

Diving for Conflicts in Mixed-Integer Programming

Ambros Gleixner and Jakob Witzig

Zuse Institute Berlin · gleixner@zib.de
SCIP Optimization Suite · <http://scip.zib.de>

Discrepancy Theory & Integer Programming

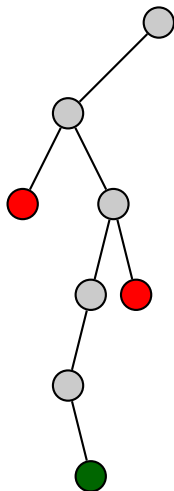
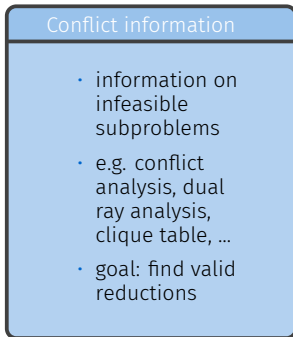
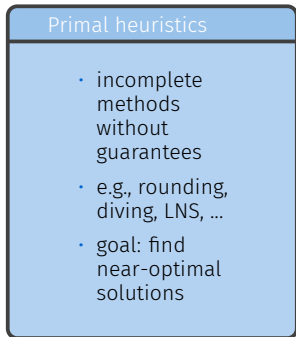
CWI · Amsterdam · June 14, 2018



SPONSORED BY THE

Federal Ministry
of Education
and Research

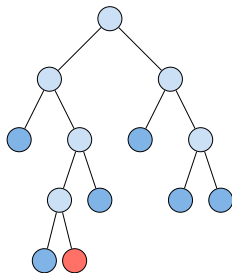
Question



Introduction: Conflict Analysis

Goal: When branch-and-bound reaches an infeasible subproblem, analyze the infeasibility to

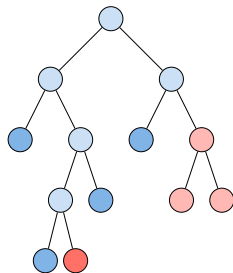
- extract a shorter reason



Introduction: Conflict Analysis

Goal: When branch-and-bound reaches an infeasible subproblem, analyze the infeasibility to

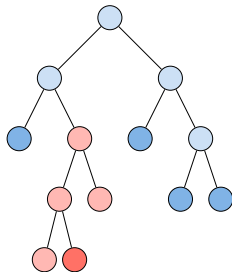
- extract a shorter reason
- that prunes other parts of the tree



Introduction: Conflict Analysis

Goal: When branch-and-bound reaches an infeasible subproblem, analyze the infeasibility to

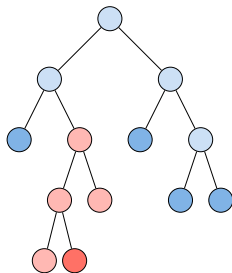
- extract a shorter reason
- that prunes other parts of the tree
- also in backtracking



Introduction: Conflict Analysis

Goal: When branch-and-bound reaches an infeasible subproblem, analyze the infeasibility to

- extract a shorter reason
- that prunes other parts of the tree
- also in backtracking



Example: contradicting bound changes after propagation

$$x_1 + x_2 + 2x_3 \leq 2 \quad (1)$$

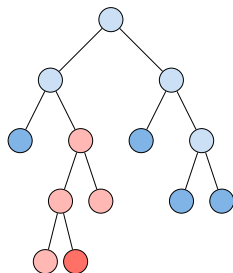
$$x_1 + x_2 - 2x_3 \leq 0 \quad (2)$$

$$x_1, x_2, x_3 \in \{0, 1\}$$

Introduction: Conflict Analysis

Goal: When branch-and-bound reaches an infeasible subproblem, analyze the infeasibility to

- extract a shorter reason
- that prunes other parts of the tree
- also in backtracking



Example: contradicting bound changes after propagation

$$x_1 + x_2 + 2x_3 \leq 2 \quad (1)$$

$$x_1 + x_2 - 2x_3 \leq 0 \quad (2)$$

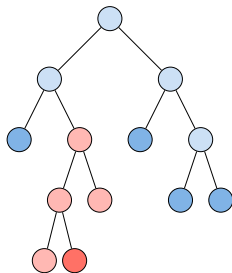
$$x_1, x_2, x_3 \in \{0, 1\}$$

$$(x_2 \geq 1) \stackrel{(1)}{\implies} (x_3 \leq 0)$$

Introduction: Conflict Analysis

Goal: When branch-and-bound reaches an infeasible subproblem, analyze the infeasibility to

- extract a shorter reason
- that prunes other parts of the tree
- also in backtracking



Example: contradicting bound changes after propagation

$$x_1 + x_2 + 2x_3 \leq 2 \quad (1)$$

$$x_1 + x_2 - 2x_3 \leq 0 \quad (2)$$

$$x_1, x_2, x_3 \in \{0, 1\}$$

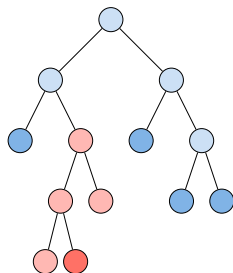
$$(x_2 \geq 1) \stackrel{(1)}{\implies} (x_3 \leq 0)$$

$$\implies (2) \text{ is violated}$$

Introduction: Conflict Analysis

Goal: When branch-and-bound reaches an infeasible subproblem, analyze the infeasibility to

- extract a shorter reason
- that prunes other parts of the tree
- also in backtracking



Example: contradicting bound changes after propagation

$$x_1 + \leq 2 \quad (1)$$

$$x_1 + \leq 0 \quad (2)$$

$$x_1, x_2, x_3 \in \{0, 1\}$$

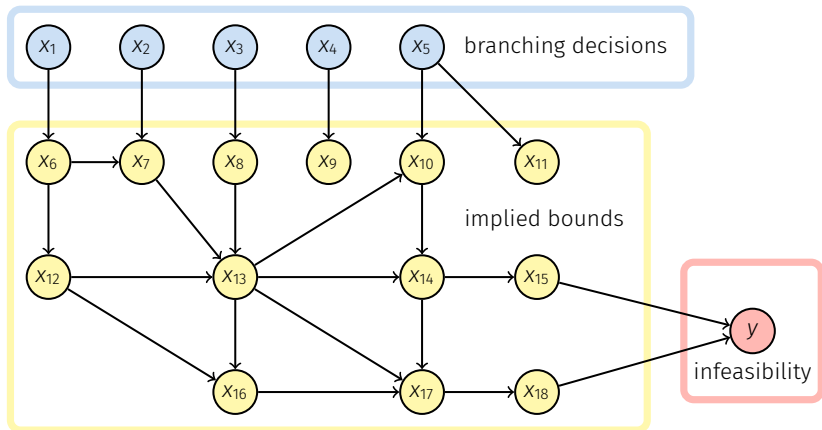
$$(x_2 \geq 1) \stackrel{(1)}{\implies} (x_3 \leq 0)$$

\implies (2) is violated

$\rightsquigarrow x_2 \geq 1$ is a sufficient reason

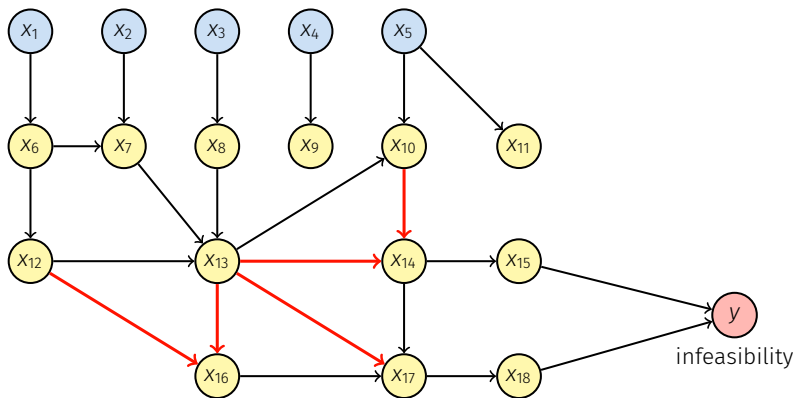
Conflict Graph Analysis

- Goes back to Marques-Silva and Sakallah (1999)
- Idea: consider implications that led to the local bounds



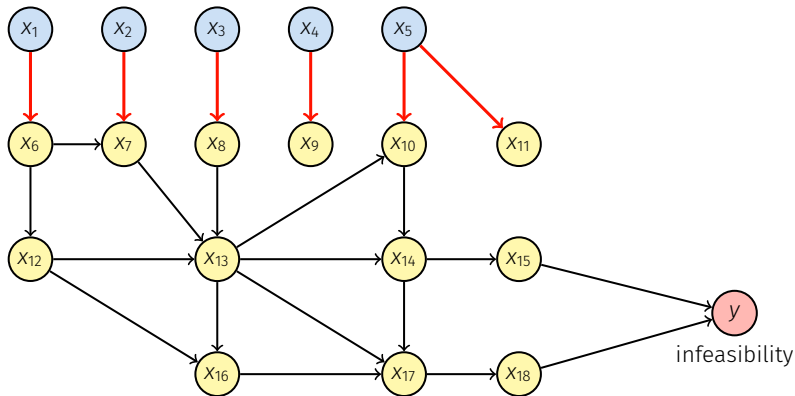
Conflict Graph Analysis

- Goes back to Marques-Silva and Sakallah (1999)
- Idea: consider implications that led to the local bounds
- Each cut that separates branching nodes from y yields a conflict constraint



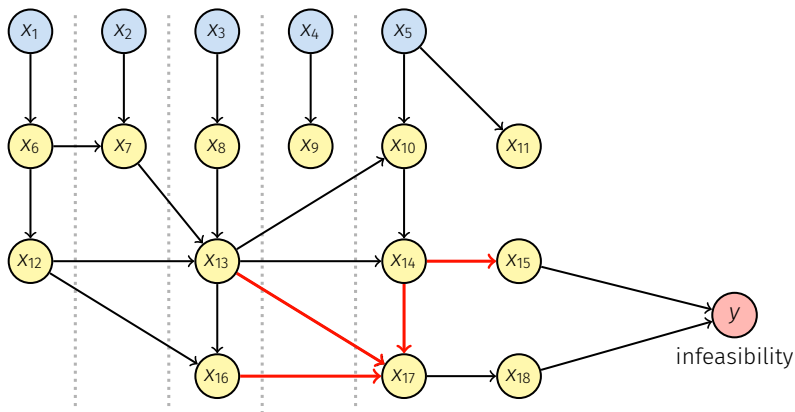
Conflict Graph Analysis

- Goes back to Marques-Silva and Sakallah (1999)
- Idea: consider implications that led to the local bounds
- Separating only branching nodes \Rightarrow no-good cut



Conflict Graph Analysis

- Goes back to Marques-Silva and Sakallah (1999)
- Idea: consider implications that led to the local bounds
- better: First Unique Implication Point (FUIP), ...



LP Infeasibility

- Assume a subproblem with bounds $\ell \leq \ell' \leq u' \leq u$

$$\min\{c^T x \mid Ax \geq b, \ell' \leq x \leq u', x_i \in \mathbb{Z} \forall i \in \mathcal{I}\} \quad (3)$$

LP Infeasibility

- Assume a subproblem with bounds $\ell \leq \ell' \leq u' \leq u$

$$\min\{c^T x \mid Ax \geq b, \ell' \leq x \leq u', x_i \in \mathbb{Z} \forall i \in \mathcal{I}\} \quad (3)$$

- LP of (3) infeasible \iff unbounded direction in the dual

$$\max\{y^T b + r^T \{\ell', u'\} \mid y^T A + r^T = c^T, y \in \mathbb{R}_+^m, r \in \mathbb{R}^n\} \quad (4)$$

- i.e. a ray (y, s)

$$\begin{aligned} y^t A + s^t &= 0 \\ y^t b + s^t \{\ell', u'\} &> 0 \end{aligned}$$

LP Infeasibility

- Assume a subproblem with bounds $\ell \leq \ell' \leq u' \leq u$

$$\min\{c^T x \mid Ax \geq b, \ell' \leq x \leq u', x_i \in \mathbb{Z} \forall i \in \mathcal{I}\} \quad (3)$$

- LP of (3) infeasible \iff unbounded direction in the dual

$$\max\{y^T b + r^T \{\ell', u'\} \mid y^T A + r^T = c^T, y \in \mathbb{R}_+^m, r \in \mathbb{R}^n\} \quad (4)$$

- i.e. a ray (y, s)

$$\begin{aligned} y^t A + s^t &= 0 \\ y^t b + s^t \{\ell', u'\} &> 0 \end{aligned}$$

\Downarrow

$$(y^t A)x \geq y^t b \quad (\text{Farkas constraint})$$

LP Infeasibility

- Assume a subproblem with bounds $\ell \leq \ell' \leq u' \leq u$

$$\min\{c^T x \mid Ax \geq b, \ell' \leq x \leq u', x_i \in \mathbb{Z} \forall i \in \mathcal{I}\} \quad (3)$$

- LP of (3) infeasible \iff unbounded direction in the dual

$$\max\{y^T b + r^T \{\ell', u'\} \mid y^T A + r^T = c^T, y \in \mathbb{R}_+^m, r \in \mathbb{R}^n\} \quad (4)$$

- i.e. a ray (y, s)

$$\begin{aligned} y^t A + s^t &= 0 \\ y^t b + s^t \{\ell', u'\} &> 0 \end{aligned}$$

\Downarrow

$$(y^t A)x \geq y^t b \quad (\text{Farkas constraint})$$

- Farkas constraint globally valid: propagate during tree search
- analogous extension for bound exceeding LPs

Motivation

Starting point of a diving heuristic

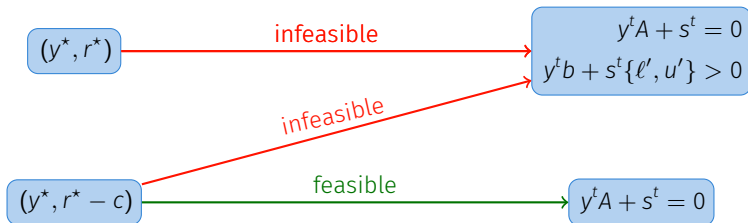
- primal feasible x^* for $\min\{c^t x \mid Ax \geq b, \ell' \leq x \leq u'\}$
- dual feasible (y^*, r^*) for $\max\{y^t b + r\{\ell', u'\} \mid y^t A + r = c\}$



Motivation

Starting point of a diving heuristic

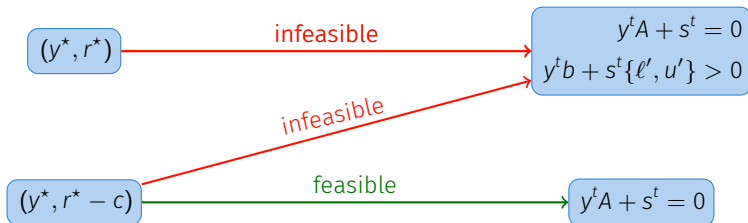
- primal feasible x^* for $\min\{c^t x \mid Ax \geq b, \ell' \leq x \leq u'\}$
- dual feasible (y^*, r^*) for $\max\{y^t b + r\{\ell', u'\} \mid y^t A + r = c\}$



Motivation

Starting point of a diving heuristic

- primal feasible x^* for $\min\{c^t x \mid Ax \geq b, \ell' \leq x \leq u'\}$
- dual feasible (y^*, r^*) for $\max\{y^t b + r\{\ell', u'\} \mid y^t A + r = c\}$



Question: How to satisfy $y^t b + s^t \{\ell', u'\} > 0$?

Motivation

$$(y^*)^t b + (r^* - c)^t \{\ell', u'\} > 0$$

$$\iff (y^*)^t b + \sum_{(r_i^* - c_i) > 0} (r_i^* - c_i) \cdot \ell'_i + \sum_{(r_i^* - c_i) < 0} (r_i^* - c_i) \cdot u'_i > 0$$

Motivation

$$(y^*)^t b + (r^* - c)^t \{\ell', u'\} > 0$$

$$\iff (y^*)^t b + \sum_{(r_i^* - c_i) > 0} (r_i^* - c_i) \cdot \ell'_i + \sum_{(r_i^* - c_i) < 0} (r_i^* - c_i) \cdot u'_i > 0$$

Violation reduced by

increasing ℓ'_i if $r_i^* - c_i > 0$

decreasing u'_i if $r_i^* - c_i < 0$

Motivation

$$(y^*)^t b + (r^* - c)^t \{\ell', u'\} > 0$$

$$\iff (y^*)^t b + \sum_{(r_i^* - c_i) > 0} (r_i^* - c_i) \cdot \ell'_i + \sum_{(r_i^* - c_i) < 0} (r_i^* - c_i) \cdot u'_i > 0$$

Violation reduced by

increasing ℓ'_i if $r_i^* - c_i > 0$

decreasing u'_i if $r_i^* - c_i < 0$

Observation

1. Each fractional candidate i with $x_i^* \notin \mathbb{Z}$ is basic.
 2. Basic variables have reduced cost $r_i^* = 0$.
- ↪ Dive optimistically: towards best bound / pseudo solution.

Motivation

$$(y^*)^t b + (r^* - c)^t \{\ell', u'\} > 0$$

$$\iff (y^*)^t b + \sum_{(r_i^* - c_i) > 0} (r_i^* - c_i) \cdot \ell'_i + \sum_{(r_i^* - c_i) < 0} (r_i^* - c_i) \cdot u'_i > 0$$

Violation reduced by

increasing ℓ'_i if $c_i < 0$

decreasing u'_i if $c_i > 0$

Observation

1. Each fractional candidate i with $x_i^* \notin \mathbb{Z}$ is basic.
 2. Basic variables have reduced cost $r_i^* = 0$.
- ↪ Dive optimistically: towards best bound / pseudo solution.

Candidate Selection

Dual view: fd-dual

- Goal: reduce violation of $y^t b + s^t \{\ell', u'\} > 0$
- Choose candidate with maximal $c_i \cdot (\lceil x_i^* \rceil - \ell')$ resp. $c_i \cdot (u'_i - \lfloor x_i^* \rfloor)$

Primal view: fd-primal

- Goal: increase objective function value
- Choose candidate with maximal $c_i \cdot (1 - f_i)$ resp. $c_i \cdot f_i$,
where $f_i := x_i^* - \lfloor x_i^* \rfloor$ is the fractionality in the LP solution x^*

Summary

1. Learning from infeasibility

- classical conflict analysis and LP extensions

2. Farkas diving

- optimistic diving towards best bound relaxation
- “diving for conflicts”

3. Outlook: “conflicts for diving”?

- traditional coefficient diving: dive towards few “variable locks” from model constraints
- conflicts diving: dive towards few “conflict locks” from Farkas constraints

Summary

1. Learning from infeasibility

- classical conflict analysis and LP extensions

2. Farkas diving

- optimistic diving towards best bound relaxation
- “diving for conflicts”

3. Outlook: “conflicts for diving”?

- traditional coefficient diving: dive towards few “variable locks” from model constraints
- conflicts diving: dive towards few “conflict locks” from Farkas constraints

Thank you for your attention!