

# Semidefinite code bounds based on quadruple distances

Dion C. Gijswijt<sup>1</sup>, Hans D. Mittelmann<sup>2</sup>,  
and Alexander Schrijver<sup>3</sup>

**Abstract.** Let  $A(n, d)$  be the maximum number of  $\{0, 1\}$  words of length  $n$ , any two having Hamming distance at least  $d$ . It is proved that  $A(20, 8) = 256$ , which implies that the quadruply shortened Golay code is optimal. Moreover, it is shown that  $A(18, 6) \leq 673$ ,  $A(19, 6) \leq 1237$ ,  $A(20, 6) \leq 2279$ ,  $A(23, 6) \leq 13674$ ,  $A(19, 8) \leq 135$ ,  $A(25, 8) \leq 5421$ ,  $A(26, 8) \leq 9275$ ,  $A(27, 8) \leq 17099$ ,  $A(21, 10) \leq 47$ ,  $A(22, 10) \leq 84$ ,  $A(24, 10) \leq 268$ ,  $A(25, 10) \leq 466$ ,  $A(26, 10) \leq 836$ ,  $A(27, 10) \leq 1585$ ,  $A(28, 10) \leq 2817$ ,  $A(25, 12) \leq 55$ , and  $A(26, 12) \leq 96$ .

The method is based on the positive semidefiniteness of matrices derived from quadruples of words. This can be put as constraint in a semidefinite program, whose optimum value is an upper bound for  $A(n, d)$ . The order of the matrices involved is huge. However, the semidefinite program is highly symmetric, by which its feasible region can be restricted to the algebra of matrices invariant under this symmetry. By block diagonalizing this algebra, the order of the matrices will be reduced so as to make the program solvable with semidefinite programming software in the above range of values of  $n$  and  $d$ .

Key words: algebra, code, error-correcting, programming, semidefinite

## 1. INTRODUCTION

For any  $n$ , we will identify elements of  $\{0, 1\}^n$  with  $\{0, 1\}$  words of length  $n$ . A *code* of length  $n$  is any subset  $C$  of  $\{0, 1\}^n$ . The (*Hamming*) *distance*  $d_H(v, w)$  between two words  $v, w$  is the number of  $i$ 's with  $v_i \neq w_i$ . The *minimum distance* of a code  $C$  is the minimum Hamming distance between any two distinct elements of  $C$ . Then  $A(n, d)$  denotes the maximum size (= cardinality) of a code of length  $n$  with minimum distance at least  $d$ .

Computing  $A(n, d)$  and finding upper and lower bounds for it have been long-time focuses in combinatorial coding theory (cf. MacWilliams and Sloane [15]). Classical is Delsarte's bound [4]. Its value can be described as the maximum  $A_2(n, d)$  of

$$(1) \quad \sum_{u, v \in \{0, 1\}^n} X_{u, v},$$

where  $X$  is a symmetric, nonnegative, positive semidefinite  $\{0, 1\}^n \times \{0, 1\}^n$  matrix with trace 1 and with  $X_{u, v} = 0$  if  $u, v \in \{0, 1\}^n$  are distinct and have distance less than  $d$ .<sup>4</sup> Then  $A(n, d) \leq A_2(n, d)$ , since for any nonempty code  $C$  of minimum distance at least  $d$ , the matrix  $X$  with  $X_{u, v} = |C|^{-1}$

if  $u, v \in C$  and  $X_{u, v} = 0$  otherwise, is a feasible solution with objective value  $|C|$ .

This is the *analytic* definition of the Delsarte bound (in the vein of Lovász [13], cf. [16], [20]). It is a semidefinite programming problem (cf. [9]), but of huge dimensions ( $2^n$ ), which makes it hard to compute in this form.

However, the problem is highly symmetric. Let  $G$  denote the isometry group of  $\{0, 1\}^n$  (i.e., the group of distance preserving permutations of the set  $\{0, 1\}^n$ ). Then  $G$  acts on the set of optimum solutions: if  $(X_{u, v})$  is an optimum solution, then also  $(X_{\pi(u), \pi(v)})$  is an optimum solution for any  $\pi \in G$ . Hence, as the set of optimum solutions is convex, by averaging we obtain a  $G$ -invariant optimum solution  $X$ . That is,  $X_{\pi(u), \pi(v)} = X_{u, v}$  for all  $u, v$  and all  $\pi \in G$ . So  $X_{u, v}$  depends only on the Hamming distance of  $u$  and  $v$ , hence there are in fact at most  $n+1$  variables. Since (in this case) the algebra of  $G$ -invariant matrices is commutative, it implies that there is a unitary matrix  $U$  such that  $U^* X U$  is a diagonal matrix for each  $G$ -invariant  $X$ . It reduces the semidefinite constraints of order  $2^n$  to  $2^n$  linear constraints, namely the nonnegativity of the diagonal elements. As the space of  $G$ -invariant matrices is  $n+1$ -dimensional, there are in fact only  $n+1$  different linear constraints, hence it reduces to a small linear programming problem.

So the Delsarte bound is initially a huge semidefinite program in variables associated with pairs and singletons of words in  $\{0, 1\}^n$ , that can be reduced to a small linear program, with a small number of variables. In [21] this method was generalized to semidefinite programs in variables associated with sets of words of size at most 3. In that case, the programs can be reduced by block diagonalization to a small semidefinite program, with a small number of variables. A reduction to a *linear* program does not work here, as in this case the corresponding algebra is not commutative. This however is not a real bottleneck, as like for linear programming there are efficient ('interior-point') algorithms for semidefinite programming — see [9].<sup>5</sup>

In the present paper we extend this method to quadruples of words. Again, by a block diagonalization, the order of the size of the semidefinite programs is reduced from exponential size to polynomial size. We will give a more precise description of the method in Section 2.

The reduced semidefinite programs still tend to get rather large, but yet for  $n$  up to 28 and several values of  $d$ , we were able to solve the associated semidefinite programming up to (more than) enough precision, using the semidefinite programming algorithm SDPA (SemiDefinite Programming Algorithm [7], cf. [19]). It gives the new upper bounds  $A_4(n, d)$  for  $A(n, d)$  displayed in Table 1. In the table we give also the values of the new bound where it does not improve the currently best known bound, as in many of such cases the new bound confirms or is very close to this best known bound.

<sup>5</sup>In fact, a semidefinite programming problem can be solved up to precision  $\varepsilon > 0$  in time bounded by a polynomial in the input size (including number of bits to describe numbers), in  $\log(1/\varepsilon)$ , and in the minimum value of  $r$  for which the feasible region contains a ball of radius  $2^{-r}$  and is contained in a ball of radius  $2^r$  around the origin (see [9] Section 1.9). For the problem class considered in this paper, the input size and  $r$  can be seen to be bounded by a polynomial in  $n$ .

<sup>1</sup> CWI and Department of Mathematics, Leiden University

<sup>2</sup> School of Mathematical and Statistical Sciences, Arizona State University

<sup>3</sup> CWI and Department of Mathematics, University of Amsterdam. Mailing address: CWI, Science Park 123, 1098 XG Amsterdam, The Netherlands. Email: lex@cwi.nl.

<sup>4</sup> For any finite set  $Z$ , a  $Z \times Z$  matrix is any function  $M : Z \times Z \rightarrow \mathbb{C}$ . The value  $M(u, v)$  is denoted by  $M_{u, v}$ . If  $M$  and  $N$  are  $Z \times Z$  matrices, its product  $MN$  is the  $Z \times Z$  matrix with  $(MN)_{x, z} := \sum_{y \in Z} M_{x, y} N_{y, z}$  for  $x, z \in Z$ .

Since  $A(n, d) = A(n+1, d+1)$  if  $d$  is odd, we can restrict ourselves to  $d$  even. We refer to the websites maintained by Erik Agrell [1] and Andries Brouwer [2] for more background on the known upper and lower bounds displayed in the table.

One exact value follows, namely  $A(20, 8) = 256$ . It means that the quadruply shortened Golay code is optimum. Studying the optimum solution of the semidefinite program and its dual optimum solution might give uniqueness of the optimum code for  $n = 20, d = 8$ , but we did not elaborate on this.

$n$	$d$	known lower bound	known upper bound	new upper bound	$A_4(n, d)$
17	4	2720	3276		3276.800
18	4	5312	6552		6553.600
19	4	10496	13104		13107.200
20	4	20480	26168		26214.400
21	4	36864	43688		43690.667
17	6	256	340		351.506
18	6	512	680	673	673.005
19	6	1024	1280	1237	1237.939
20	6	2048	2372	2279	2279.758
21	6	2560	4096		4096.000
22	6	4096	6941		6943.696
23	6	8192	13766	13674	13674.962
17	8	36	36		38.192
18	8	64	72		72.998
19	8	128	142	135	135.710
20	8	256	274	256	256.000
25	8	4096	5477	5421	5421.499
26	8	4096	9672	9275	9275.544
27	8	8192	17768	17099	17099.64
21	10	42	48	47	47.007
22	10	64	87	84	84.421
23	10	80	150		151.324
24	10	128	280	268	268.812
25	10	192	503	466	466.809
26	10	384	886	836	836.669
27	10	512	1764	1585	1585.071
28	10	1024	3170	2817	2817.313
25	12	52	56	55	55.595
26	12	64	98	96	96.892
27	12	128	169		170.667
28	12	178	288		288.001

Table 1. Bounds for  $A(n, d)$

In the computations, the accuracy of the standard double precision version of SDPA (considered in the comparison [17]) was insufficient for several of the cases solved here. The semidefinite programs generated appear to have rather thin feasible regions so that SDPA and the other high-quality but double precision codes terminate prematurely with large infeasibilities. We have used the multiple precision versions of SDPA developed by M. Nakata for quantum chemistry computations in [18]. The times needed in Table 1 varied from a few hours for the small cases to  $1\frac{1}{2}$  days for  $A_4(20, 4)$ , 13 days for  $A_4(23, 6)$ , 22 days for  $A_4(25, 8)$ , 30 days for  $A_4(27, 10)$ , 43 days for  $A_4(26, 8)$ , and four months for  $A_4(28, 10)$ . (Compare this to the cases  $k = 2$  (the Delsarte bound) and  $k = 3$  (cf. [21]), where the corresponding running time are in the order of fractions of seconds and of minutes, respectively.)

The approach outlined above of course suggests a hierarchy of upper bounds by considering sets of words of size at most  $k$ , for  $k = 2, 3, 4, \dots$ . This connects to hierarchies of

bounds for 0, 1 programming problems developed by Lasserre [11], Laurent [12], Lovász and Schrijver [14], and Sherali and Adams [23]. The novelty of the present paper lies in exploiting the symmetry and giving an explicit block diagonalization that will enable us to calculate the bounds.

In fact, the relevance of the present paper might be three-fold. First, it may lie in coding and design theory, as we give new upper bounds for codes and show that the quadruply shortened Golay code is optimal. Second, the results may be of interest for algebraic combinatorics (representations of the symmetric group and extensions), as we give an explicit block diagonalization of the centralizer algebra of groups acting on pairs of words from  $\{0, 1\}^n$ . Third, the relevance may come from semidefinite programming theory and practice, by exploiting symmetry and reducing sizes of programs, and by gaining insight into the border of what is possible with current-state semidefinite programming software, both as to problem size, precision, and computing time.

We do not give explicitly all formulas in our description of the method, as they are sometimes quite involved, rather it may serve as a manual to obtain an explicit implementation, which should be straightforward to derive.

## 2. THE BOUND $A_k(n, d)$

For any  $n, d, k \in \mathbb{Z}_+$ , we define the number  $A_k(n, d)$  as follows. Let  $\mathcal{C}$  be the collection of codes  $S \subseteq \{0, 1\}^n$  of minimum distance at least  $d$ . For any  $k$ , let  $\mathcal{C}_k$  be the collection of  $S \in \mathcal{C}$  with  $|S| \leq k$ .

For  $S \in \mathcal{C}_k$ , define

$$(2) \quad \mathcal{C}(S) := \{S' \in \mathcal{C} \mid S \subseteq S', |S| + 2|S' \setminus S| \leq k\}.$$

The rationale of this definition is that  $|S' \cup S''| \leq k$  for all  $S', S'' \in \mathcal{C}(S)$ .

For  $x : \mathcal{C}_k \rightarrow \mathbb{R}$  and  $S \in \mathcal{C}_k$ , let  $M_S(x)$  be the  $\mathcal{C}(S) \times \mathcal{C}(S)$  matrix given by

$$(3) \quad M_S(x)_{S', S''} := \begin{cases} x(S' \cup S'') & \text{if } S' \cup S'' \in \mathcal{C}, \\ 0 & \text{otherwise,} \end{cases}$$

for  $S', S'' \in \mathcal{C}(S)$ . Define

$$(4) \quad A_k(n, d) := \max \left\{ \sum_{v \in \{0, 1\}^n} x(\{v\}) \mid x : \mathcal{C}_k \rightarrow \mathbb{R}, x(\emptyset) = 1, M_S(x) \text{ positive semidefinite for each } S \in \mathcal{C}_k \right\}.$$

Note that, as  $x(S)$  occurs on the diagonal of  $M_S(x)$ ,  $x$  has nonnegative values only.

**Proposition 1.**  $A(n, d) \leq A_k(n, d)$ .

**Proof.** Let  $C$  be a maximum-size code of length  $n$  and minimum distance at least  $d$ . Define  $x(S) := 1$  if  $S \subseteq C$  and  $x(S) := 0$  otherwise. Then  $M_S(x)$  is positive semidefinite for each  $S \in \mathcal{C}_k$ , as for this  $x$  one has  $x(S' \cup S'') = x(S')x(S'')$  for  $S', S'' \in \mathcal{C}(S)$ . Moreover,

$$(5) \quad A(n, d) = |C| = \sum_{v \in \{0,1\}^n} x(\{v\}). \quad \blacksquare$$

The upper bound  $A_2(n, d)$  can be proved to be equal to the Delsarte bound [4] (see [8]). The bound given in [21] is a slight sharpening of  $A_3(n, d)$ .

Now to make the problem computationally tractable, let again  $G$  denote the isometry group of  $\{0, 1\}^n$  (the group of distance preserving permutations of  $\{0, 1\}^n$ ). Then, if  $x$  is an optimum solution of (4) and  $\pi \in G$ ,  $x^\pi$  is also an optimum solution. (We refer to Section 3.1 for notation.) As the feasible region in (4) is convex, by averaging over all  $\pi \in G$  we obtain a  $G$ -invariant optimum solution. So we can reduce the feasible region to those  $x$  that are  $G$ -invariant. Then  $M_S(x)$  is  $G_S$ -invariant, where  $G_S$  is the  $G$ -stabilizer of  $S$ , i.e.,

$$(6) \quad G_S = \{\pi \in G \mid \pi(S) = S\}.$$

That is, if  $\pi \in G_S$  and  $L_\pi$  denotes the  $\mathcal{C}(S) \times \mathcal{C}(S)$  permutation matrix corresponding to  $S' \mapsto \pi(S')$  for  $S' \in \mathcal{C}(S)$ , then  $L_\pi M_S(x) L_\pi^T = M_S(x)$ . This allows us to block diagonalize  $M_S(x)$ , and to make the problems tractable for larger  $n$ .

In fact, it suffices to check positive semidefiniteness of  $M_S(x)$  for only one  $S$  in each  $G$ -orbit of  $\mathcal{C}_k$ , since for  $\pi \in G$ ,  $M_{\pi(S)}(x)$  arises from  $M_S(x)$  by renaming the row and column indices.

We now fix  $k = 4$  (we will use letter  $k$  for other purposes). If  $|S| = 4$ , then  $|\mathcal{C}(S)| = 1$ , and so  $M_S(x)$  is a  $1 \times 1$  matrix, hence itself forms a full block diagonalization. If  $S$  is odd and  $|S| \leq 3$ , then  $M_S(x)$  is a principal submatrix of  $M_R(x)$ , where  $R$  is any subset of  $S$  with  $|R| = |S| - 1$ . (This because if  $S' \supseteq S$  and  $|S'| + 2|S' \setminus S| \leq 4$ , then  $|R| + 2|S' \setminus R| \leq 4$ .) So we need to consider only those  $S$  with  $|S| = 2$  or  $|S| = 0$ .

In the coming sections we will discuss how to obtain an explicit block diagonalization for  $S$  with  $|S| = 2$  and  $|S| = 0$ . In Section 6 we will discuss how to find a further reduction by considering words of even weights only, which is enough to obtain the bounds.

### 3. PRELIMINARIES

In this section we recall a few basic facts. Underlying mathematical disciplines are representation theory and  $\mathbb{C}$ -\*-algebra, but because the potential readership of this paper might possess diverse background, we give a brief elementary exposition. For more information, we refer to Burrow [3] and Serre [22] for group actions and representation theory and to Davidson [5] for  $\mathbb{C}$ -\*-algebras.

#### 3.1. Group actions

An *action* of a group  $H$  on a set  $Z$  is a group homomorphism from  $H$  into the group of permutations of  $Z$ . One then says that  $H$  *acts on*  $Z$ . An action of  $H$  on  $Z$  induces in a natural way actions of  $H$  on derived sets like  $Z \times Z$ ,  $\mathcal{P}(Z)$ ,  $\{0, 1\}^Z$ , and  $\mathbb{C}^Z$ .

If  $\pi \in H$  and  $z \in Z$ , then  $z^\pi$  denotes the image of  $z$  under the permutation associated with  $\pi$ . If  $H$  acts on  $Z$ , an element

$z \in Z$  is called *H-invariant* if  $z^\pi = z$  for each  $\pi \in H$ . The set of  $H$ -invariant elements of  $Z$  is denoted by  $Z^H$ .

A function  $\phi : Z \rightarrow Z$  is *H-equivariant* if  $\phi(z^\pi) = \phi(z)^\pi$  for each  $z \in Z$  and each  $\pi \in H$ . If  $Z$  is a vector space, the collection of  $H$ -equivariant endomorphisms  $Z \rightarrow Z$  is denoted by  $\text{End}_H(Z)$ . It is called the *centralizer algebra* of the action of  $H$  on  $Z$ .

If  $Z$  is a finite set and  $H$  acts on  $Z$ , then there is a natural isomorphism

$$(7) \quad \text{End}_H(\mathbb{C}^Z) \cong (\mathbb{C}^{Z \times Z})^H.$$

Indeed, there is the classical isomorphism  $\phi : \mathbb{C}^{Z \times Z} \rightarrow \text{End}(\mathbb{C}^Z)$  given by  $\phi(A)(x) = Ax$  for  $A \in \mathbb{C}^{Z \times Z}$  and  $x \in \mathbb{C}^Z$ . Now let  $\pi \in H$ , and let  $L_\pi$  be the permutation matrix in  $\mathbb{C}^{Z \times Z}$  describing the action of  $\pi$  on  $Z$ . So  $L_\pi z = z^\pi$  for  $z \in Z$ . Moreover, since  $L_\pi$  is a permutation matrix,  $L_\pi^T = L_\pi^{-1}$ . Then for any  $A \in \mathbb{C}^{Z \times Z}$  and  $\pi \in H$ :

$$(8) \quad \begin{aligned} A^\pi = A &\iff L_\pi A L_\pi^T = A \iff L_\pi A = \\ &= A L_\pi \iff \forall x \in \mathbb{C}^Z : L_\pi A x = A L_\pi x \iff \\ &\forall x \in \mathbb{C}^Z : (A x)^\pi = A(x^\pi) \iff \forall x \in \mathbb{C}^Z : \\ &(\phi(A)(x))^\pi = \phi(A)(x^\pi). \end{aligned}$$

Hence

$$(9) \quad \begin{aligned} A \in (\mathbb{C}^{Z \times Z})^H &\iff \forall \pi \in H : A^\pi = A \\ &\iff \forall \pi \in H : (\phi(A)(x))^\pi = \phi(A)(x^\pi) \iff \\ &\phi(A) \in \text{End}_H(\mathbb{C}^Z). \end{aligned}$$

This proves (7).

If  $Z$  is a linear space, the symmetric group  $S_n$  acts naturally on the  $n$ -th tensor power  $Z^{\otimes n}$ . As usual, we denote the subspace of symmetric tensors by

$$(10) \quad \text{Sym}^n(Z) := (Z^{\otimes n})^{S_n}.$$

#### 3.2. Matrix \*-algebras

A *matrix \*-algebra* is a set of matrices (all of the same order) that is a  $\mathbb{C}$ -linear space and is closed under multiplication and under taking the conjugate transpose ( $X \mapsto X^*$ ). If a group  $H$  acts on a finite set  $Z$ , then

$$(11) \quad (\mathbb{C}^{Z \times Z})^H \text{ is a matrix *-algebra.}$$

Indeed, a  $Z \times Z$  matrix  $A$  belongs to  $(\mathbb{C}^{Z \times Z})^H$  if and only if  $L_\pi A = A L_\pi$  for each  $\pi \in H$  (where  $L_\pi$  is defined as above). This property is closed under linear combinations, matrix product, and taking the conjugate transpose (as  $L_\pi^* = L_\pi^{-1}$ ).

If  $\mathcal{A}$  and  $\mathcal{B}$  are matrix \*-algebras, a function  $\phi : \mathcal{A} \rightarrow \mathcal{B}$  is an *algebra \*-homomorphism* if  $\phi$  is linear and maintains multiplication and taking the conjugate transpose. It is an *algebra \*-isomorphism* if  $\phi$  is moreover a bijection.

If  $\phi : \mathcal{A} \rightarrow \mathcal{B}$  is an algebra \*-homomorphism and  $A \in \mathcal{A}$  is positive semidefinite, then also  $\phi(A)$  is positive semidefinite. Indeed, if  $p$  is the minimal polynomial of  $A$ , then  $p(\phi(A)) =$

$\phi(p(A)) = 0$ . So each eigenvalue of  $\phi(A)$  is also an eigenvalue of  $A$ , and hence nonnegative.

The sets  $\mathbb{C}^{m \times m}$ , for  $m \in \mathbb{Z}_+$ , are the *full matrix \*-algebras*. An algebra \*-isomorphism  $\mathcal{A} \rightarrow \mathcal{B}$  is called a *full block diagonalization* of  $\mathcal{A}$  if  $\mathcal{B}$  is a direct sum of full matrix \*-algebras.

Each matrix \*-algebra has a full block diagonalization (see [5] Theorem III.1.1) — we need it explicitly in order to perform the calculations for determining  $A_4(n, d)$ . (A full block diagonalization is in fact unique, up to obvious transformations: reordering the terms in the sum, and resetting  $X \mapsto U^*XU$ , for some fixed unitary matrix  $U$ , applied to some full matrix \*-algebra.)

### 3.3. Actions of $S_2$

Let  $Z$  be a finite set on which the symmetric group  $S_2$  acts. This action induces an action of  $S_2$  on  $\mathbb{C}^Z$ . For  $\pm \in \{+, -\}$ , let  $L_\pm := \{x \in \mathbb{R}^Z \mid x^\sigma = \pm x\}$ , where  $\sigma$  is the non-identity element of  $S_2$ . Then  $L_+$  and  $L_-$  are the eigenspaces of  $\sigma$ .

Let  $U_\pm$  be a matrix whose columns form an orthonormal basis of  $L_\pm$ . The matrices  $U_\pm$  are easily obtained from the  $S_2$ -orbits on  $Z$ . Then the matrix  $[U_+ \ U_-]$  is unitary. Moreover,  $U_+^*XU_- = 0$  for each  $X$  in  $(\mathbb{C}^{Z \times Z})^{S_2}$ . As  $L_+$  and  $L_-$  are the eigenspaces of  $\sigma$ , the function  $X \mapsto U_+^*XU_+ \oplus U_-^*XU_-$  defines a full block diagonalization of  $(\mathbb{C}^{Z \times Z})^{S_2}$ .

### 3.4. Fully block diagonalizing $\text{Sym}^n(\mathbb{C}^{2 \times 2})$

We describe a full block diagonalization

$$(12) \quad \xi_n : \text{Sym}^n(\mathbb{C}^{2 \times 2}) \rightarrow \bigoplus_{k=0}^{\lfloor \frac{1}{2}n \rfloor} \mathbb{C}^{[k, n-k] \times [k, n-k]},$$

as can be derived from the work of Dunkl [6] (cf. Vallentin [24], Schrijver [21]).

Here (and further in this paper) we need the following notation. Denote by  $P$  and  $T$  the set of ordered pairs and ordered triples, respectively, from  $\{0, 1\}$ , i.e.,

$$(13) \quad P := \{0, 1\}^2 \text{ and } T := \{0, 1\}^3.$$

As mentioned, we identify elements of  $\{0, 1\}^t$  with  $0, 1$  words of length  $t$ . We will view  $\{0, 1\}$  as the field of two elements and add elements of  $P$  and  $T$  modulo 2.

For any finite set  $V$  and  $n \in \mathbb{Z}_+$ , let

$$(14) \quad \Lambda_V^n := \{\lambda : V \rightarrow \mathbb{Z}_+ \mid \sum_{v \in V} \lambda(v) = n\}.$$

For any  $\lambda \in \Lambda_V^n$ , let

$$(15) \quad \Omega_\lambda := \{\rho : \{1, \dots, n\} \rightarrow V \mid |\rho^{-1}(v)| = \lambda(v) \text{ for each } v \in V\}.$$

Then  $\{\Omega_\lambda \mid \lambda \in \Lambda_V^n\}$  is the collection of orbits on  $V^n$  under the natural action of the symmetric group  $S_n$  on  $V^n$  (cf. Section 3.1).

To describe the block diagonalization of  $\text{Sym}^n(\mathbb{C}^{2 \times 2})$ , let, for any  $\alpha \in \Lambda_P^n$ ,

$$(16) \quad D_\alpha := \sum_{\rho \in \Omega_\alpha} \bigotimes_{i=1}^n E_{\rho(i)} \in \text{Sym}^n(\mathbb{C}^{2 \times 2}).$$

Here, for  $c = (c_1, c_2) \in P$ ,  $E_c$  denotes the  $\{0, 1\} \times \{0, 1\}$  matrix with 1 in position  $c_1, c_2$  and 0 elsewhere. Then  $\{D_\alpha \mid \alpha \in \Lambda_P^n\}$  is a basis of  $\text{Sym}^n(\mathbb{C}^{2 \times 2})$ . (Throughout, we identify  $\mathbb{C}^{2 \times 2}$  with  $\mathbb{C}^{\{0,1\} \times \{0,1\}}$ .) So it suffices to describe the block diagonalization (12) on this basis.

For any  $\alpha \in \Lambda_P^n$  and  $k \in \mathbb{Z}_+$  with  $k \leq \lfloor \frac{n}{2} \rfloor$ , define the following number:

$$(17) \quad \gamma_{\alpha, k} := \binom{n-2k}{i_\alpha - k}^{-1/2} \binom{n-2k}{j_\alpha - k}^{-1/2} \sum_{u=0}^n (-1)^{u-\alpha(11)} \binom{u}{\alpha(11)} \binom{n-2k}{u-k} \binom{n-k-u}{i_\alpha - u} \binom{n-k-u}{j_\alpha - u},$$

where

$$(18) \quad i_\alpha := \alpha(10) + \alpha(11) \text{ and } j_\alpha := \alpha(01) + \alpha(11).$$

Next, define the following  $[k, n-k] \times [k, n-k]$  matrix  $\Gamma_{\alpha, k}$ :

$$(19) \quad (\Gamma_{\alpha, k})_{i, j} := \begin{cases} \gamma_{\alpha, k} & \text{if } i = i_\alpha \text{ and } j = j_\alpha, \\ 0 & \text{otherwise.} \end{cases}$$

for  $i, j \in [k, n-k]$ . Now the full block diagonalization (12) is given by

$$(20) \quad \xi_n : D_\alpha \mapsto \bigoplus_{k=0}^{\lfloor \frac{1}{2}n \rfloor} \Gamma_{\alpha, k}$$

for  $\alpha \in \Lambda_P^n$  — see [21] Theorem 1.

## 4. FULLY BLOCK DIAGONALIZING $M_S(x)$ IF $|S| = 2$

We now go over to describing a full block diagonalization of  $\text{End}_{G_S}(\mathbb{C}^{\mathcal{C}(S)})$ , where  $S$  is a subset of  $\{0, 1\}^n$  with  $|S| = 2$ . As before, we denote the isometry group of  $\{0, 1\}^n$  (the group of distance preserving permutations of  $\{0, 1\}^n$ ) by  $G$ , and the  $G$ -stabilizer of  $S$  by  $G_S$  (cf. (6)).

Note that the  $G$ -orbit of any  $S \in \mathcal{C}$  with  $|S| = 2$  is determined by the distance  $m$  between the two elements of  $S$ . Hence we can assume  $S := \{\mathbf{0}, u\}$ , where  $u$  is the element of  $\{0, 1\}^n$  with precisely  $m$  1's, in positions  $1, \dots, m$ . First let

$$(21) \quad H := \{\pi \in G \mid \pi(\mathbf{0}) = \mathbf{0}, \pi(u) = u\}.$$

So  $H \cong S_m \times S_{n-m}$ . Then there is a one-to-one relation between

$$(22) \quad W := \{v \in \{0, 1\}^n \mid d_H(\mathbf{0}, v) \in [d, n] \text{ and } d_H(u, v) \in \{0\} \cup [d, n]\}$$

and  $\mathcal{C}(S)$ , given by  $v \mapsto S \cup \{v\}$ .

Consider the embedding

$$(23) \quad \Phi : \text{End}_H(\mathbb{C}^{\mathcal{C}(S)}) \rightarrow \text{Sym}^m(\mathbb{C}^{2 \times 2}) \otimes \text{Sym}^{n-m}(\mathbb{C}^{2 \times 2})$$

defined by

$$(24) \quad \Phi(X) := \sum_{v, w \in W} X_{S \cup \{v\}, S \cup \{w\}} \bigotimes_{i=1}^n E_{v_i, w_i}$$

for  $X \in \text{End}_H(\mathbb{C}^{\mathcal{C}(S)})$ , where  $E_{v_i, w_i}$  is the  $\{0, 1\} \times \{0, 1\}$  matrix with a 1 in position  $v_i, w_i$ , and 0 elsewhere.

**Proposition 2.**  $(\xi_m \otimes \xi_{n-m}) \circ \Phi$  gives a full block diagonalization of  $\text{End}_H(\mathbb{C}^{\mathcal{C}(S)})$ .

**Proof.** The image of  $\Phi$  is equal to the linear hull of those  $D_\alpha \otimes D_\beta$  with  $\alpha \in \Lambda_P^m$  and  $\beta \in \Lambda_P^{n-m}$  such that (using notation (18))

$$(25) \quad i_\alpha + i_\beta \in [d, n], j_\alpha + j_\beta \in [d, n], m - i_\alpha + i_\beta \in \{0\} \cup [d, n], m - j_\alpha + j_\beta \in \{0\} \cup [d, n].$$

Composing it with the full block diagonalizations  $\xi_m$  and  $\xi_{n-m}$ , the image is equal to the direct sum over  $k, l$  of the linear hull of the submatrices of  $\Gamma_{\alpha, k} \otimes \Gamma_{\beta, l}$  induced by the rows and columns indexed by  $(i, i')$  with  $i + i' \in [d, n]$  and  $m - i + i' \in \{0\} \cup [d, n]$ .  $\blacksquare$

The stabilizer  $G_S$  contains a further symmetry, namely replacing any  $c \in \{0, 1\}^n$  by  $c + u \pmod{2}$ . This leaves  $S = \{\mathbf{0}, u\}$  invariant. It means an action of  $S_2$  on  $\text{End}_H(\mathbb{C}^{\mathcal{C}(S)})$ , and the corresponding reduction can be obtained with the method of Section 3.3.

## 5. FULLY BLOCK DIAGONALIZING $M_{\emptyset}(x)$

We secondly consider  $S = \emptyset$ . Then  $\mathcal{C}(S) = \mathcal{C}_2$ , which is the set of all codes of length  $n$ , minimum distance at least  $d$ , and size at most 2. Moreover,  $G_S = G$  (the group of distance preserving permutations of  $\{0, 1\}^n$ ). So now we are out for a full block diagonalization of  $\text{End}_G(\mathbb{C}^{\mathcal{C}_2})$ . This will be obtained in a number of steps.

We first consider block diagonalizing  $\text{End}_G(\mathbb{C}^{N^2})$ , where  $N := \{0, 1\}^n$ , so that  $N^2$  is the collection of *ordered* pairs from  $N$ . This is done in Section 5.2, using Section 5.1. The next step, in Section 5.3, is to reduce this block diagonalization to those pairs  $(v, w)$  in  $N^2$  for which  $v$  and  $w$  have distance 0 or at least  $d$ . From this, we derive in Section 5.4 a block diagonalization of  $\text{End}_G(\mathbb{C}^{\mathcal{C}'_2})$ , where  $\mathcal{C}'_2 := \mathcal{C}_2 \setminus \{\emptyset\}$ , the collection of all *unordered* pairs  $\{v, w\}$  from  $N$  where  $v$  and  $w$  have distance 0 or at least  $d$ . Finally, in Section 5.5 we consider the effect of extending  $\mathcal{C}'_2$  to  $\mathcal{C}_2$ , that is, adding  $\emptyset$ .

### 5.1. The algebra $\mathcal{A}$

We first consider an algebra  $\mathcal{A}$  consisting of (essentially)  $4 \times 4$  matrices. For any  $c \in P = \{0, 1\}^2$ , let  $\bar{c} := c + (1, 1) \pmod{2}$ . Let  $\mathcal{A}$  be the centralizer algebra of the action of  $S_2$  on  $P$  generated by  $c \mapsto \bar{c}$  on  $c \in P$ . We can find a full block diagonalization with the method of Section 3.3. We need it explicitly. Note that

$$(26) \quad \mathcal{A} = \{A \in \mathbb{C}^{P \times P} \mid A_{\bar{c}, \bar{d}} = A_{c, d} \text{ for all } c, d \in P\}$$

and that  $\mathcal{A}$  is a matrix  $*$ -algebra of dimension 8.

For  $c, d \in P$ , let  $E_{c, d}$  be the  $P \times P$  matrix with precisely one 1, in position  $(c, d)$ . Define for  $t \in T$ :

$$(27) \quad B_t := E_{c, d} + E_{\bar{c}, \bar{d}},$$

where  $(c, d)$  is any of the two pairs in  $P^2$  satisfying

$$(28) \quad c_1 + c_2 = t_1, d_1 + d_2 = t_2, c_2 + d_2 = t_3,$$

writing  $c = (c_1, c_2)$ ,  $d = (d_1, d_2)$ , and  $t = (t_1, t_2, t_3)$ . (Note that  $(c, d)$  is unique up to exchanging it with  $(\bar{c}, \bar{d})$ .) Then  $\{B_t \mid t \in T\}$  is a basis of  $\mathcal{A}$ .

For  $i \in \{0, 1\}$ , let  $U_i \in \mathbb{C}^{P \times \{0, 1\}}$  be defined by

$$(29) \quad (U_i)_{c, a} = \frac{1}{2} \sqrt{2} (-1)^{ic_2} \delta_{a, c_1 + c_2}$$

for  $c \in P$  and  $a \in \{0, 1\}$ .

**Proposition 3.**  $A \mapsto U^* A U$  is a full block diagonalization of  $\mathcal{A}$ .

**Proof.** One directly checks that the matrix  $U := [U_0 \ U_1]$  is unitary, i.e.,  $U^* U = I$ . Moreover, for all  $c, d \in P$  and  $a, b, i, j \in \{0, 1\}$  we have

$$(30) \quad (U_i^* E_{c, d} U_j)_{a, b} = (U_i)_{c, a} (U_j)_{d, b} = \frac{1}{2} (-1)^{ic_2 + jd_2} \delta_{a, c_1 + c_2} \delta_{b, d_1 + d_2}.$$

Hence, if  $t \in T$  and  $c, d$  satisfy (28), then

$$(31) \quad (U_i^* B_t U_j)_{a, b} = \frac{1}{2} ((-1)^{ic_2 + jd_2} + (-1)^{ic_2 + jd_2 + i + j}) \delta_{a, c_1 + c_2} \delta_{b, d_1 + d_2} = \frac{1}{2} (-1)^{ic_2 + jd_2} (1 + (-1)^{i + j}) \delta_{a, c_1 + c_2} \delta_{b, d_1 + d_2} = (-1)^{it_3} \delta_{i, j} \delta_{a, t_1} \delta_{b, t_2}.$$

So  $U_0^* \mathcal{A} U_1 = 0$ , and hence, as  $\dim \mathcal{A} = 8$ ,  $U^* \mathcal{A} U$  gives a full block diagonalization of  $\mathcal{A}$ .  $\blacksquare$

Note that moreover for  $i = 0, 1$  and  $t \in T$ :

$$(32) \quad U_i^* B_t U_i = (-1)^{it_3} E_{t_1, t_2}.$$

### 5.2. The algebra $\text{Sym}^n(\mathcal{A})$

It is convenient to denote  $N := \{0, 1\}^n$ . Our next step is to find a full block diagonalization of  $\text{End}_G(\mathbb{C}^{N^2})$ , where  $N^2$  is

(as usual) the collection of ordered pairs from  $N$ .

For this purpose, we will view  $\text{End}_G(\mathbb{C}^{N^2})$  as  $\text{Sym}^n(\mathcal{A})$  by using the algebra isomorphism

$$(33) \quad \text{End}_G(\mathbb{C}^{N^2}) \rightarrow \text{Sym}^n(\mathcal{A}),$$

based on the natural isomorphisms

$$(34) \quad \mathbb{C}^{\{0,1\}^n} \cong \mathbb{C}^{\{0,1\}^2} \otimes \mathbb{C}^{\{0,1\}^{n-2}} \cong (\mathbb{C}^{\{0,1\}^2})^{\otimes n},$$

using the fact that  $G$  consists of all permutations of  $\{0,1\}^n$  given by a permutation of the indices in  $\{1, \dots, n\}$  followed by swapping 0 and 1 on a subset of it.

Let  $U_0$  and  $U_1$  be the  $\{0,1\}^2 \times \{0,1\}^{n-2}$  matrices given in Section 5.1. Define

$$(35) \quad \phi : \text{Sym}^n(\mathcal{A}) \rightarrow \bigoplus_{m=0}^n \text{Sym}^m(\mathbb{C}^{\{0,1\} \times \{0,1\}}) \otimes \text{Sym}^{n-m}(\mathbb{C}^{\{0,1\} \times \{0,1\}})$$

by

$$(36) \quad \phi(A) := \bigoplus_{m=0}^n (U_0^{\otimes m} \otimes U_1^{\otimes n-m})^* A (U_0^{\otimes m} \otimes U_1^{\otimes n-m})$$

for  $A \in \text{Sym}^n(\mathcal{A})$ .

**Proposition 4.**  $\phi$  is an algebra  $*$ -isomorphism.

**Proof.** Trivially,  $\phi$  is linear. As  $U^*AU = U_0^*AU_0 \oplus U_1^*AU_1$ ,  $\phi$  is a bijection (cf. Lang [10], Chapter XVI, Proposition 8.2). Moreover, it is an algebra  $*$ -isomorphism, since  $U_i^*U_i = I$  for  $i = 0, 1$  and hence  $U_0^{\otimes m} \otimes U_1^{\otimes n-m}$  is unitary.  $\blacksquare$

Since a full block diagonalization of  $\text{Sym}^m(\mathbb{C}^{2 \times 2})$ , expressed in the standard basis of  $\text{Sym}^m(\mathbb{C}^{2 \times 2})$ , is known for any  $m$  (Section 3.4), and since the tensor product of full block diagonalizations is again a full block diagonalization, we readily obtain with  $\phi$  a full block diagonalization of  $\text{Sym}^n(\mathcal{A})$ . To use it in computations, we need to describe it in terms of the standard basis of  $\text{Sym}^n(\mathcal{A})$ . First we express  $\phi$  in terms of the standard bases of  $\text{Sym}^n(\mathcal{A})$  and of  $\text{Sym}^m(\mathbb{C}^{2 \times 2})$  and  $\text{Sym}^{n-m}(\mathbb{C}^{2 \times 2})$ .

Let  $\Lambda_T^n$  and  $\Omega_\lambda$  be as in (14) and (15). For  $\lambda \in \Lambda_T^n$ , define

$$(37) \quad B_\lambda := \sum_{\rho \in \Omega_\lambda} \bigotimes_{i=1}^n B_{\rho(i)}.$$

Then  $\{B_\lambda \mid \lambda \in \Lambda_T^n\}$  is a basis of  $\text{Sym}^n(\mathcal{A})$ .

We need the ‘Krawtchouk polynomial’: for  $n, k, t \in \mathbb{Z}_+$ ,

$$(38) \quad K_k^n(t) := \sum_{i=0}^k (-1)^i \binom{t}{i} \binom{n-t}{k-i}.$$

For later purposes we note here that for all  $n, k, t \in \mathbb{Z}_+$  with  $t \leq n$ :

$$(39) \quad K_{n-k}^n(t) = (-1)^t K_k^n(t).$$

This follows directly from (38), by replacing  $k$  by  $n-k$  and  $i$  by  $t-i$ .

For  $\lambda \in \Lambda_T^n$ ,  $\alpha \in \Lambda_P^m$ ,  $\beta \in \Lambda_P^{n-m}$ , define

$$(40) \quad \vartheta_{\lambda, \alpha, \beta} := \delta_{\lambda', \alpha + \beta} \prod_{c \in P} K_{\lambda(c)}^{\lambda'(c)}(\beta(c)),$$

where for  $\lambda \in \Lambda_T^n$ ,  $\lambda' \in \Lambda_P^n$  is defined by

$$(41) \quad \lambda'(c) := \lambda(c0) + \lambda(c1)$$

for  $c \in P$ . Here  $c0$  ( $c1$  respectively) stand for the triple obtained from concatenating the pair  $c = c_1c_2$  with the bit 0 (1 respectively) at the end.

We now express  $\phi$  in the standard bases (37) and (16).

**Proposition 5.** For any  $\lambda \in \Lambda_T^n$ ,

$$(42) \quad \phi(B_\lambda) = \bigoplus_{m=0}^n \sum_{\alpha \in \Lambda_P^m, \beta \in \Lambda_P^{n-m}} \vartheta_{\lambda, \alpha, \beta} D_\alpha \otimes D_\beta.$$

**Proof.** By (32), the  $m$ -th component of  $\phi(B_\lambda)$  is equal to

$$(43) \quad \sum_{\rho \in \Omega_\lambda} \left( \bigotimes_{i=1}^m E_{\rho_1(i), \rho_2(i)} \right) \otimes \left( \bigotimes_{i=m+1}^n (-1)^{\rho_3(i)} E_{\rho_1(i), \rho_2(i)} \right) = \sum_{\substack{\mu \in \Lambda_P^m, \nu \in \Lambda_P^{n-m} \\ \mu + \nu = \lambda}} \left( \sum_{\sigma \in \Omega_\mu} \bigotimes_{i=1}^m E_{\sigma_1(i), \sigma_2(i)} \right) \otimes \left( \sum_{\tau \in \Omega_\nu} \bigotimes_{i=1}^{n-m} (-1)^{\tau_3(i)} E_{\tau_1(i), \tau_2(i)} \right) = \sum_{\substack{\mu \in \Lambda_P^m, \nu \in \Lambda_P^{n-m} \\ \mu + \nu = \lambda}} \left( \prod_{c \in P} \binom{\mu'(c)}{\mu(c1)} \right) D_{\mu'} \otimes \left( \prod_{c \in P} (-1)^{\nu(c1)} \binom{\nu'(c)}{\nu(c1)} \right) D_{\nu'}.$$

If we sum over  $\alpha := \mu'$  and  $\beta := \nu'$ , we can next, for each  $c \in P$ , sum over  $j$  and set  $\nu(c1) := j$ , and  $\mu(c1) := \lambda(c1) - j$ . In this way we get that the last expression in (43) is equal to

$$(44) \quad \sum_{\substack{\alpha \in \Lambda_P^m, \beta \in \Lambda_P^{n-m} \\ \alpha + \beta = \lambda'}} \left( \prod_{c \in P} \sum_{j=0}^{\lambda(c1)} (-1)^j \binom{\alpha(c)}{\lambda(c1)-j} \binom{\beta(c)}{j} \right) D_\alpha \otimes$$

$$D_\beta = \sum_{\alpha \in \Lambda_P^m, \beta \in \Lambda_P^{n-m}} \vartheta_{\lambda, \alpha, \beta} D_\alpha \otimes D_\beta. \quad \blacksquare$$

This describes the algebra isomorphism  $\phi$  in (35) in terms of the basis  $\{B_\lambda \mid \lambda \in \Lambda_T^n\}$ . With the block diagonalization of  $\text{Sym}^n(\mathbb{C}^{2 \times 2})$  given in Section 3.4 it implies a full block diagonalization

$$(45) \quad \psi : \text{Sym}^n(\mathcal{A}) \rightarrow \bigoplus_{m=0}^n \bigoplus_{k=0}^{\lfloor \frac{1}{2}m \rfloor} \bigoplus_{l=0}^{\lfloor \frac{1}{2}(n-m) \rfloor} \mathbb{C}^{[k, m-k] \times [k, m-k]} \otimes \mathbb{C}^{[l, n-m-l] \times [l, n-m-l]},$$

described by

$$(46) \quad \psi(B_\lambda) = \bigoplus_{m=0}^n \bigoplus_{k=0}^{\lfloor \frac{1}{2}m \rfloor} \bigoplus_{l=0}^{\lfloor \frac{1}{2}(n-m) \rfloor} \psi_{m, k, l}(B_\lambda)$$

where

$$(47) \quad \psi_{m, k, l}(B_\lambda) := \sum_{\alpha \in \Lambda_P^m, \beta \in \Lambda_P^{n-m}} \vartheta_{\lambda, \alpha, \beta} \Gamma_{\alpha, k} \otimes \Gamma_{\beta, l}$$

for  $\lambda \in \Lambda_T^n$ .

Inserting (17) and (19) in (47) makes the block diagonalization explicit, and it can readily be programmed. Note that  $\alpha, \beta$  in the summation can be restricted to those with  $\alpha + \beta = \lambda'$ . Note also that at most one entry of the matrix  $\Gamma_{\alpha, k} \otimes \Gamma_{\beta, l}$  is nonzero.

### 5.3. Deleting distances

For  $m, k, l$ , we will use the natural isomorphism

$$(48) \quad \mathbb{C}^{([k, m-k] \times [l, n-m-l]) \times ([k, m-k] \times [l, n-m-l])} \cong \mathbb{C}^{[k, m-k] \times [k, m-k]} \otimes \mathbb{C}^{[l, n-m-l] \times [l, n-m-l]}.$$

Then, using notation (18) and (41),

**Proposition 6.** *Let  $D \subseteq [0, n]$ . Then the linear hull of*

$$(49) \quad \{\psi_{m, k, l}(B_\lambda) \mid \lambda \in \Lambda_T^n, i_{\lambda'}, j_{\lambda'} \in D\}$$

*is equal to the subspace  $\mathbb{C}^{F \times F}$  of (48), where*

$$(50) \quad F := \{(i, i') \in [k, m-k] \times [l, n-m-l] \mid i + i' \in D\}.$$

**Proof.** For any  $\lambda \in \Lambda_T^n$ , if  $\psi_{m, k, l}(B_\lambda)_{(i, i'), (j, j')}$  is nonzero, then  $i + i' = i_{\lambda'}$  and  $j + j' = j_{\lambda'}$ . This follows from (46) and from the definition of the matrices  $\Gamma_{\alpha, k}$  (cf. (19)).

Hence, for any fixed  $a, b \in \mathbb{Z}_+$ , the linear hull of the  $\psi_{m, k, l}(B_\lambda)$  with  $i_{\lambda'} = a$  and  $j_{\lambda'} = b$  is equal to the set of

matrices in (48) that are nonzero only in positions  $(i, i'), (j, j')$  with  $i + i' = a$  and  $j + j' = b$ .  $\blacksquare$

So if distances are restricted to  $D \subseteq [0, n]$ , we can reduce the block diagonalization to those rows and columns with index in  $F$ .

### 5.4. Unordered pairs

We now go over from ordered pairs to unordered pairs. First, let  $\mathcal{C}'_2 := \mathcal{C}_2 \setminus \{\emptyset\}$ , and consider  $\text{End}_G(\mathbb{C}^{\mathcal{C}'_2})$ . Let again  $N := \{0, 1\}^n$ . Let  $\tau$  be the permutation of  $N^2$  swapping  $(c, d)$  and  $(d, c)$  in  $N^2$ . Let  $Q_\tau$  be the corresponding permutation matrix in  $\mathbb{C}^{N^2 \times N^2}$ . Note that  $N^2$  corresponds to the set of row indices of the matrices  $B_\lambda$  (cf. (34)). Then there is a natural isomorphism

$$(51) \quad \text{End}_G(\mathbb{C}^{\mathcal{C}'_2}) \cong \mathcal{R} := \{A \in \text{Sym}^n(\mathcal{A}) \mid Q_\tau A = A = A Q_\tau\}.$$

While  $\psi$  is a full block diagonalization of  $\text{Sym}^n(\mathcal{A})$ , we claim that  $\psi|_{\mathcal{R}}$  is a full block diagonalization of  $\mathcal{R}$ . For this we need, for any  $s, t \in \mathbb{Z}$ ,

$$(52) \quad [s, t]_{\text{even}} := \{u \in [s, t] \mid u \text{ even}\}.$$

**Proposition 7.** *The image of  $\psi_{m, k, l}$  of  $\mathcal{R}$  is equal to*

$$(53) \quad \mathbb{C}^{[k, m-k] \times [k, m-k]} \otimes \mathbb{C}^{[l, n-m-l]_{\text{even}} \times [l, n-m-l]_{\text{even}}}.$$

**Proof.** For any  $\lambda \in \Lambda_T^n$ , let  $\tilde{\lambda} \in \Lambda_T^n$  be given by  $\tilde{\lambda}(t_1, t_2, t_3) := \lambda(t_1, t_2, t_3 + t_1)$  for  $t \in T$ . So for any  $c \in P$ ,  $\tilde{\lambda}(c1) = \lambda(c1)$  if  $c_1 = 0$  and  $\tilde{\lambda}(c1) = \lambda'(c) - \lambda(c1)$  if  $c_1 = 1$ . Hence  $B_{\tilde{\lambda}} = Q_\tau B_\lambda$ .

So an element of  $A \in \mathcal{A}$  satisfies  $Q_\tau A = A$  if and only if  $A$  belongs to the linear hull of the matrices  $B_\lambda + B_{\tilde{\lambda}}$ .

For any  $m$  and  $\alpha \in \Lambda_P^m, \beta \in \Lambda_P^{n-m}$  one has by (39)

$$(54) \quad \vartheta_{\tilde{\lambda}, \alpha, \beta} = (-1)^{i\beta} \vartheta_{\lambda, \alpha, \beta}.$$

This implies that the matrix  $\psi_{m, k, l}(B_\lambda + B_{\tilde{\lambda}})$  has only 0's in rows whose index  $(i, i')$  has  $i'$  odd. Similarly, the matrix  $\psi_{m, k, l}(B_\lambda - B_{\tilde{\lambda}})$  has only 0's in rows whose index  $(i, i')$  has  $i'$  even. So the space of matrices invariant under permuting the rows by  $\tau$  corresponds under  $\psi_{m, k, l}$  to those matrices that have 0's in rows whose index  $(i, i')$  has  $i'$  odd.

A similar argument holds for permuting columns by  $\tau$ .  $\blacksquare$

### 5.5. Adding $\emptyset$

So far we have a full block decomposition of  $\text{End}_G(\mathbb{C}^{\mathcal{C}'_2})$ , where  $\mathcal{C}'_2 = \mathcal{C}_2 \setminus \{\emptyset\}$ . We need to incorporate  $\emptyset$  in it. It is a basic fact from representation theory that if  $V_1, \dots, V_t$  is the canonical decomposition of  $\mathbb{C}^{\mathcal{C}'_2}$  into isotypic components (cf. Serre [22]), then  $\text{End}_G(\mathbb{C}^{\mathcal{C}'_2}) = \bigoplus_{i=1}^t \text{End}_G(V_i)$ , and each  $\text{End}_G(V_i)$  is  $*$ -isomorphic to a full matrix algebra.

We can assume that  $V_1$  is the set of  $G$ -invariant elements of  $\mathbb{C}^{\mathcal{C}'_2}$ . Hence, as  $\emptyset$  is  $G$ -invariant,  $V'_1 := \mathbb{C}^\emptyset \oplus V_1$  is the set of  $G$ -invariant elements of  $\mathbb{C}^{\mathcal{C}_2}$ . One may check that the block indexed by  $(m, k, l) = (n, 0, 0)$  corresponds to  $V_1$ . So replacing block  $(n, 0, 0)$  by  $\text{End}_G(V'_1)$  gives a full block diagonalization of  $\text{End}_G(\mathbb{C}^{\mathcal{C}_2})$ . Note that  $\text{End}_G(V'_1) = \text{End}(V'_1)$ , as each element of  $V'_1$  is  $G$ -invariant.

We can easily determine a basis for  $V'_1$ , namely the set of characteristic vectors of the  $G$ -orbits of  $\mathcal{C}_2$ . Then for any  $B \in \text{End}_G(\mathbb{C}^{\mathcal{C}_2})$ , we can directly calculate its projection in  $\text{End}(V'_1)$ . This gives the required new component of the full block diagonalization.

## 6. RESTRICTION TO EVEN WORDS

We can obtain a further reduction by restriction to the collection  $E$  of words in  $\{0, 1\}^n$  of even weight. (The *weight* of a word is the number of 1's in it.) By a parity check argument one knows that for even  $d$  the bound  $A(n, d)$  is attained by a code  $C \subseteq E$ . A similar phenomenon applies to  $A_k(n, d)$ :

**Proposition 8.** *For even  $d \geq 2$ , the maximum value in (4) does not change if  $x(S)$  is required to be zero if  $S \not\subseteq E$ .*

**Proof.** Let  $\varepsilon : \{0, 1\}^n \rightarrow E$  be defined by  $\varepsilon(w) = w$  if  $w$  has even weight and  $\varepsilon(w) = w + e_n$  if  $w$  has odd weight. Here  $e_n$  is the  $n$ -th unit basis vector, and addition is modulo 2. If  $d$  is even, then for all  $v, w \in \{0, 1\}^n$ :  $d_H(v, w) \geq d$  if and only if  $d_H(\varepsilon(v), \varepsilon(w)) \geq d$ . Now  $\varepsilon$  induces a projection  $p : \mathbb{R}^{\mathcal{C}} \rightarrow \mathbb{R}^{\mathcal{E}}$ , where  $\mathcal{E}$  is the collection of codes in  $\mathcal{C}$  with all words having even weight.

One easily checks that if  $M_S(x)$  is positive semidefinite for all  $S$ , then  $M_S(p(x))$  is positive semidefinite for all  $S$ . Moreover,

$$(55) \quad \sum_{v \in \{0, 1\}^n} p(x)(\{v\}) = \sum_{v \in \{0, 1\}^n} x(\{v\}). \quad \blacksquare$$

This implies that restricting  $x$  to be nonzero only on subsets  $S$  of  $E$  does not change the value of the upper bound. However, it gives a computational reduction. This can be obtained by using Proposition 6 and by observing that the restriction amounts to an invariance under an action of  $S_2$ , for which we can use Section 3.3. The latter essentially implies that in (53) we can restrict the left hand side factor to rows and columns with index in  $[k, m - k]_{\text{even}}$ . As it means a reduction of the program size by only a linear factor, we leave the details to the reader.

## 7. SOME FURTHER NOTES

It is of interest to remark that the equality  $A(20, 8) = 256$  in fact follows if we take  $k = 4$  and require in (4) only that  $M_S(x)$  is positive semidefinite for all  $S$  with  $|S| = 0$  or  $|S| = 4$ .

An observation useful to note (but not used in this paper) is the following. A well-known relation is  $A(n + 1, d) \leq$

$2A(n, d)$ . The same relation holds for  $A_k(n, d)$ :

**Proposition 9.** *For all  $n, d$ :  $A_k(n + 1, d) \leq 2A_k(n, d)$ .*

**Proof.** Let  $x$  attain the maximum (4) for  $A_k(n + 1, d)$ . For each  $S \subseteq \{0, 1\}^n$ , let  $S' := \{w0 \mid w \in S\}$  and  $S'' := \{w1 \mid w \in S\}$ . Define  $x'(S) := x(S')$  and  $x''(S) := x(S'')$  for all  $S \in \mathcal{C}$ . Then  $x'$  and  $x''$  are feasible solutions of (4) for  $A_k(n, d)$ . Moreover  $\sum_{v \in \{0, 1\}^n} (x'(\{v\}) + x''(\{v\})) = \sum_{w \in \{0, 1\}^{n+1}} x(\{w\})$ . Thus  $2A_k(n, d) \geq A_k(n + 1, d)$ .  $\blacksquare$

This implies, using  $A_4(20, 8) = 256$  and  $A(24, 8) \geq 4096$  (the extended Golay code), that  $A_4(21, 8) = 512$ ,  $A_4(22, 8) = 1024$ ,  $A_4(23, 8) = 2048$ , and  $A_4(24, 8) = 4096$ . We did not display these values in the table, and we do not need to solve the corresponding semidefinite programming problems.

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#### *Biographical sketches.*

**Dion Gijswijt** studied mathematics at the University of Amsterdam, Amsterdam, The Netherlands. He received his MSc. degree in 2001, and he received his PhD. in 2005 with a dissertation on "Matrix algebras and semidefinite programming techniques for codes".

From 2005 to 2011, he held postdoc positions at Eötvös University, Budapest, Hungary; at University of Amsterdam, Amsterdam, The Netherlands; at CWI, Amsterdam, The Netherlands and at Leiden University, Leiden, The Netherlands.

Currently, he is an assistant professor at TU Delft, Delft, The Netherlands, and holds a research position at CWI, Amsterdam, The Netherlands. He is active in the field of combinatorial optimization, with research interests including (quantum) information theory, graph- and matroid optimization and semidefinite programming.

**Hans D. Mittelmann** received his M.S. degree in Mathematics from the University of Mainz (Germany) in 1971 and his PhD from the Technical University in Darmstadt (Germany) in 1973. In 1976 he finished the habilitation for mathematics at this university and in 1977 accepted a position as associate professor with tenure at the University of Dortmund (Germany). At that time his research was in the numerical solution of partial differential equations and the finite element method.

Dr. Mittelmann spent a Sabbatical in 1981 at the Computer Science Department of Stanford University and in 1982 accepted a full professorship at Arizona State University. He held visiting positions at several universities including the universities of Erlangen, Heidelberg, and Leipzig in Germany, the University of Jyväskylä in Finland, the King Fahd University of Petroleum and Minerals in Saudi Arabia, and the Tokyo Institute of Technology. Recently his research is in computational optimization and its applications.

**Alexander Schrijver** received his Ph.D. in mathematics in

1977 from the Free University in Amsterdam. After positions at the Universities of Amsterdam and Tilburg, he is since 1989 a researcher at CWI (Center of Mathematics and Computer Science) in Amsterdam and professor of mathematics at the University of Amsterdam. He has held visiting positions at Oxford, Szeged, Bonn, Paris, Rutgers and Yale universities and was a Consultant at Bell Communications Research and at Microsoft Research.

He is editor-in-chief of *Combinatorica* and on the editorial board of seven other journals. He received twice the Fulkerson Prize from the American Mathematical Society and the Mathematical Programming Society, twice the Lanchester Prize from the Operations Research Society of America, the Dantzig Prize from the Society for Industrial and Applied Mathematics, the Von Neumann Theory Award and the Edelman Award from the Institute for Operations Research and Management Science, the Spinoza Prize from the Netherlands Organization for Scientific Research (NWO), and honorary doctorates in mathematics from the Universities of Waterloo (Ontario) and Budapest. He is a member of the Royal Netherlands Academy of Arts and Sciences, of the Nordrhein-Westfälische Akademie der Wissenschaften, of the Nationale Akademie der Wissenschaften Leopoldina, and of the Academia Europaea, and was knighted in the Order of the Dutch Lion by the Queen of The Netherlands.