

# Primal heuristic for MINLPs in SCIP

Ambros Gleixner, and Felipe Serrano

Zuse Institute Berlin · [serrano@zib.de](mailto:serrano@zib.de)  
SCIP Optimization Suite · <http://scip.zib.de>

Workshop on Discrepancy Theory and Integer Programming

Amsterdam · June 12, 2018



SPONSORED BY THE

Federal Ministry  
of Education  
and Research

# Outline

Introduction: LP-based Branch and Bound  
Spatial Branch and bound

## Heuristics

- Sub-NLP
- NLP diving
- Multi-start
- MPEC
- Undercover
- RENS

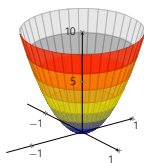
## Conclusion



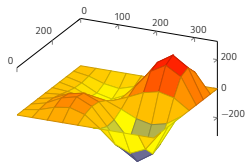
# Mixed-Integer Nonlinear Programs (MINLPs)

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & g_k(x) \leq 0 \quad \forall k \in [m] \\ & x_i \in \mathbb{Z} \quad \forall i \in \mathcal{I} \subseteq [n] \\ & x_i \in [\ell_i, u_i] \quad \forall i \in [n] \end{aligned}$$

The functions  $g_k \in C^1([\ell, u], \mathbb{R})$  can be



convex or



nonconvex

# One way of solving MINLPs to global optimality

- Methods for finding (good) feasible solutions  
    ~> Primal heuristics
  
- Proof that there is no better solution  
    ~> LP-based spatial branch and bound

## LP based spatial Branch & Bound

- Build a (extended formulation of a) **polyhedral** relaxation  $\mathcal{R}$
- Solve  $\mathcal{R}$  and get solution  $x^*$
- If  $x^*$  is feasible we are done. If not,
- Try to strengthen  $\mathcal{R}$  by separating  $x^*$
- When not possible, branch possibly on continuous variables (**spatially**)

## Building polyhedral relaxations: the problem

- We can start with the variable's bounds as our relaxation.
- Then we have to solve the separation problem: Given  $\{x \in [l, u] : g(x) \leq 0\}$  and  $\bar{x}$  s.t.  $g(\bar{x}) > 0$  either
  - Find a separating inequality or
  - prove that none exists.

## Building polyhedral relaxations: the problem

- We can start with the variable's bounds as our relaxation.
- Then we have to solve the separation problem: Given  $\{x \in [l, u] : g(x) \leq 0\}$  and  $\bar{x}$  s.t.  $g(\bar{x}) > 0$  either
  - Find a separating inequality or
  - prove that none exists.
- Very expensive for general  $g$

## Building polyhedral relaxations: the problem

- We can start with the variable's bounds as our relaxation.
- Then we have to solve the separation problem: Given  $\{x \in [l, u] : g(x) \leq 0\}$  and  $\bar{x}$  s.t.  $g(\bar{x}) > 0$  either
  - Find a separating inequality or
  - prove that none exists.
- Very expensive for general  $g$
- However, when  $g$  is convex, it is as easy as computing a gradient:

$$g(\bar{x}) + \nabla g(\bar{x})(x - \bar{x}) \leq 0$$



## Building polyhedral relaxations: the problem

- We can start with the variable's bounds as our relaxation.
- Then we have to solve the separation problem: Given  $\{x \in [l, u] : g(x) \leq 0\}$  and  $\bar{x}$  s.t.  $g(\bar{x}) > 0$  either
  - Find a separating inequality or
  - prove that none exists.
- Very expensive for general  $g$
- However, when  $g$  is convex, it is as easy as computing a gradient:

$$g(\bar{x}) + \nabla g(\bar{x})(x - \bar{x}) \leq 0$$

- Idea: find convex underestimator  $\hat{g}$  of  $g(x)$

## Building polyhedral relaxations: the problem

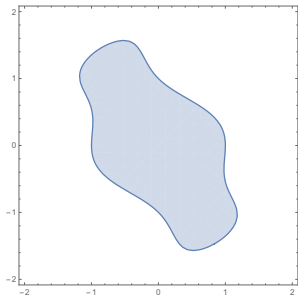
- We can start with the variable's bounds as our relaxation.
- Then we have to solve the separation problem: Given  $\{x \in [l, u] : g(x) \leq 0\}$  and  $\bar{x}$  s.t.  $g(\bar{x}) > 0$  either
  - Find a separating inequality or
  - prove that none exists.
- Very expensive for general  $g$
- However, when  $g$  is convex, it is as easy as computing a gradient:

$$g(\bar{x}) + \nabla g(\bar{x})(x - \bar{x}) \leq 0$$

- Idea: find convex underestimator  $\hat{g}$  of  $g(x)$
- Then  $\{x \in [l, u] : g(x) \leq 0\} \subseteq \{x \in [l, u] : \hat{g}(x) \leq 0\}$
- If  $\hat{g}(\bar{x}) > 0$  we can separate.

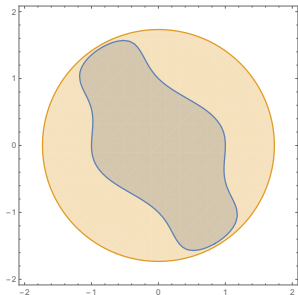
## Building polyhedral relaxations: an example

- $x^2 + y^2 + 2 \exp(xy^3) \leq 3$  with  $x, y \in [-2, 2]$



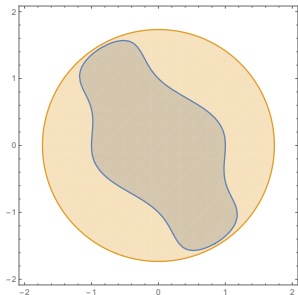
## Building polyhedral relaxations: an example

- $x^2 + y^2 + 2 \exp(xy^3) \leq 3$  with  $x, y \in [-2, 2]$
- $\exp(\cdot) > 0 \Rightarrow x^2 + y^2 \leq x^2 + y^2 + 2 \exp(xy^3)$



## Building polyhedral relaxations: an example

- $x^2 + y^2 + 2 \exp(xy^3) \leq 3$  with  $x, y \in [-2, 2]$
- $\exp(\cdot) > 0 \Rightarrow x^2 + y^2 \leq x^2 + y^2 + 2 \exp(xy^3)$



- Admittedly, ad-hoc argument
- In practice: if functions are simple enough, we know convex/concave envelopes
- If function is not simple enough, make it simpler!

## Building polyhedral relaxation in SCIP

- $x^2 + y^2 + 2 \exp(xy^3) \leq 3$
- Introduce auxiliary variables
  - $z_1 = y^3$
  - $z_2 = xz_1$
  - $x^2 + y^2 + 2 \exp(z_2) \leq 3$
- We can find polyhedral relaxations of  $z_1 = y^3$
- For  $z_2 = xz_1$  we have McCormick inequalities:

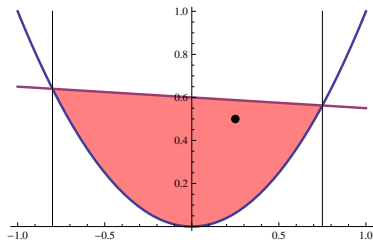
$$\max\{x\underline{z}_1 + z_1\underline{x} - \underline{x}z_1, x\bar{z}_1 + z_1\bar{x} - \bar{x}z_1\} \leq z_2 \leq \min\{x\bar{z}_1 + z_1\underline{x} - \underline{x}\bar{z}_1, x\underline{z}_1 + z_1\bar{x} - \bar{x}\underline{z}_1\}$$

- Finally,  $x^2 + y^2 + 2 \exp(z_2)$  is convex

## Spatial Branch and bound

Solutions might not be separable:  $\text{conv}\{(x, y) : x^2 = y, x \in [\ell, u]\}$  is

$$x^2 \leq y \leq \ell^2 + \frac{u^2 - \ell^2}{u - \ell}(x - \ell) \quad \forall x \in [\ell, u].$$

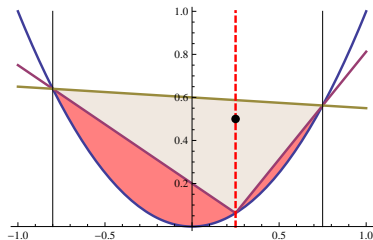
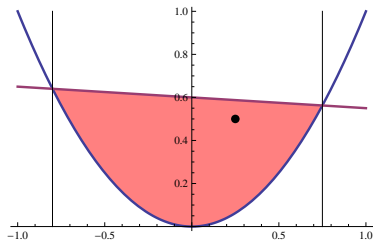


## Spatial Branch and bound

Solutions might not be separable:  $\text{conv}\{(x, y) : x^2 = y, x \in [\ell, u]\}$  is

$$x^2 \leq y \leq \ell^2 + \frac{u^2 - \ell^2}{u - \ell}(x - \ell) \quad \forall x \in [\ell, u].$$

Branching on a **nonlinear variable in a nonconvex constraint** allows for tighter relaxations:





# Outline

Introduction: LP-based Branch and Bound  
Spatial Branch and bound

## Heuristics

- Sub-NLP
- NLP diving
- Multi-start
- MPEC
- Undercover
- RENS

## Conclusion

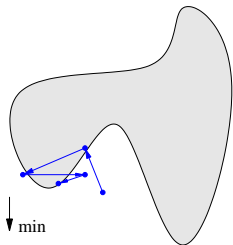


## Sub-NLP

- Idea: fix integer variables to integer values and run a local NLP solver
- Good for: MINLP

Let  $\bar{x}$  be LP-optimum of the current node's relaxation

- If there is a  $i \in \mathcal{I}$  such that  $\bar{x}_i \notin \mathbb{Z} \rightarrow \text{STOP}$
- Fix  $x_i$  to  $\bar{x}_i$ .
- Solve remaining NLP to local optimality using  $\bar{x}$  as initial point.

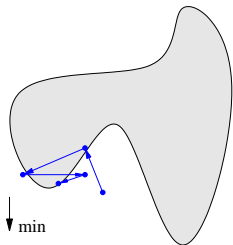


## Sub-NLP

- Idea: fix integer variables to integer values and run a local NLP solver
- Good for: MINLP

Let  $\bar{x}$  be LP-optimum of the current node's relaxation

- If there is a  $i \in \mathcal{I}$  such that  $\bar{x}_i \notin \mathbb{Z} \rightarrow \text{STOP}$
- Fix  $x_i$  to  $\bar{x}_i$ .
- Solve remaining NLP to local optimality using  $\bar{x}$  as initial point.



Extends MIP heuristics to MINLP

- SCIP runs its MIP heuristics on MIP relaxation of MINLP
- use heuristic's proposed solution as  $\bar{x}$

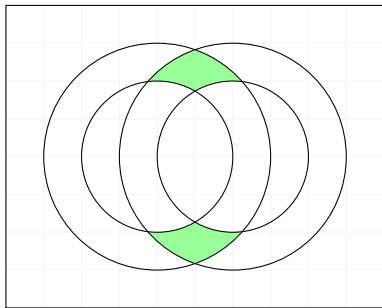
## NLP diving

- Idea: Solve NLP relaxations, fixing an integer variable after each NLP
- Good for: MINLP
  
- solve NLP relaxation
- fix an integer variable
- propagate
- repeat
- if fixing is infeasible, backtrack
  - undo last fixing and fix to another value
  - if infeasible again, abort

## Multi-start Heuristic [Chinneck et al. 2013]

- Idea: use different starting points for NLP solver
- Good for: NLPs without too many integer variables

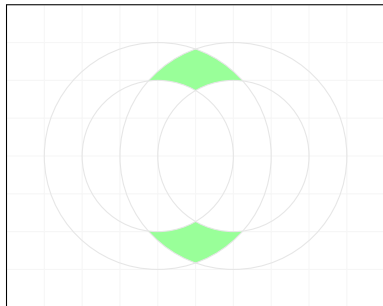
$$\begin{aligned}4 &\leq x^2 + y^2 \leq 9 \\4 &\leq (x - 2)^2 + y^2 \leq 9 \\x &\in [-4, 6] \\y &\in [-4, 4]\end{aligned}$$



## Multi-start in SCIP

Input: Nonlinear Constraints  $g_i(x) \leq 0$

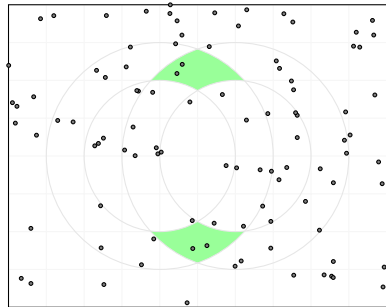
1. generate random points in  $[\ell, u]$



## Multi-start in SCIP

Input: Nonlinear Constraints  $g_i(x) \leq 0$

1. generate random points in  $[\ell, u]$

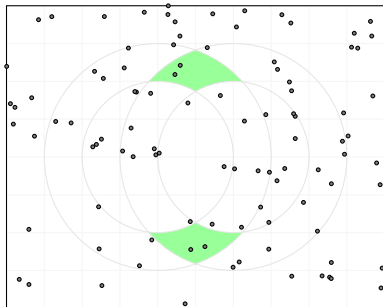


## Multi-start in SCIP

Input: Nonlinear Constraints  $g_i(x) \leq 0$

1. generate random points in  $[\ell, u]$
2. for each point  $x_k$ :
  - $s_i^k := \frac{-g_i(x_k)}{\|\nabla g_i(x_k)\|^2} \nabla g_i(x_k) \quad \forall i$
  - Update:

$$x_k^+ = x_k + \frac{1}{n} \sum_{i=1}^n s_i^k$$



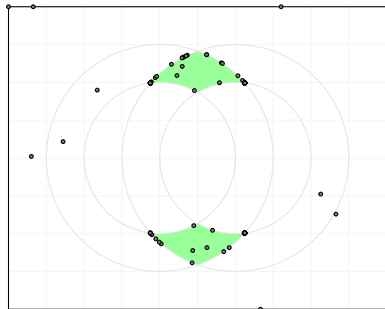


## Multi-start in SCIP

Input: Nonlinear Constraints  $g_i(x) \leq 0$

1. generate random points in  $[\ell, u]$
2. for each point  $x_k$ :
  - $s_i^k := \frac{-g_i(x_k)}{\|\nabla g_i(x_k)\|^2} \nabla g_i(x_k) \quad \forall i$
  - Update:

$$x_k^+ = x_k + \frac{1}{n} \sum_{i=1}^n s_i^k$$

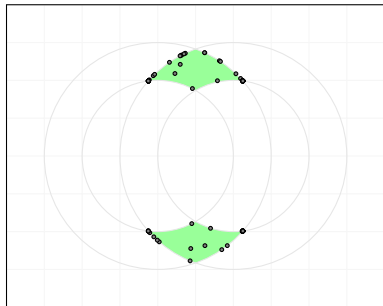


## Multi-start in SCIP

Input: Nonlinear Constraints  $g_i(x) \leq 0$

1. generate random points in  $[\ell, u]$
2. for each point  $x_k$ :
  - $s_i^k := \frac{-g_i(x_k)}{\|\nabla g_i(x_k)\|^2} \nabla g_i(x_k) \forall i$
  - Update:

$$x_k^+ = x_k + \frac{1}{n} \sum_{i=1}^n s_i^k$$



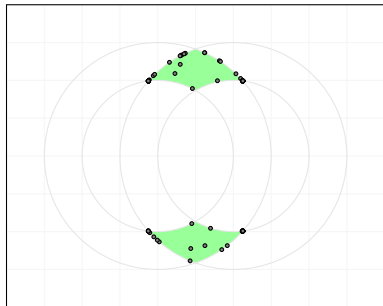
## Multi-start in SCIP

Input: Nonlinear Constraints  $g_i(x) \leq 0$

1. generate random points in  $[\ell, u]$
2. for each point  $x_k$ :
  - $s_i^k := \frac{-g_i(x_k)}{\|\nabla g_i(x_k)\|^2} \nabla g_i(x_k) \quad \forall i$
  - Update:

$$x_k^+ = x_k + \frac{1}{n} \sum_{i=1}^n s_i^k$$

3. identify clusters of points  $C_1, \dots, C_p$



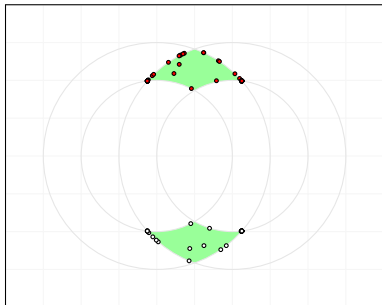
## Multi-start in SCIP

Input: Nonlinear Constraints  $g_i(x) \leq 0$

1. generate random points in  $[\ell, u]$
2. for each point  $x_k$ :
  - $s_i^k := \frac{-g_i(x_k)}{\|\nabla g_i(x_k)\|^2} \nabla g_i(x_k) \forall i$
  - Update:

$$x_k^+ = x_k + \frac{1}{n} \sum_{i=1}^n s_i^k$$

3. identify clusters of points  $C_1, \dots, C_p$
4. for each cluster
  - build convex combination  
 $y := \frac{1}{|C_j|} \sum_{x \in C_j} x$
  - round each fractional integer variable to closest integer
  - use resulting point as starting point for NLP



## MPEC Heuristic [Schewe and Schmidt 2016]

- Idea: write  $x \in \{0, 1\}$  as  $x(1 - x) = 0$ , relax to  $x(1 - x) \leq \varepsilon$  and solve sequences of NLP with  $\varepsilon \rightarrow 0$
- Good for: Mixed **Binary** NLPs
- MPEC stands for Mathematical Program with Equilibrium Constraints

$$\begin{array}{ll} \min f(x) & \\ \text{s.t. } g_j(x) \leq 0 & \forall j \in \{1, \dots, m\} \\ x_i \in [\ell_i, u_i] & \forall i \in \{1, \dots, k\} \\ x_i \in \{0, 1\} & \forall i \in \{k + 1, \dots, n\} \end{array}$$

## MPEC Heuristic [Schewe and Schmidt 2016]

- Idea: write  $x \in \{0, 1\}$  as  $x(1 - x) = 0$ , relax to  $x(1 - x) \leq \varepsilon$  and solve sequences of NLP with  $\varepsilon \rightarrow 0$
- Good for: Mixed **Binary** NLPs
- MPEC stands for Mathematical Program with Equilibrium Constraints

$$\begin{aligned} & \min f(x) \\ \text{s.t. } & g_j(x) \leq 0 \quad \forall j \in \{1, \dots, m\} \\ & x_i \in [\ell_i, u_i] \quad \forall i \in \{1, \dots, k\} \\ & x_i \in [0, 1] \quad \forall i \in \{k + 1, \dots, n\} \\ & x_i(1 - x_i) \leq 0 \quad \forall i \in \{k + 1, \dots, n\} \end{aligned} \quad (\text{NLP})$$

## MPEC Heuristic [Schewe and Schmidt 2016]

- Idea: write  $x \in \{0, 1\}$  as  $x(1 - x) = 0$ , relax to  $x(1 - x) \leq \varepsilon$  and solve sequences of NLP with  $\varepsilon \rightarrow 0$
- Good for: Mixed **Binary** NLPs
- MPEC stands for Mathematical Program with Equilibrium Constraints

$$\begin{array}{ll} \min f(x) \\ \text{s.t. } g_j(x) \leq 0 & \forall j \in \{1, \dots, m\} \\ x_i \in [l_i, u_i] & \forall i \in \{1, \dots, k\} \\ x_i \in [0, 1] & \forall i \in \{k + 1, \dots, n\} \\ x_i(1 - x_i) \leq \varepsilon & \forall i \in \{k + 1, \dots, n\} \end{array} \quad (NLP_\varepsilon)$$

# MPEC in SCIP

## Algorithm

0. choose  $\varepsilon \in [0, \frac{1}{4}]$  and  $x \in \mathbb{R}^n$



# MPEC in SCIP

## Algorithm

0. choose  $\varepsilon \in [0, \frac{1}{4}]$  and  $x \in \mathbb{R}^n$
1.  $x^* :=$  solution of  $NLP_\varepsilon$  using  $x$  as starting point

# MPEC in SCIP

## Algorithm

0. choose  $\varepsilon \in [0, \frac{1}{4}]$  and  $x \in \mathbb{R}^n$
1.  $x^* :=$  solution of  $NLP_\varepsilon$  using  $x$  as starting point
2. if  $x^*$  is feasible for  $NLP_\varepsilon$  and  $x_i^* \in \{0, 1\} \rightarrow$  STOP

## Algorithm

0. choose  $\varepsilon \in [0, \frac{1}{4}]$  and  $x \in \mathbb{R}^n$
1.  $x^* :=$  solution of  $NLP_\varepsilon$  using  $x$  as starting point
2. if  $x^*$  is feasible for  $NLP_\varepsilon$  and  $x_i^* \in \{0, 1\} \rightarrow$  STOP
3. if  $x^*$  is feasible for  $NLP_\varepsilon$  but not binary:

## Algorithm

0. choose  $\varepsilon \in [0, \frac{1}{4}]$  and  $x \in \mathbb{R}^n$
1.  $x^* :=$  solution of  $NLP_\varepsilon$  using  $x$  as starting point
2. if  $x^*$  is feasible for  $NLP_\varepsilon$  and  $x_i^* \in \{0, 1\} \rightarrow$  STOP
3. if  $x^*$  is feasible for  $NLP_\varepsilon$  but not binary:
  - $\varepsilon := \frac{\varepsilon}{2}$ ; GOTO 1. with  $x := x^*$

## Algorithm

0. choose  $\varepsilon \in [0, \frac{1}{4}]$  and  $x \in \mathbb{R}^n$
1.  $x^* :=$  solution of  $NLP_\varepsilon$  using  $x$  as starting point
2. if  $x^*$  is feasible for  $NLP_\varepsilon$  and  $x_i^* \in \{0, 1\} \rightarrow$  STOP
3. if  $x^*$  is feasible for  $NLP_\varepsilon$  but not binary:
  - $\varepsilon := \frac{\varepsilon}{2}$ ; GOTO 1. with  $x := x^*$
4.  $x^*$  is infeasible for  $NLP_\varepsilon$  but satisfies  $x_i^*(1 - x_i^*) \leq \varepsilon \rightarrow$  STOP

## Algorithm

0. choose  $\varepsilon \in [0, \frac{1}{4}]$  and  $x \in \mathbb{R}^n$
1.  $x^* :=$  solution of  $NLP_\varepsilon$  using  $x$  as starting point
2. if  $x^*$  is feasible for  $NLP_\varepsilon$  and  $x_i^* \in \{0, 1\} \rightarrow$  STOP
3. if  $x^*$  is feasible for  $NLP_\varepsilon$  but not binary:
  - $\varepsilon := \frac{\varepsilon}{2}$ ; GOTO 1. with  $x := x^*$
4.  $x^*$  is infeasible for  $NLP_\varepsilon$  but satisfies  $x_i^*(1 - x_i^*) \leq \varepsilon \rightarrow$  STOP
5.  $x^*$  is infeasible for  $NLP_\varepsilon$  and there are  $x_i^*(1 - x_i^*) > \varepsilon$

## Algorithm

0. choose  $\varepsilon \in [0, \frac{1}{4}]$  and  $x \in \mathbb{R}^n$
1.  $x^* :=$  solution of  $NLP_\varepsilon$  using  $x$  as starting point
2. if  $x^*$  is feasible for  $NLP_\varepsilon$  and  $x_i^* \in \{0, 1\} \rightarrow$  STOP
3. if  $x^*$  is feasible for  $NLP_\varepsilon$  but not binary:
  - $\varepsilon := \frac{\varepsilon}{2}$ ; GOTO 1. with  $x := x^*$
4.  $x^*$  is infeasible for  $NLP_\varepsilon$  but satisfies  $x_i^*(1 - x_i^*) \leq \varepsilon \rightarrow$  STOP
5.  $x^*$  is infeasible for  $NLP_\varepsilon$  and there are  $x_i^*(1 - x_i^*) > \varepsilon$ 
  - reset or fix  $x_i$  for binary variables with  $x_i^*(1 - x_i^*) > \varepsilon$

## Algorithm

0. choose  $\varepsilon \in [0, \frac{1}{4}]$  and  $x \in \mathbb{R}^n$
1.  $x^* :=$  solution of  $NLP_\varepsilon$  using  $x$  as starting point
2. if  $x^*$  is feasible for  $NLP_\varepsilon$  and  $x_i^* \in \{0, 1\} \rightarrow$  STOP
3. if  $x^*$  is feasible for  $NLP_\varepsilon$  but not binary:
  - $\varepsilon := \frac{\varepsilon}{2}$ ; GOTO 1. with  $x := x^*$
4.  $x^*$  is infeasible for  $NLP_\varepsilon$  but satisfies  $x_i^*(1 - x_i^*) \leq \varepsilon \rightarrow$  STOP
5.  $x^*$  is infeasible for  $NLP_\varepsilon$  and there are  $x_i^*(1 - x_i^*) > \varepsilon$ 
  - reset or fix  $x_i$  for binary variables with  $x_i^*(1 - x_i^*) > \varepsilon$
  - $x_i := \begin{cases} 0, & x_i^* > 0.5 \\ 1, & \text{otherwise} \end{cases}$

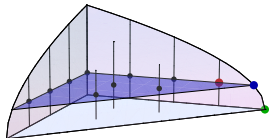


## Algorithm

0. choose  $\varepsilon \in [0, \frac{1}{4}]$  and  $x \in \mathbb{R}^n$
1.  $x^* :=$  solution of  $NLP_\varepsilon$  using  $x$  as starting point
2. if  $x^*$  is feasible for  $NLP_\varepsilon$  and  $x_i^* \in \{0, 1\} \rightarrow$  STOP
3. if  $x^*$  is feasible for  $NLP_\varepsilon$  but not binary:
  - $\varepsilon := \frac{\varepsilon}{2}$ ; GOTO 1. with  $x := x^*$
4.  $x^*$  is infeasible for  $NLP_\varepsilon$  but satisfies  $x_i^*(1 - x_i^*) \leq \varepsilon \rightarrow$  STOP
5.  $x^*$  is infeasible for  $NLP_\varepsilon$  and there are  $x_i^*(1 - x_i^*) > \varepsilon$ 
  - reset or fix  $x_i$  for binary variables with  $x_i^*(1 - x_i^*) > \varepsilon$
  - $x_i := \begin{cases} 0, & x_i^* > 0.5 \\ 1, & \text{otherwise} \end{cases}$
  - GOTO 1.

## Undercover [Berthold and Gleixner 2014]

- Idea: fix variables so that MINLP transforms into a MIP
- Good for: MIQCQP
  
- Solve a relaxation (LP, NLP)
- Identify minimum set  $\mathcal{C}$  of variables to be fixed in order to obtain a MIP
- Fix variables in  $\mathcal{C}$  to relaxation's solution.
- Solve MIP
- Postprocess: Fix integer values and solve NLP

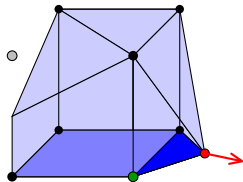


# Undercover in SCIP

- Identifying minimum set  $\mathcal{C}$  of variables to be fixed
  - If  $\frac{\partial^2}{\partial x_i \partial x_j} g_R(x) \neq 0$  then  $x_i$  or  $x_j$  must be fixed
  - Build graph with nodes  $x_i$  and arcs  $\{x_i, x_j\}$  if  $\frac{\partial}{\partial x_i \partial x_j} g_R(x) \neq 0$
  - Minimum vertex cover yields the set we are looking for.
- Fix variables in  $\mathcal{C}$  to relaxation's solution
  - Fix a variable, if variable must be integer, fix to rounded value.
  - Propagate bounds: to avoid "obvious" infeasible fixings
  - If next fixing value is outside bounds, choose closest bound or resolve relaxation
  - If infeasible, backtrack: undo last fixing and try new value

## RENS: The optimal rounding [Berthold 2014]

- RENS stands for Relaxation Enforced Neighborhood Search
- Idea: restrict integer variables around LP-relaxation's solution and solve remaining MINLP
- Good for: MIP, MINLP
  
- Let  $\bar{x}$  be the LP solution
- If  $|\{i \in \mathcal{I} : \bar{x}_i \in \mathbb{Z}\}| > p|\mathcal{I}|$  for some  $p \in [0, 1]$  then
- Change bounds of  $x_i$  to  $\{\lfloor \bar{x}_i \rfloor, \lceil \bar{x}_i \rceil\}$
- Solve smaller MINLP
  
- This gives the feasible rounding with best objective value



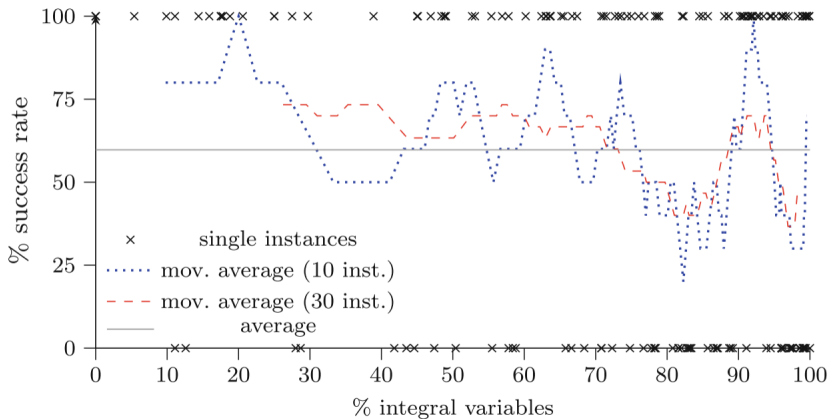
# Computational results for RENS

**Table 1** Computing optimal roundings (aggregated results)

	Integrality		Succ	Prim. gap		Comp. effort	
	>90 %	Avg (%)		Mean	Std dev	Nodes	Time (s)
MIP + cuts	55/159	71.7	95/159	8.22	20.34	814.4	22.6
MIP – cuts	62/159	73.6	80/159	10.88	21.19	719.9	21.7
MIQCP (LP)	9/70	59.9	49/70	11.61	13.14	627.7	30.9
MIQCP (NLP)	1/70	13.8	48/70	1.30	3.37	7,078.8	168.1
MINLP (LP)	6/105	63.5	65/105	13.80	17.73	11,175.6	83.0
MINLP (NLP)	1/105	15.0	73/105	4.60	14.99	93,908.0	262.7

- Basic LP solutions often show high integrality
- Success rate seems to decrease when more integer variables are fixed
- Roundability of MIP and MINLP are similar

# Computational results for RENS



**Fig. 3** Moving averages of success rate, MIPLIB instances, after cuts

- Basic LP solutions often show high integrality
- Success rate seems to decrease when more integer variables are fixed
- Roundability of MIP and MINLP are similar

# Outline

Introduction: LP-based Branch and Bound  
Spatial Branch and bound

## Heuristics

- Sub-NLP
- NLP diving
- Multi-start
- MPEC
- Undercover
- RENS

## Conclusion



# Conclusion

## Summary

- very brief introduction to LP-based branch and bound
- overview of MINLP heuristics in SCIP



# Conclusion

## Summary

- very brief introduction to LP-based branch and bound
- overview of MINLP heuristics in SCIP

## What is missing in SCIP

- Non-linear Feasibility Pump
- Problem specific heuristics

# Conclusion

## Summary

- very brief introduction to LP-based branch and bound
- overview of MINLP heuristics in SCIP

## What is missing in SCIP

- Non-linear Feasibility Pump
- Problem specific heuristics

*Thank you for your attention*

# Primal heuristic for MINLPs in SCIP

Ambros Gleixner, and Felipe Serrano

Zuse Institute Berlin · [serrano@zib.de](mailto:serrano@zib.de)  
SCIP Optimization Suite · <http://scip.zib.de>

Workshop on Discrepancy Theory and Integer Programming

Amsterdam · June 12, 2018



SPONSORED BY THE

Federal Ministry  
of Education  
and Research

# Literature I



Timo Berthold.

**RENS – the optimal rounding.**

*Mathematical Programming Computation*, 6(1):33–54, 2014.

doi: 10.1007/s12532-013-0060-9.



Timo Berthold and Ambros M. Gleixner.

**Undercover: a primal MINLP heuristic exploring a largest sub-MIP.**

*Mathematical Programming*, 144(1-2):315–346, 2014.

doi: 10.1007/s10107-013-0635-2.



Lars Schewe and Martin Schmidt.

**Computing feasible points for minlps with mpecs.**

Technical report, Technical report, Optimization Online, 2016. URL

[http://www.optimization-online.org/DB\\_HTML/2016/12/5778.html](http://www.optimization-online.org/DB_HTML/2016/12/5778.html), 2016.



Laurence Smith, John Chinneck, and Victor Aitken.

**Improved constraint consensus methods for seeking feasibility in nonlinear programs.**

*Computational Optimization and Applications*, 54(3):555–578, 2013.

doi: [10.1007/s10589-012-9473-z](https://doi.org/10.1007/s10589-012-9473-z).