq H(4\epsilon) + 4\epsilon \log(2d) = O(\epsilon \log(d/\epsilon))$.

**Proof.** Since $AB$ is a classical-quantum state, we have

$$I(A : B_1) = S(A) + S(B_1) - S(AB_1) = S(B_1),$$

where the first equality is by definition and the second equality uses $S(A) = d$ since $A$ is uniformly distributed in $[0, 1]^d$, and $S(AB_1) = d$ since the matrix $\sigma = \frac{1}{2^d} \sum_{a \in [0, 1]^d} |a\rangle\langle a| \otimes |\psi_a\rangle\langle \psi_a| = $ is block diagonal with $2^d$ rank-1 blocks on the diagonal. It thus suffices to bound the entropy of the singular values of the reduced state of $B_1$, which is

$$\rho = \frac{1}{2^d} \sum_{a \in [0, 1]^d} |\psi_a\rangle\langle \psi_a|.$$

Let $\sigma_0 \geq \sigma_1 \geq \cdots \geq \sigma_{2d} \geq 0$ be its singular values. These form a probability distribution since $\rho$ is density operator. Note that the upper-left entry of the matrix $|\psi_a\rangle\langle \psi_a|$ is $D(s_0) = 1 - 4\epsilon$, hence so is the upper-left entry of $\rho$. This implies $\sigma_0 \geq 1 - 4\epsilon$. Consider sampling a number $N \in [0, 1, \ldots, 2d]$ according to the $\sigma$-distribution. Let $Z$ be the indicator random variable for the event $N \neq 0$, which has probability $1 - \sigma_0 \leq 4\epsilon$. Note that $H(N \mid Z = 0) = 0$, because $Z = 0$
implies $N = 0$. Also, $H(N | Z = 1) \leq \log(2d)$, because if $Z = 1$ then $N$ ranges over $2d$ elements.

We now have

$$S(\rho) = H(N) = H(N, Z) = H(Z) + H(N | Z)$$

$$= H(Z) + \Pr[Z = 0] \cdot H(N | Z = 0) + \Pr[Z = 1] \cdot H(N | Z = 1)$$

$$\leq H(4\varepsilon) + 4\varepsilon \log(2d)$$

$$= O(\varepsilon \log(d/\varepsilon)).$$

(Using Fact 6)

Combining these three steps implies $T = \Omega\left(\frac{d}{\varepsilon \log(d/\varepsilon)}\right)$.

### 3.3.2 Near-optimal lower bound for quantum agnostic learning

**Theorem 16.** Let $C$ be a concept class with VC-dim$(C) = d$. Then for every $\delta \in (0, 1/2)$ and $\varepsilon \in (0, 1/4)$, a quantum algorithm which $(\varepsilon, \delta)$-learns $C$ has quantum agnostic sample complexity $\Omega\left(\frac{d}{\varepsilon^2 \log(d/\varepsilon)} + \frac{\log(1/\delta)}{\varepsilon^2}\right)$.

**Proof.** The proof is analogous to Theorem 13, with the $B_i$ now being quantum samples for $D_a$, $|\psi_a\rangle = \sum_{i \in [d], \ell \in \{0, 1\}} \sqrt{D_a(i, \ell)} |i, \ell\rangle$. Again we only need to re-analyze step 3:

1. $I(A : B) \geq (1 - \delta)(1 - H(1/4))d - H(\delta) = \Omega(d)$.
2. $I(A : B) \leq T \cdot I(A : B_1)$.
3. $I(A : B_1) = O(\varepsilon^2 \log(d/\varepsilon))$.

**Proof.** As in step 3 of the proof of Theorem 15, it suffices to upper bound the entropy of

$$\rho = \frac{1}{2d} \sum_{a \in \{0, 1\}^d} |\psi_a\rangle \langle \psi_a|.$$

We will lower bound the largest singular value of $\rho$. Consider state $|\psi\rangle = \frac{1}{\sqrt{2d}} \sum_{i \in [d], \ell \in \{0, 1\}} |i, \ell\rangle$.

$$\langle \psi | \psi_a \rangle = \frac{1}{d} \sum_{i \in [d]} \frac{1}{2} \left( \sqrt{1 + 4\varepsilon} + \sqrt{1 - 4\varepsilon} \right) = \frac{1}{2} \left( \sqrt{1 + 4\varepsilon} + \sqrt{1 - 4\varepsilon} \right) \geq 1 - 2\varepsilon^2 - O(\varepsilon^4),$$

where the last inequality used the Taylor series expansion of $\sqrt{1 + x}$. This implies that the largest singular value of $\rho$ is at least

$$\langle \psi | \rho | \psi \rangle = \frac{1}{2d} \sum_{a \in \{0, 1\}^d} |\langle \psi | \psi_a \rangle|^2 \geq 1 - 4\varepsilon^2 - O(\varepsilon^4).$$

We can now finish as in step 3 of the proof of Theorem 15:

$$I(A : B_1) \leq S(\rho) \leq O(H(\varepsilon^2) + \varepsilon^2 \log d) \quad \text{Fact 6} \quad \geq 6 \quad O(\varepsilon^2 \log(d/\varepsilon)).$$

Combining these three steps implies $T = \Omega\left(\frac{d}{\varepsilon^2 \log(d/\varepsilon)}\right)$. \qed
4 A lower bound by analysis of state identification

In this section we present a tight lower bound on quantum sample complexity for both the PAC and the agnostic learning settings, using ideas from Fourier analysis to analyze the performance of the Pretty Good Measurement. The core of both lower bounds is the following theorem.

**Theorem 17.** For $m \geq 10$, let $f : \{0, 1\}^m \rightarrow \mathbb{R}$ be defined as $f(z) = (1 - \beta |z|)^T$ for some $\beta \in (0, 1]$ and $T \in [1, m/(e^3 \beta)]$. For $k \leq m$, let $M \in \mathbb{F}_2^{m \times k}$ be a matrix with rank $k$. Suppose $A \in \mathbb{R}^{2^k \times 2^k}$ is defined as $A(x, y) = (f \circ M)(x + y)$ for $x, y \in \{0, 1\}^k$, then

$$\sqrt{A}(x, x) \leq \frac{2\sqrt{e}}{2^{k/2}} \left(1 - \frac{\beta}{2}\right)^{T/2} e^{11T^2 \beta^2/m + \sqrt{Tm\beta}} \text{ for all } x \in \{0, 1\}^k.$$

**Proof.** We first make an observation that relates the eigenvalues of a matrix $P$ defined as $P(x, y) = g(x + y)$ for $x, y \in \{0, 1\}^k$, to the Fourier coefficients of $g$.

**Claim 18.** Suppose $g : \{0, 1\}^k \rightarrow \mathbb{R}$ and $P \in \mathbb{R}^{2^k \times 2^k}$ is defined as $P(x, y) = g(x + y)$, then the eigenvalues of $P$ are $\{2^k \hat{g}(Q) : Q \in \{0, 1\}^k\}$.

**Proof.** Let $H \in \mathbb{R}^{2^k \times 2^k}$ be the matrix defined as $H(x, y) = (-1)^{x \cdot y}$ for $x, y \in \{0, 1\}^k$. It is easy to see that $H^{-1}(x, y) = (-1)^{x \cdot y}/2^k$. We now show that $H$ diagonalizes $P$:

$$(HPH^{-1})(x, y) = \frac{1}{2^k} \sum_{z_1, z_2 \in \{0, 1\}^k} (-1)^{x \cdot z_1 + y \cdot z_2} \hat{g}(z_1 + z_2)$$

$$= \frac{1}{2^k} \sum_{z_1, z_2 \in \{0, 1\}^k} (-1)^{z_1 \cdot x + z_2 \cdot y} \hat{g}(Q)(-1)^Q(z_1 + z_2) \quad \text{(Fourier expansion of $g$)}$$

$$= \frac{1}{2^k} \sum_{Q \in \{0, 1\}^k} \hat{g}(Q) \sum_{z_1 \in \{0, 1\}^k} (-1)^{Q \cdot z_1} \sum_{z_2 \in \{0, 1\}^k} (-1)^{Q \cdot z_2}$$

$$= 2^k \hat{g}(x) \delta_{x, y} \quad \text{(using } \sum_{z \in \{0, 1\}^k} (-1)^{a+b}z = 2^k \delta_{a,b}).$$

The eigenvalues of $P$ are the diagonal entries, $\{2^k \hat{g}(Q) : Q \in \{0, 1\}^k\}$.

We now relate the eigenvalues of $A$ to the Fourier coefficients of $f$:

**Claim 19.** For all $x \in \{0, 1\}^k$, we have

$$\sqrt{A}(x, x) = \frac{1}{2^{k/2}} \sum_{Q \in \{0, 1\}^k} \sqrt{\sum_{S \in \{0, 1\}^k : M' \cdot S = Q} \hat{f}(S)}.$$

**Proof.** Since $A(x, y) = (f \circ M)(x + y)$, by Claim 18 it follows that $H$ (as defined in the proof of Claim 18) diagonalizes $A$ and the eigenvalues of $A$ are $\{2^k \hat{f} \circ \hat{M}(Q) : Q \in \{0, 1\}^k\}$. Hence, we have

$$\sqrt{A} = H^{-1} \cdot \text{diag}(\{\sqrt{2^k \hat{f} \circ \hat{M}(Q) : Q \in \{0, 1\}^k}\}) \cdot H,$$

and the diagonal entries of $\sqrt{A}$ are

$$\sqrt{A}(x, x) = \frac{1}{2^{k/2}} \sum_{Q \in \{0, 1\}^k} \sqrt{\hat{f} \circ \hat{M}(Q)}$$

$$= \frac{1}{2^{k/2}} \sum_{Q \in \{0, 1\}^k} \sqrt{\sum_{S \in \{0, 1\}^k : M' \cdot S = Q} \hat{f}(S)}.$$

(18) diagonalizes $A$.
In the following lemma, we give an upper bound on the Fourier coefficients of \( f \), which in turn (from the claim above) gives an upper bound on the diagonal entries of \( \sqrt{A} \).

**Lemma 20.** The Fourier coefficients of \( f : \{0,1\}^m \rightarrow \mathbb{R} \) defined as \( f(z) = (1 - \frac{\beta |z|}{m})^T \), satisfy

\[
0 \leq \hat{f}(S) \leq 4e \left( 1 - \frac{\beta}{2} \right) \left( \frac{T^2 \beta}{m} \right)^q e^{2 \pi T^2 \beta^2 / m}, \quad \text{for all } S \text{ such that } |S| = q.
\]

**Proof.** In order to see why the Fourier coefficients of \( f \) are non-negative, we first define the set \( U = \{ u_x^T \}_{x \in \{0,1\}^m} \) where \( u_x = \sqrt{1 - \beta |0,0| + \sqrt{\beta / m} \sum_{i \in [m]} |i, x_i|} \). Let \( V \) be the \( 2^m \times 2^m \) Gram matrix for the set \( U \). For \( x, y \in \{0,1\}^m \), we have

\[
V(x, y) = (u_x^* u_y)^T = \left( 1 - \beta + \frac{\beta}{m} \sum_{i=1}^{m} (x_i | y_i) \right)^T = \left( 1 - \beta + \frac{\beta}{m} (m - |x + y|) \right)^T = \left( 1 - \beta \frac{|x + y|}{m} \right)^T = f(x + y).
\]

By Claim 18, the eigenvalues of the Gram matrix \( V \) are \( \{ 2^m \hat{f}(S) : S \in \{0,1\}^m \} \). Since the Gram matrix is psd, the eigenvalues are non-negative, which implies that \( \hat{f}(S) \geq 0 \) for all \( S \in \{0,1\}^m \).

We now prove the upper bound in the lemma. By definition,

\[
\hat{f}(S) = \mathbb{E}_{z \in \{0,1\}^m} \left[ (1 - \frac{|z|}{m})^T (-1)^S z \right]
= \mathbb{E}_{z \in \{0,1\}^m} \left[ (1 - \frac{\beta}{2} + \frac{\beta}{2m} \sum_{i=1}^{m} (-1)^i) \right]^T (-1)^S z
= \sum_{\ell=0}^{T} \binom{T}{\ell} (1 - \frac{\beta}{2})^{T-\ell} \left( \frac{\beta}{2m} \right)^\ell \mathbb{E}_{z \in \{0,1\}^m} \left[ \sum_{i_1, \ldots, i_\ell=1}^{m} (-1)^{z_{i_1} + \cdots + z_{i_\ell}} \right]
= \sum_{\ell=0}^{T} \binom{T}{\ell} (1 - \frac{\beta}{2})^{T-\ell} \left( \frac{\beta}{2m} \right)^\ell \sum_{i_1, \ldots, i_\ell=1}^{m} 1_{\{ z_{i_1} + \cdots + z_{i_\ell} = 0 \}} \quad \text{(using } \mathbb{E}_{z \in \{0,1\}^m} \left[ (-1)^{z_1 + z_2} \right] = \delta_{z_1, z_2} \text{)}
\]

We will use the following claim to upper bound the combinatorial sum in the quantity above.

**Claim 21.** Fix \( S \in \{0,1\}^m \) with Hamming weight \( |S| = q \). For every \( \ell \in \{q, \ldots, T\} \), we have

\[
\sum_{i_1, \ldots, i_\ell=1}^{m} 1_{\{ z_{i_1} + \cdots + z_{i_\ell} = 0 \}} \leq \begin{cases} \ell! \cdot m^{(\ell-q)/2} \left( 2^{(\ell-q)/2} ((\ell - q)/2) \right) & \text{if } (\ell - q) \text{ is even} \\ 0 & \text{otherwise} \end{cases}
\]

**Proof.** Since \( |S| = q \), we can write \( S = e_{i_1} + \cdots + e_{i_q} \) for distinct \( r_1, \ldots, r_q \in [m] \). There are \( \binom{m}{q} \) ways to pick \( q \) indices in \( (i_1, \ldots, i_\ell) \) (w.l.o.g. let them be \( i_1, \ldots, i_q \)) and there are \( q! \) factorial ways to assign \( (r_1, \ldots, r_q) \) to \( (i_1, \ldots, i_q) \). It remains to count the number of ways that we can assign values to the remaining indices \( i_{q+1}, \ldots, i_\ell \) such that \( e_{i_{q+1}} + \cdots + e_{i_\ell} = 0 \). If \( \ell - q \) is odd then this number is 0, so from now on assume \( \ell - q \) is even. We upper bound the number of such assignments by partitioning the \( \ell - q \) indices into pairs and assigning the same value to both indices in each pair.

We first count the number of ways to partition a set of \( \ell - q \) indices into subsets of size 2. This number is exactly \( (\ell - q)! \left( 2^{(\ell-q)/2} ((\ell - q)/2)! \right)^{-1} \). Furthermore, there are \( m \) possible values that can be assigned to the pair of indices in each of the \( (\ell - q)/2 \) subsets such that \( e_i + e_j = 0 \) within
each subset. Note that assigning \( m \) possible values to each pair of indices in the \((\ell - q)/2\) subsets overcounts, but this rough upper bound is sufficient for our purposes.

Combining the three arguments, we conclude

\[
\sum_{r_{1,\ldots, r_{\ell}}=1}^{d} 1_{[e_{r_{1}} + \ldots + e_{r_{\ell}} = S]} \leq \left( \frac{\ell}{q} \right)! \cdot (\ell - q)! \cdot m^{(\ell - q)/2} \left( 2^{(\ell - q)/2} \left( \frac{\ell - q}{2} \right)! \right).
\]

which yields the claim. \(\Box\)

Continuing with the evaluation of the Fourier coefficient and using the claim above, we have

\[
\widehat{f}(S) = \sum_{\ell=0}^{T} \left( T \right)^{\ell} \left( 1 - \frac{\beta}{2} \right)^{T - \ell} \left( \frac{\beta}{2m} \right)^{\ell} \sum_{r_{1,\ldots, r_{\ell}}=1}^{m} 1_{[e_{r_{1}} + \ldots + e_{r_{\ell}} = S]}
\]

\[
\leq \sum_{\ell=q}^{T} \left( T \right)^{\ell} \left( 1 - \frac{\beta}{2} \right)^{T - \ell} \left( \frac{\beta}{2m} \right)^{\ell} \cdot m^{(\ell - q)/2} \left( 2^{(\ell - q)/2} \left( \frac{\ell - q}{2} \right)! \right)
\]

(by Claim 21)

\[
= \left( 1 - \frac{\beta}{2} \right)^{T} \left( \frac{2}{m} \right)^{q/2} \sum_{\ell=q}^{T} \left( T \right)^{\ell} \left( \frac{\beta}{m(2 - \beta)} \right)^{\ell} \cdot m^{\ell/2} \left( \frac{\ell - q}{2} \right)!
\]

(since \( \beta < 1 \) and \( \frac{T}{\ell)! \leq T^{\ell} \))

\[
= \left( 1 - \frac{\beta}{2} \right)^{T} \left( \frac{2}{m} \right)^{q/2} \sum_{\ell=q}^{T} \left( \frac{T \beta}{m} \right)^{\ell} \cdot \frac{1}{(r/2)!}
\]

(substituting \( r \leftarrow (\ell - q) \))

\[
\leq \left( 1 - \frac{\beta}{2} \right)^{T} \left( \frac{2}{m} \right)^{q/2} \sum_{\ell=q}^{T} \left( \frac{T \beta}{\sqrt{2m}} \right)^{\ell} \cdot \frac{1}{(r/2)!}
\]

(using \( n! \geq (n/e)^{n} \))

\[
= \left( 1 - \frac{\beta}{2} \right)^{T} \left( \frac{2}{m} \right)^{q/2} \sum_{r=0}^{T} \left( \frac{\sqrt{e} T \beta}{\sqrt{4m}} \right)^{r}
\]

(since the summands are \( \geq 0 \))

\[
= \left( 1 - \frac{\beta}{2} \right)^{T} \left( \frac{2}{m} \right)^{q/2} \left( \sum_{r=0}^{T} \left( \frac{\sqrt{e} T \beta}{\sqrt{4m}} \right)^{r} \right)
\]

Note that by the assumptions of the theorem, \( T^{2} e^{3} \beta^{2}/m \leq T \beta \leq T \), which allowed us to split the sum into two pieces in the last equality. At this point, we upper bound both pieces in the last equation separately. For the first piece, using Claim 5 it follows that \( \left( \frac{\sqrt{e} T \beta}{\sqrt{4m}} \right)^{r} \) is maximized at \( r = \left[ T^{2} \beta^{2}/m \right] \). Hence we get

\[
\left[ e^{3} T^{2} \beta^{2}/m \right] \sum_{r=0}^{\left[ e^{3} T^{2} \beta^{2}/m \right]} \left( \frac{\sqrt{e} T \beta}{\sqrt{4m}} \right)^{r} \leq \left( 2 \cdot \frac{1}{2} \right) e^{2} T^{2} \beta^{2}/m^{1/2} \leq 2 e^{2} T^{2} \beta^{2}/m^{1/2} \leq 2 e^{2} T^{2} \beta^{2}/m^{1/2},
\]

(6)
where the first inequality uses Claim 5 and the second inequality uses $2 + x \leq 2e^x$ for $x \geq 0$ and $e^3 + 1/2 \leq 22$. For the second piece, we use

$$\sum_{r=[e^3T^2/2]/m+1}^{T} \left( \frac{\sqrt{e} T \beta}{m} \right)^r \leq \sum_{r=[e^3T^2/2]/m+1}^{T} \left( \frac{1}{e} \right)^r \leq \sum_{r=1}^{T} \left( \frac{1}{e} \right)^r = \frac{1-e^{-T}}{e-1} \leq 2/3. \quad (7)$$

So we finally get

$$\hat{f}(S) \leq \left( 1 - \frac{\beta}{2} \right)^T \left( \frac{T \beta}{m} \right)^q \left( 2e^{22T^2 \beta^2/m+1} + 2/3 \right) \quad \text{(using Eq. (6), (7))}$$

$$\leq 4 \epsilon \left( 1 - \frac{\beta}{2} \right)^T \left( \frac{T \beta}{m} \right)^q e^{22T^2 \beta^2/m} \quad \text{(since } 22T^2 \beta^2/m > 0)$$

The theorem follows by putting together Claim 19 and Lemma 20:

$$\sqrt{A}(x, x) = \frac{1}{2k^2} \sum_{Q \in \{0, 1\}^s} \sum_{S \in \{0, 1\}^{m}: M^t S = Q} \sqrt{\hat{f}(S)} \quad \text{(using Claim 19)}$$

$$\leq \frac{1}{2k^2} \sum_{Q \in \{0, 1\}^s} \sum_{S \in \{0, 1\}^{m}: M^t S = Q} \sqrt{\hat{f}(S)} \quad \text{(using lower bound from Lemma 20)}$$

$$= \frac{1}{2k^2} \sum_{S \in \{0, 1\}^{m}} \sqrt{\hat{f}(S)} \quad \text{($U_Q[M^t S = Q] = \{0, 1\}^m$ since rank($M$)=k)}$$

$$= \frac{1}{2k^2} \sum_{Q \in \{0, 1\}^s} \sum_{|S| = q} \sqrt{\hat{f}(S)}$$

$$\leq 2 \sqrt{e} \left( 1 - \frac{\beta}{2} \right)^{T/2} e^{11T^2 \beta^2/m} \sum_{q=0}^{m} \binom{m}{q} \left( \frac{T \beta}{m} \right)^{q/2} \quad \text{(using Lemma 20)}$$

$$= \frac{2 \sqrt{e}}{2k^2} \left( 1 - \frac{\beta}{2} \right)^{T/2} e^{11T^2 \beta^2/m} \left( 1 + \sqrt{T \beta/m} \right)^m \quad \text{($\binom{m}{q} \leq (1+q)^q$)}$$

$$\leq \frac{2 \sqrt{e}}{2k^2} \left( 1 - \frac{\beta}{2} \right)^{T/2} e^{11T^2 \beta^2/m + \sqrt{T \beta m}}. \quad \text{(using } (1+x)^t \leq e^{xt} \text{ for } x, t \geq 0)$$

4.1 Optimal lower bound for quantum PAC learning

**Theorem 22.** Let $C$ be a concept class with $\text{VC-dim}(C) = d + 1$, for sufficiently large $d$. Then for every $\delta \in (0, 1/2)$ and $\epsilon \in (0, 1/20)$, a quantum algorithm which $(\epsilon, \delta)$-learns $C$ has quantum PAC sample complexity $\Omega\left( \frac{d}{\epsilon} + \frac{1}{\epsilon} \log \frac{1}{\delta} \right)$.

**Proof.** The $d$-independent part of the lower bound is Lemma 10. To prove the $d$-dependent part, define a distribution $D$ on a set $S = \{s_0, \ldots, s_d\} \subseteq \{0, 1\}^n$ that is shattered by $C$ as follows: $D(s_0) = 1 - 20\delta$ and $D(s_i) = 20\delta/d$ for all $i \in [d]$.

Now consider a $[d, k, r]$ linear code (for $k \geq d/4$, distance $r \geq d/8$) as shown to exist in Theorem 3 with the generator matrix $M \in \mathbb{F}_2^{d \times k}$ of rank $k$. Let $\{Mx : x \in \{0, 1\}^k\} \subseteq \{0, 1\}^d$ be the set of
codewords in this linear code; these satisfy \( d_H(Mx, My) \geq d/8 \) whenever \( x \neq y \). For each \( x \in \{0, 1\}^k \), let \( c^x \) be a concept defined on the shattered set as: \( c^x(s_i) = 0 \) and \( c^x(s_i) = (Mx) \) for all \( i \in [d] \). The existence of such concepts in \( \mathbb{C} \) follows from the fact that \( S \) is shattered by \( \mathbb{C} \). From the distance property of the code, we have \( \Pr_{s \sim D}[c_i^s \neq c_i^t] \geq \frac{20k d}{d^2} \) for all \( i \in [d] \). This in particular implies that an \((\epsilon, \delta)\)-quantum PAC learner that tries to \( \epsilon \)-approximate a concept from \( \{c^x : x \in \{0, 1\}^k\} \) should successfully identify that concept with probability at least \( 1 - \delta \).

We now consider the following state identification problem: for \( x \in \{0, 1\}^k \), denote \( \psi_x = \sum_{i \in [0, \ldots, d]} \sqrt{D(s_i)}|s_i, c^x(s_i)\rangle \). Let the quantum PAC sample complexity be \( T \) and assume \( T \leq d/(20e^2 \epsilon) \), since otherwise \( T \geq \Omega(d/\epsilon) \) and the theorem follows. Suppose the learner has knowledge of the ensemble \( \mathcal{E} = \{(2^{-k}, |\psi_x\rangle^\otimes T) : x \in \{0, 1\}^k\} \), and is given \( |\psi_x\rangle^\otimes T \in \mathcal{E} \) for a uniformly random \( x \). The learner would like to maximize the average probability of success to identify the given state. For this problem, we prove a lower bound on \( T \) using the PGM defined in Section 2.6. In particular, we show that using the PGM, if a learner successfully identifies the states in \( \mathcal{E} \), then \( T = \Omega(d/\epsilon) \). Since the PGM is the optimal measurement\(^5\) that the learner could have performed, the result follows. The following lemma makes this lower bound rigorous and will conclude the proof of the theorem.

**Lemma 23.** For \( x \in \{0, 1\}^k \) let \( \psi_x = \sum_{i \in [0, \ldots, d]} \sqrt{D(s_i)}|s_i, c^x(s_i)\rangle \), and \( \mathcal{E} = \{(2^{-k}, |\psi_x\rangle^\otimes T) : x \in \{0, 1\}^k\} \). Then\(^6\)

\[
\Pr_{\psi_x \sim \mathcal{E}}[\text{success}] \geq \frac{4e\epsilon}{2d/4+T e} e^{8800T^2 \epsilon^2/d + 4\sqrt{T d} \epsilon}.
\]

Before we prove the lemma, we first show why it implies the theorem. Since we observed above that \( \Pr_{\psi_x \sim \mathcal{E}}[\text{success}] = \Pr_{\psi_x \sim \mathcal{E}}[\text{success}] = \Omega(1) \) (say for \( \delta = 1/4 \)), which in turn implies

\[
\Omega(\max\{d, T \epsilon\}) \leq O(\min\{T^2 \epsilon^2/d, \sqrt{T d} \epsilon\}).
\]

Note that if \( T \epsilon \) maximizes the left-hand side, then \( d \leq T \epsilon \) and hence \( T \geq \Omega(d/\epsilon) \). The remaining cases are \( \Omega(d) \leq T^2 \epsilon^2/d \) and \( \Omega(d) \leq \sqrt{T d} \epsilon \). Both these statements give us \( T \geq \Omega(d/\epsilon) \). Hence the theorem follows, and it remains to prove Lemma 23:

**Proof.** Let \( \mathcal{E}' = \{(2^{-k/2}, |\psi_x\rangle^\otimes T) : x \in \{0, 1\}^k\} \) and \( G \) be the \( 2^k \times 2^k \) Gram matrix for \( \mathcal{E}' \). As we saw in Section 2.6, the success probability of identifying the states in the ensemble \( \mathcal{E} \) using the PGM is

\[
\Pr_{\psi_x \sim \mathcal{E}}[\text{success}] = \sum_{x \in \{0, 1\}^k} \sqrt{G(x, x)}.
\]

For all \( x, y \in \{0, 1\}^k \), the entries of the Gram matrix \( G \) can be written as:

\[
G(x, y) = \frac{1}{2^k} \langle \psi_x | \psi_y \rangle^T = \frac{1}{2^k} \left( (1 - 20 \epsilon) + \frac{20 \epsilon}{d} \sum_{i=1}^{d} \langle c^x(s_i) | c^y(s_i) \rangle \right)^T
\]

\[
= \frac{1}{2^k} \left( (1 - 20 \epsilon) + \frac{20 \epsilon}{d} (d - d_H(Mx, My)) \right)^T = \frac{1}{2^k} \left( (1 - 20 \epsilon) + \frac{20 \epsilon}{d} d_H(Mx, My) \right)^T.
\]

\(^5\)For \( x \in \{0, 1\}^k \), define unitary \( U_{x,c} : |s_i, b\rangle \rightarrow |s_i, b + c^x(s_i)\rangle \) for all \( i \in [0, \ldots, d] \). The ensemble \( \mathcal{E} \) is generated by applying \( \{U_{x,c} : x \in \{0, 1\}^k \} \) to \( \sum_{i \in [0, \ldots, d]} \sqrt{D(s_i)}|s_i, 0\rangle \). View \( c^x = (0, Mx) \in \{0, 1\}^{d+1} \) as a concatenated string where \( Mx \) is a codeword of the \( [d, k, r]_2 \) code. Since the \( 2^k \) codewords of the \( [d, k, r]_2 \) code form a linear subspace, \( \{U_{x,c} : x \in \{0, 1\}^k \} \) is an Abelian group. From the discussion in Section 2.6, we conclude that the PGM is the optimal measurement for this state identification problem.

\(^6\)We made no attempt to optimize the constants here.
where $Mx, My \in \{0,1\}^d$ are codewords in the linear code defined earlier. Define $f : \{0,1\}^d \rightarrow \mathbb{R}$ as $f(z) = (1 - \frac{2k}{d} |z|)^T$, and let $A(x,y) = (f \circ M)(x + y)$ for $x,y \in \{0,1\}^k$. Note that $G = A/2^k$. Since we assumed $T \leq d/(20\varepsilon^3\delta)$, we can use Theorem 17 (by choosing $m = d$ and $\beta = 20\varepsilon$) to upper bound the success probability of successfully identifying the states in the ensemble $\mathcal{E}$ using the PGM.

$$p^{PGM}(\mathcal{E}) = \sum_{x \in \{0,1\}^{S}} \sqrt{A(x,x)^2}$$

$$= \frac{1}{2^k} \sum_{x \in \{0,1\}^{S}} \sqrt{A(x,x)^2}$$

$$\leq \frac{4e}{2^k} \left(1 - \frac{\beta}{2}\right)^T e^{22T^2\beta^2/d + 2\sqrt{Td\beta}}$$

$$= \frac{4e}{2^k} \left(1 - 10\varepsilon\right)^T e^{8800T^2\varepsilon^2/d + 4\sqrt{5Td\varepsilon}}$$

$$\leq \frac{4e}{2^k + T\varepsilon} e^{8800T^2\varepsilon^2/d + 4\sqrt{5Td\varepsilon}}$$

The lemma follows by observing that $k \geq d/4$.

4.2 Optimal lower bound for quantum agnostic learning

We now use the same approach to obtain a tight lower bound on quantum sample complexity in the agnostic setting.

**Theorem 24.** Let $\mathcal{C}$ be a concept class with VC-dim($\mathcal{C}$) = $d$, for sufficiently large $d$. Then for every $\delta \in (0,1/2)$ and $\varepsilon \in (0,1/10)$, a quantum algorithm which $(\varepsilon, \delta)$-learns $\mathcal{C}$ has quantum agnostic sample complexity $\Omega\left(\frac{d}{\varepsilon^2} + \frac{1}{\varepsilon} \log \frac{1}{\delta}\right)$.

**Proof.** The $d$-independent part of the lower bound is Lemma 11. For the $d$-dependent term in the lower bound, consider a $[d,k,r]_2$ linear code (for $k \geq d/4$, distance $r \geq d/8$) as shown to exist in Theorem 3, with generator matrix $M \in \mathbb{F}_2^{d \times k}$ of rank $k$. Let $\{Mx : x \in \{0,1\}^k\} \subseteq \{0,1\}^d$ be the set of $2^k$ codewords in this linear code; these satisfy $d_H(Mx,My) \geq d/8$ whenever $x \neq y$. To each codeword $x \in \{0,1\}^k$ we associate a distribution $D_x$ as follows:

$$D_x(s_i, b) = \frac{1}{d} \left(\frac{1}{2} + \frac{1}{2}\right)_{-1}^{(Mx)_i + b a}, \text{ for } (i,b) \in [d] \times \{0,1\},$$

where $S = \{s_1, \ldots, s_d\}$ is a set that is shattered by $\mathcal{C}$, and $a$ is a parameter which we shall pick later. Let $c^x \in \mathcal{C}$ be a concept that labels $S$ according to $Mx \in \{0,1\}^d$. The existence of such $c^x \in \mathcal{C}$ follows from the fact that $S$ is shattered by $\mathcal{C}$. Note that $c^x$ is the minimal-error concept in $\mathcal{C}$ w.r.t. $D_x$, (i.e., $c^x$ is the Bayes classifier for the distribution $D_x$). A learner that labels $S$ according to some string $\ell \in \{0,1\}^d$ has additional error $d_H(Mx,\ell) \cdot a/d$ compared to $c^x$. This in particular implies that an $(\varepsilon, \delta)$-quantum agnostic learner has to find (with probability at least $1 - \delta$) an $\ell$ such that $d_H(Mx,\ell) \leq d\varepsilon/a$. We pick $a = 20\varepsilon$ and we get $d_H(Mx,\ell) \leq d/20$. However, since $Mx$ was a codeword of a $[d,k,r]_2$ code with distance $r \geq d/8$, finding an $\ell$ satisfying $d_H(Mx,\ell) \leq d/20$ is equivalent to identifying $Mx$, and hence $x$. 

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Now consider the following state identification problem: let $|\psi_x\rangle = \sum_{(i,b)\in[d]\times\{0,1\}} \sqrt{D_x(s_i,b)}|s_i,b\rangle$ for $x \in \{0,1\}^k$. Let the quantum agnostic sample complexity be $T$. Assume $T \leq d/(100\varepsilon^2)$, since otherwise $T \geq \Omega(d/\varepsilon^2)$ and the theorem follows. Suppose the learner has knowledge of the ensemble $\mathcal{E} = \{(2^{-k},|\psi_x\rangle^T) : x \in \{0,1\}^k\}$, and is given $|\psi_x\rangle^T \in \mathcal{E}$ for uniformly random $x$. The learner would like to maximize the average probability of success to identify the given state. For this problem, we prove a lower bound on $T$ using the PGM defined in Section 2.6. In particular, we show that using the PGM, if a learner successfully identifies the states in $\mathcal{E}$, then $T = \Omega(d/\varepsilon^2)$. Since the PGM is the optimal measurement\footnote{For $x \in \{0,1\}^k$, define unitary $U_{c,x} = \sum_{i\in[d]}|x_i\rangle|s_i\rangle \otimes X^{(M_x)}$, where $X$ is the NOT-gate, so $X^{(M_x)}|b\rangle = |b + (M_x)i\rangle$ for $b \in \{0,1\}$. The ensemble $\mathcal{E}$ is generated by applying $(U_{c,x})_{x\in\{0,1\}^k}$ to $\frac{1}{\sqrt{d}} \sum_{(i,b)\in[d]\times\{0,1\}} \sqrt{\frac{1}{2} \oplus \frac{1}{2} (-1)^b \alpha|s_i,b\rangle}$. Since the $2^k$ codewords of the $[d,k,r]$ code form a linear subspace, $(U_{c,x})_{x\in\{0,1\}^k}$ is an Abelian group. From the discussion in Section 2.6, we conclude that the PGM is the optimal measurement for this state identification problem.} that the learner could have performed, the result follows. The following lemma makes this lower bound rigorous and will conclude the proof of the theorem.

**Lemma 25.** For $x \in \{0,1\}^k$, let $|\psi_x\rangle = \sum_{(i,b)\in[d]\times\{0,1\}} \sqrt{D_x(s_i,b)}|s_i,b\rangle$, and $\mathcal{E} = \{(2^{-k},|\psi_x\rangle^T) : x \in \{0,1\}^k\}$. Then

$$p_{PGM}(\mathcal{E}) \leq \frac{4e}{d\ln 2 \sqrt{2\pi T}} e^{220000T^2\varepsilon^4/d + 20\sqrt{Td}\varepsilon^2}.$$ 

Before we prove the lemma, we first show why it implies the theorem. Since we observed above that $p^{opt}(\mathcal{E}) = p_{PGM}(\mathcal{E})$, a good learner satisfies $p_{PGM}(\mathcal{E}) = \Omega(1)$ (say for $\delta = 1/4$), which in turn implies

$$\Omega(\max\{d, T\varepsilon^2\}) \leq O(\min\{T^2\varepsilon^4/d, \sqrt{Td}\varepsilon^2\}).$$

Like in the proof of Theorem 22, this implies a lower bound of $T = \Omega(d/\varepsilon^2)$ and proves the theorem. It remains to prove Lemma 25:

**Proof.** Let $\mathcal{E}' = \{(2^{-k/2}|\psi_x\rangle^T) : x \in \{0,1\}^k\}$ and $G$ be the $2^k \times 2^k$ Gram matrix for the set $\mathcal{E}'$. As we saw in Section 2.6, the success probability of identifying the states in the ensemble $\mathcal{E}$ using the PGM is

$$p_{PGM}(\mathcal{E}) = \sum_{x \in \{0,1\}^k} \sqrt{G(x,x)^2}.$$

For all $x, y \in \{0,1\}^k$, the entries of $G$ can be written as:

$$2^k \cdot G(x,y) = \langle \psi_x | \psi_y \rangle^T$$

$$= \left( \sum_{(i,b)\in[d]\times\{0,1\}} \sqrt{D_x(i,b)D_y(i,b)} \right)^T$$

$$= \left( \frac{1}{2d} \sum_{(i,b)\in[d]\times\{0,1\}} \sqrt{(1 + 10\varepsilon(-1)^{(M_x)\langle i,b\rangle})(1 + 10\varepsilon(-1)^{(M_y)\langle i,b\rangle})} \right)^T$$

$$= \left( \frac{1}{2d} \sum_{(i,b): (M_x)\langle i\rangle = (M_y)\langle i\rangle} (1 + 10\varepsilon(-1)^{(M_x)\langle i,b\rangle}) + \frac{1}{2d} \sum_{(i,b): (M_x)\langle i\rangle \neq (M_y)\langle i\rangle} \sqrt{1 - 100\varepsilon^2} \right)^T$$

$$= \left( \frac{d - d_H(M_x,M_y)}{d} + \frac{\sqrt{1 - 100\varepsilon^2}}{d} d_H(M_x,M_y) \right)^T$$

$$= \left( 1 - \frac{\sqrt{1 - 100\varepsilon^2}}{d} d_H(M_x,M_y) \right)^T.$$
(first inequality is by assumption and the second inequality follows for \( \varepsilon \leq 1/10 \) and \( \beta \leq 1 \)). Since we assumed \( T \leq d/(100^3\varepsilon^2) \), we can use Theorem 17 (by choosing \( m = d \) and \( \beta = 1 - \sqrt{1 - 100\varepsilon^2} \)) to upper bound the success probability of identifying the states in the ensemble \( E \):

\[
P^{PGM}(E) = \sum_{x \in \{0,1\}^k} \sqrt{G(x,x)}^2
\]

\[
= \frac{1}{2^k} \sum_{x \in \{0,1\}^k} \sqrt{A(x,x)}^2
\]

(since \( G = A/2^k \))

\[
\leq \frac{4e}{2^k} \left( 1 - \frac{\beta}{2} \right)^T e^{22T^2\beta^2/d + 2\sqrt{Td\beta}}
\]

(using Theorem 17)

\[
\leq \frac{4e}{2^k} \left( 1 - \frac{\beta}{2} \right)^T e^{220000T^2\varepsilon^4/d + 20\sqrt{Td\varepsilon}}
\]

(using \( \beta = 1 - \sqrt{1 - 100\varepsilon^2} \leq 100\varepsilon^2 \))

\[
\leq \frac{4e}{2^k} \left( 1 - 25\varepsilon^2 \right)^T e^{220000T^2\varepsilon^4/d + 20\sqrt{Td\varepsilon}}
\]

(using \( (1 - x)^t \leq e^{-xt} \) for \( x, t \geq 0 \))

The lemma follows by observing that \( k \geq d/4 \).

\[\square\]

### 4.3 Additional results

In this section we mention two additional results that can also be obtained using Theorem 17.

#### 4.3.1 Quantum PAC sample complexity under random classification noise

In the theorem below, we show a lower bound on the quantum PAC sample complexity under the random classification noise model with noise rate \( \eta \). Recall that in this model, for every \( c \in C \) and distribution \( D, \epsilon, \delta > 0 \), given access to copies of the \( \eta \)-noisy state,

\[
\sum_{x \in \{0,1\}^n} \sqrt{(1-\eta)D(x)|x, c(x)} + \sqrt{\eta D(x)|x, 1-c(x)},
\]

a quantum PAC learner is required to output an hypothesis \( h \) such that \( err_D(c,h) \leq \epsilon \) with probability at least \( 1 - \delta \).

**Theorem 26.** Let \( C \) be a concept class with VC-dim\((C) = d + 1 \), for sufficiently large \( d \). Then for every \( \delta \in (0, 1/2), \epsilon \in (0, 1/20) \) and \( \eta \in (0, 1/2) \), a quantum algorithm which \((\epsilon, \delta)\)-learns \( C \) in the PAC setting with noisy labels (with noise rate \( \eta \)) has quantum PAC sample complexity \( \Omega\left(\frac{d}{(1-2\eta)^2\epsilon} + \frac{\log(1/\delta)}{(1-2\eta)^2\epsilon} \right) \).

One can use exactly the same proof technique as in Lemma 10 and Theorem 22 to prove this, with only the additional inequality \( 1 - 2\sqrt{\eta(1-\eta)} \leq (1 - 2\eta)^2 \), which holds for \( \eta \leq 1/2 \). We omit the details of the calculation.
4.3.2 Distinguishing codeword states

Ashley Montanaro (personal communication) alerted us to the following interesting special case of our PGM-based result.

Consider an \([n,k,d]_2\) linear code \(\{Mx : x \in \{0,1\}^k\}\), where \(M \in \mathbb{F}_2^{n \times k}\) is the rank-\(k\) generator matrix of the code, \(k = \Omega(n)\), and distinct codewords have Hamming distance at least \(d\).\(^8\) For every \(x \in \{0,1\}^k\), define a codeword state \(|\psi_x\rangle = \frac{1}{\sqrt{n}} \sum_{i \in [n]} |i\rangle (Mx)_i\). These states form an example of a quantum fingerprinting scheme [BCWW01]: \(2^k\) states whose pairwise inner products are bounded away from 1. How many copies do we need to identify one such fingerprint?

Let \(E = \{(2^{-k}, |\psi_x\rangle) : x \in \{0,1\}^k\}\) be an ensemble of codeword states. Consider the following task: given \(T\) copies of an unknown state drawn uniformly from \(E\), we are required to identify the state with probability \(\geq 4/5\). From Holevo’s theorem one can easily obtain a lower bound of \(T = \Omega(k/\log n)\) copies, since the learner should obtain \(\Omega(k)\) bits of information (i.e., identify \(k\)-bit string \(x\) with probability \(\geq 4/5\)), while each copy of the codeword state gives at most \(O(\log n)\) bits of information. In the theorem below, we improve that \(\Omega(k/\log n)\) to the optimal \(\Omega(k)\) for constant-rate codes.

**Theorem 27.** Let \(E = \{|\psi_x\rangle = \frac{1}{\sqrt{n}} \sum_{i \in [n]} |i\rangle (Mx)_i : x \in \{0,1\}^k\}\), where \(M \in \mathbb{F}_2^{n \times k}\) is the generator matrix of an \([n,k,d]_2\) linear code with \(k = \Omega(n)\). Then \(\Omega(k)\) copies of an unknown state from \(E\) (drawn uniformly at random) are necessary to be able to identify that state with probability at least \(4/5\).

One can use exactly the proof technique of Theorem 22 to prove the theorem. Suppose we are given \(T\) copies of the unknown codeword state. Assume \(T \leq n\), since otherwise \(T \geq n \geq \sqrt{k}n\) and the theorem follows. Observe that the Gram matrix \(G\) for \(E' = \{(2^{-k/2}|\psi_x\rangle \otimes |T : x \in \{0,1\}^k\}\) can be written as 

\[
G(x,y) = \frac{1}{2^k} \left(1 - \frac{|M(x+y)|}{n}\right)^T
\]

for \(x,y \in \{0,1\}^k\). Using Theorem 17 (choosing \(\beta = 1\) and \(m = n\)) to upper bound the success probability of successfully identifying the states in the ensemble \(E\) using the PGM, we obtain

\[
p^\text{PGM}(E) \leq \frac{4e}{2^{k+T}} e^{22T^2/n + 2\sqrt{Tn}}.
\]

As in the proof of Theorem 22, this implies the lower bound of Theorem 27. We omit the details of the calculation.

5 Conclusion

The main result of this paper is that quantum examples give no significant improvement over the usual random examples in passive, distribution-independent settings. Of course, these negative results do not mean that quantum machine learning is useless. In our introduction we already mentioned improvements from quantum examples for learning under the uniform distribution; improvements from using quantum membership queries; and improvements in time complexity based on quantum algorithms like Grover’s and HHL. Quantum machine learning is still in its infancy, and we hope for many more positive results.

We end by identifying a number of open questions for future work:

- We gave lower bounds on sample complexity for the rather benign random classification noise. What about other noise models, such a malicious noise?

\(^8\)Note that throughout this paper \(C\) was a concept class in \([0,1]^n\) and \(d\) was the VC dimension of \(C\). The use of \(n,d\) in this section has been changed to conform to the convention in coding theory.
• What is the quantum sample complexity for learning concepts whose range is \([k]\) rather than \([0,1]\), for some \(k > 2\)? Even the classical sample complexity is not fully determined yet [SB14, Section 29.2].

• In the introduction we mentioned a few examples of learning under the uniform distribution where quantum examples are significantly more powerful than classical examples. Can we find more such examples of quantum improvements in sample complexity in fixed-distribution settings?

• Can we find more examples of quantum speed-up in time complexity of learning?

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References


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