

Introduction to Semidefinite Programming I:
Basic properties and variations on the
Goemans-Williamson approximation algorithm for
max-cut
MFO seminar on Semidefinite Programming

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Positive semidefinite matrices

Definition: For a symmetric $n \times n$ matrix X , the following conditions are equivalent:

1. X is *positive semidefinite* (written $X \succeq 0$) if all eigenvalues of X are nonnegative.
2. $u^T X u \geq 0$ for all $u \in \mathbb{R}^n$.
3. $X = U U^T$ for some matrix $U \in \mathbb{R}^{n \times p}$.
4. For some vectors $v_1, \dots, v_n \in \mathbb{R}^p$, $X_{ij} = v_i^T v_j$ ($i, j \in [n]$).
Say that X is the *Gram matrix* of the v_i 's.
5. All principal minors of X are nonnegative.

Definition: X is *positive definite* (written $X \succ 0$) if all eigenvalues of X are positive.

Notation

- ▶ \mathcal{S}_n : the space of $n \times n$ symmetric matrices.
- ▶ \mathcal{S}_n^+ : the cone of positive semidefinite matrices.
- ▶ \mathcal{S}_n^{++} : the cone of positive definite matrices.
- ↪ \mathcal{S}_n^{++} is the interior of the cone \mathcal{S}_n^+ .

Trace inner product on \mathcal{S}_n :

$$A \cdot B = \text{Tr}(A^T B) = \sum_{i,j=1}^n A_{ij} B_{ij}$$

The PSD cone is self-dual: For $X \in \mathcal{S}_n$,

$$A \in \mathcal{S}_n^+ \iff A \cdot B \geq 0 \quad \forall B \in \mathcal{S}_n^+$$

Primal/dual semidefinite programs

Given matrices $C, A_1, \dots, A_m \in \mathcal{S}_n$ and a vector $b \in \mathbb{R}^m$

Primal SDP:

$$p^* := \max_X C \cdot X \quad \text{such that} \quad A_j \cdot X = b_j \quad (j = 1, \dots, m), \quad X \succeq 0$$

Dual SDP:

$$d^* := \min_y b \cdot y \quad \text{such that} \quad \sum_{j=1}^m y_j A_j - C \succeq 0$$

Weak duality: $p^* \leq d^*$

Pf: If X is *primal feasible* and y is *dual feasible*, then

$$0 \leq \left(\sum_{j=1}^m y_j A_j - C \right) \cdot X = \sum_j y_j (A_j \cdot X) - C \cdot X = b \cdot y - C \cdot X$$

Analogy between LP and SDP

Given vectors $c, a_1, \dots, a_m \in \mathbb{R}^n$ and $b \in \mathbb{R}^m$

Primal/dual LP:

$$\max_x c \cdot x \quad \text{such that} \quad a_j \cdot x = b_j \quad (\forall j \leq m), \quad x \in \mathbb{R}_+^n$$

$$\min_y b \cdot y \quad \text{such that} \quad \sum_{j=1}^m y_j a_j - c \geq 0$$

Primal SDP:

$$\max_X C \cdot X \quad \text{such that} \quad A_j \cdot X = b_j \quad (j = 1, \dots, m), \quad X \in \mathcal{S}_n^+$$

- ▶ SDP is the analogue of LP, replacing \mathbb{R}_+^n by \mathcal{S}_n^+ .
- ▶ Get LP when C, A_j are diagonal matrices.

Strong duality: $p^* = d^*$?

Strong duality holds for LP, but we need some regularity condition (e.g., *Slater condition*) to have strong duality for SDP !

Primal (P) / Dual (D) SDP's: $p^* \leq d^*$

(P) $p^* = \sup C \cdot X$ s.t. $A_j \cdot X = b_j$ ($j = 1, \dots, m$), $X \succeq 0$

(D) $d^* = \inf b \cdot y$ s.t. $\sum_{j=1}^m y_j A_j - C \succeq 0$

Strong duality Theorem:

1. If (P) is *strictly feasible* ($\exists X \succ 0$ feasible for (P)) and bounded ($p^* < \infty$), then $p^* = d^*$ and (D) attains its infimum.
2. If (D) is *strictly feasible* ($\exists y$ with $\sum_j y_j A_j - C \succ 0$) and bounded ($d^* > -\infty$), then $p^* = d^*$ and (P) attains its supremum.

Proof of 2. Assume $d^* \in \mathbb{R}$ and $\sum_j \tilde{y}_j A_j - C \succ 0 \quad \exists \tilde{y}$

$$p^* = \max_{X \succeq 0} \begin{array}{l} C \cdot X \\ A_j \cdot X = b_j \end{array} \stackrel{?}{\geq} d^* = \inf_y \begin{array}{l} b \cdot y \\ \sum_j y_j A_j - C \succeq 0 \end{array}$$

Goal: There exists X feasible for (P) with $C \cdot X \geq d^*$.

WMA $b \neq 0$ (else, $b = 0$ implies $d^* = 0$ and choose $X = 0$). Set

$$\mathcal{M} := \left\{ \sum_j y_j A_j - C \mid y \in \mathbb{R}^m, b \cdot y \leq d^* \right\}.$$

Fact: $\mathcal{M} \cap \mathcal{S}_n^{++} = \emptyset$.

Pf: Otherwise, let y for which $b \cdot y \leq d^*$ and $\sum_j y_j A_j - C \succ 0$.

Then one can find y' with $b \cdot y' < b \cdot y \leq d^*$ and $\sum_j y'_j A_j - C \succ 0$.

\rightsquigarrow This contradicts the minimality of d^* .

Sketch of proof for 2. (continued)

As $\mathcal{M} \cap \mathcal{S}_n^{++} = \emptyset$, there is a hyperplane separating \mathcal{M} and \mathcal{S}_n^{++} .
That is, there exists $Z \succeq 0$ non-zero with $Z \cdot Y \leq 0 \forall Y \in \mathcal{M}$, i.e.,

$$b \cdot y \leq d^* \implies Z \cdot \left(\sum_j y_j A_j - C \right) \leq 0$$

By Farkas' lemma, there exists $\mu \in \mathbb{R}_+$ for which

$$(Z \cdot A_j)_j = \mu b \quad \text{and} \quad \mu d^* \leq Z \cdot C$$

If $\mu = 0$, then $0 \geq \underbrace{Z}_{\succeq 0} \cdot \underbrace{\left(\sum_j \tilde{y}_j A_j - C \right)}_{\succ 0} > 0$, a contradiction.

Hence $\mu > 0$ and Z/μ is feasible for (P) with $C \cdot (Z/\mu) \geq d^*$.
QED.

An example with duality gap

$$\begin{aligned}
 p^* &= \min x_{12} \quad \text{s.t.} \quad \begin{pmatrix} 0 & x_{12} & 0 \\ x_{12} & x_{22} & 0 \\ 0 & 0 & 1 + x_{12} \end{pmatrix} \succeq 0 \\
 &= \min \frac{1}{2} E_{12} \cdot X \quad \text{s.t.} \quad \begin{aligned}
 E_{11} \cdot X &= 0 && \rightsquigarrow a \\
 E_{13} \cdot X &= 0 && \rightsquigarrow b \\
 E_{23} \cdot X &= 0 && \rightsquigarrow c \\
 (E_{33} - \frac{1}{2} E_{12}) \cdot X &= 1 && \rightsquigarrow y \\
 X &\succeq 0
 \end{aligned}
 \end{aligned}$$

$$\begin{aligned}
 d^* &= \max y \quad \text{s.t.} \quad \frac{1}{2} E_{12} - a E_{11} - b E_{13} - c E_{23} - y (E_{33} - \frac{1}{2} E_{12}) \succeq 0 \\
 &= \max y \quad \text{s.t.} \quad \begin{pmatrix} -a & \frac{y+1}{2} & -b \\ \frac{y+1}{2} & 0 & -c \\ -b & -c & -y \end{pmatrix} \succeq 0
 \end{aligned}$$

Thus, $p^* = 0$, $d^* = -1 \rightsquigarrow$ non-zero duality gap

Complexity

Recall: An LP with rational data has a *rational* optimum solution whose *bit size is polynomially bounded* in terms of the bit length of the input data.

Not true for SDP:

▶ $\sqrt{2} = \max x \quad \text{s.t.} \quad \begin{pmatrix} 1 & x \\ x & 2 \end{pmatrix} \succeq 0$

▶ Any solution to

$$\begin{pmatrix} x_1 - 2 & 0 \\ 0 & 1 \end{pmatrix} \succeq 0, \quad \begin{pmatrix} x_2 & x_1 \\ x_1 & 1 \end{pmatrix} \succeq 0, \dots, \quad \begin{pmatrix} x_n & x_{n-1} \\ x_{n-1} & 1 \end{pmatrix} \succeq 0$$

satisfies $x_1 \geq 2^{2^{n-1}}$.

Complexity (continued)

Theorem: SDP can be solved in polynomial time to an arbitrary prescribed precision. [Assuming certain technical conditions hold.]

- ▶ Theoretically: Use the ellipsoid method [since checking whether $X \succeq 0$ is in P, e.g. with Gaussian elimination]
- ▶ Practically: Use e.g. interior-point algorithms.

More precisely: Let K denote the feasible region of the SDP. Assume we know $R \in \mathbb{N}$ s.t. $\exists X \in K$ with $\|X\| \leq R$ if $K \neq \emptyset$.

Given $\epsilon > 0$, the ellipsoid based algorithm, either finds X^* at distance at most ϵ from K such that $C \cdot X^* \geq C \cdot X - \epsilon \quad \forall X \in K$ at distance at least ϵ from the border, or claims: there is no such X .

The running time is polynomial in n , m , the bit size of A_j , C , b , $\log R$, and $\log(1/\epsilon)$.

Feasibility of SDP

Feasibility SDP problem (F): Given integer $A_0, A_j \in \mathcal{S}_n$, decide whether there exists $x \in \mathbb{R}^m$ s.t. $A_0 + \sum_{j=1}^m x_j A_j \succeq 0$?

- ▶ $(F) \in \text{NP} \iff (F) \in \text{co-NP}$. [Ramana 97]
- ▶ $(F) \in \text{P}$ for **fixed** n or m . [Porkolab-Khachiyan 97]
- ▶ Testing existence of a *rational* solution is in P for **fixed dimension** m . [Porkolab-Khachiyan 97]

↪ More on complexity and algorithms for SDP in other lectures.

Use SDP to express convex quadratic constraints

Consider the convex quadratic constraint:

$$x^T A x \leq b^T x + c$$

where $A \succeq 0$.

▶ Write $A = B^T B$ for some $B \in \mathbb{R}^{p \times n}$.

▶ **Then:** $x^T A x \leq b^T x + c \iff \begin{pmatrix} I_p & Bx \\ x^T B^T & b^T x + c \end{pmatrix} \succeq 0$

↪ Use **Schur complement:** Given $C \succ 0$,

$$\begin{pmatrix} C & B \\ B^T & A \end{pmatrix} \succeq 0 \iff A - B^T C^{-1} B \succeq 0$$

The S-lemma [Yakubovich 1971]

Consider the quadratic polynomials:

$$f(x) = x^T A x + 2a^T x + \alpha = (1 \ x^T) \begin{pmatrix} \alpha & a^T \\ a & A \end{pmatrix} \begin{pmatrix} 1 \\ x \end{pmatrix}$$

$$g(x) = x^T B x + 2b^T x + \beta = (1 \ x^T) \begin{pmatrix} \beta & b^T \\ b & B \end{pmatrix} \begin{pmatrix} 1 \\ x \end{pmatrix}$$

Question: Characterize when

$$(*) \ f(x) \geq 0 \implies g(x) \geq 0$$

Answer: Assume $f(x) > 0$ for some x . Then, (*) holds IFF

$$\begin{pmatrix} \beta & b^T \\ b & B \end{pmatrix} - \lambda \begin{pmatrix} \alpha & a^T \\ a & A \end{pmatrix} \succeq 0 \text{ for some } \lambda \geq 0$$

Testing sums of squares of polynomials

Question: How to check whether a polynomial

$p(x) = \sum_{\alpha \in \mathbb{N}^n, |\alpha| \leq 2d} p_\alpha x^\alpha$ can be written as a **sum of squares**:

$p(x) \stackrel{?}{=} \sum_{j=1}^m (u_j(x))^2$ for some polynomials u_j ?

$$x^\alpha = x_1^{\alpha_1} \cdots x_n^{\alpha_n}$$

Answer: Use semidefinite programming:

▶ Write $u_j(x) = (a_j)^T [x]_d$

$$[x]_d = (x^\alpha)_{|\alpha| \leq d}$$

▶ $\sum_j (u_j(x))^2 = ([x]_d)^T \underbrace{\left(\sum_j a_j a_j^T \right)}_{\rightsquigarrow A \succeq 0} [x]_d$

↪ Test feasibility of SDP:

$$\sum_{\substack{\beta, \gamma: |\beta|, |\gamma| \leq d \\ \beta + \gamma = \alpha}} A_{\beta, \gamma} = p_\alpha \quad (|\alpha| \leq 2d), \quad A \succeq 0$$

Two milestone applications of SDP to combinatorial optimization

- ▶ Approximate maximum stable sets and minimum vertex coloring with the theta number.

Work of Lovász [1979], Grötschel-Lovász-Schrijver [1981]

- ▶ (First non-trivial) 0.878-approximation algorithm for max-cut of Goemans-Williamson [1995]

The theta number

$G = (V, E)$ graph.

$S \subseteq V$ **stable set** if S contains no edge.

- ▶ $\alpha(G)$:= maximum size of a stable set \rightsquigarrow stability number
- ▶ $\chi(G)$:= minimum number of colors needed to color the vertices so that adjacent vertices receive distinct colors.
 \rightsquigarrow Computing $\alpha(G), \chi(G)$ is an NP-hard problem.

▶ **The theta number of Lovász [1979]:**

$$\vartheta(G) := \max J \cdot X \quad \text{s.t.} \quad \text{Tr}(X) = 1, \quad X_{ij} = 0 \quad (ij \in E), \quad X \succeq 0$$

▶ **Lovász 'sandwich' theorem:** $\alpha(G) \leq \vartheta(G) \leq \chi(\bar{G})$.

\rightsquigarrow Can compute $\alpha(G), \chi(\bar{G})$ via SDP for graphs with $\alpha(G) = \chi(\bar{G})$.

Maximum cuts in graphs

$G = (V, E)$, $n = |V|$, $w = (w_e)_{e \in E}$ edge weights.

$S \subseteq V \rightsquigarrow$ **cut** $\delta(S) :=$ all edges **cut** by the partition $(S, V \setminus S)$.

Max-Cut problem: Find a cut of maximum weight. $\rightsquigarrow \text{mc}(G)$

- ▶ Max-Cut is NP-hard.

No $(16/17 + \epsilon)$ -approximation algorithm unless $P=NP$.

- ▶ Max-Cut is in P for graphs with no K_5 minor, since it can be computed with the LP: [Barahona-Mahjoub 86]

$$\max w^T x \quad \text{s.t.} \quad x_{ij} - x_{ik} - x_{jk} \leq 0, \quad x_{ij} + x_{ik} + x_{jk} \leq 2 \quad \forall i, j, k \in V$$

An easy $1/2$ -approximation algorithm for $w \geq 0$: Consider the random partition $(S, V \setminus S)$, where $i \in S$ with prob. $1/2$:

$$E(w(S)) = w(E)/2 \geq \text{mc}(G)/2$$

Goemans-Williamson approximation algorithm for Max-Cut

- ▶ Encode a partition $(S, V \setminus S)$ by a vector $x \in \{\pm 1\}^n$.
- ↪ Encode the cut $\delta(S)$ by the matrix $X = xx^T$.

↪ **Reformulate Max-Cut:**

$$\max \frac{1}{2} \sum_{ij \in E} w_{ij} (1 - x_i x_j) \quad \text{s.t. } x \in \{\pm 1\}^n$$

▶ **Solve the SDP relaxation:**

$$\max \frac{1}{2} \sum_{ij \in E} w_{ij} (1 - X_{ij}) \quad \text{s.t. } X \succeq 0, \text{diag}(X) = e$$

↪ v_1, \dots, v_n unit vectors s.t. $X = (v_i^T v_j)$ is opt. for SDP.

▶ **Randomized rounding:** Pick a random hyperplane H with normal r .

↪ partition $(S, V \setminus S)$ depending on the sign of $v_i^T r$.

Performance analysis

Theorem: For $w \geq 0$,

$$\text{mc}(G) \geq \underbrace{E(w(\delta(S)))}_{\geq 0.878 \text{ sdp}(G)} \geq 0.878 \text{ mc}(G).$$

Basic lemma: $\text{Prob}(ij \in \delta(S)) = \frac{\arccos(v_i^T v_j)}{\pi}$.

$$\begin{aligned} E(w(\delta(S))) &= \sum_{ij \in E} w_{ij} \text{Prob}(ij \in \delta(S)) \\ &= \sum_{ij \in E} w_{ij} \frac{\arccos(v_i^T v_j)}{\pi} \\ &= \sum_{ij \in E} w_{ij} \frac{(1 - v_i^T v_j)}{2} \underbrace{\frac{2 \arccos(v_i^T v_j)}{\pi (1 - v_i^T v_j)}}_{\geq \alpha_{\text{GW}} \sim 0.878} \\ &\geq \text{sdp}(G) \alpha_{\text{GW}} \end{aligned}$$

Extension to ± 1 quadratic programming

Given $A \in \mathcal{S}_n$

Integer problem: $\text{ip}(A) := \max x^T A x \quad \text{s.t. } x \in \{\pm 1\}^n$

SDP relaxation: $\text{sdp}(A) := \max A \cdot X \quad \text{s.t. } X \succeq 0, \text{diag}(X) = e.$

- ▶ $A = \frac{1}{4} L_w$, L_w : Laplacian matrix of $(G, w) \rightsquigarrow$ Max-Cut
where $L_w(i, i) = w(\delta(i))$, $L_w(i, j) = -w_{ij}$.
- \rightsquigarrow When $A \succeq 0$, $Ae = e$, $A_{ij} \leq 0$ ($i \neq j$) \rightsquigarrow 0.878-approx. alg.
- ▶ When $A \succeq 0 \rightsquigarrow \frac{2}{\pi}$ (~ 0.636)-approx. alg. [Nesterov 97]
- ▶ When $\text{diag}(A) = 0 \rightsquigarrow$ Grothendieck constant

Nesterov $\frac{2}{\pi}$ -approximation algorithm

- ▶ **Solve SDP:** Let v_1, \dots, v_n unit vectors s.t. $X = (v_i^T v_j)$ maximizes $A \cdot X$.
 - ▶ **Random hyperplane rounding:** Pick a random unit vector r .
- ↪ random ± 1 vector: $x = (\text{sgn}(r^T v_i))_{i=1}^n$

Lemma 1 [identity of Grothendieck] $E(xx^T) = \frac{2}{\pi} \arcsin X$.

Proof:

$$\begin{aligned} E(\text{sgn}(r^T v_i) \text{sgn}(r^T v_j)) &= 1 - 2 \text{Prob}(\text{sgn}(r^T v_i) \neq \text{sgn}(r^T v_j)) \\ &= 1 - 2 \frac{\arccos(v_i^T v_j)}{\pi} = \frac{2}{\pi} \left(\frac{\pi}{2} - \arccos(v_i^T v_j) \right) \\ &= \frac{2}{\pi} \arcsin(v_i^T v_j). \end{aligned}$$

Global performance analysis

Lemma 2: $\arcsin X - X \succeq 0$ **Proof:** $\arcsin x - x = \sum_k a_k x^{2k+1}$ where $a_k \geq 0$.**Global analysis:**

$$\begin{aligned}
 E(x^T A x) = A \cdot E(x x^T) &= A \cdot \left(E(x x^T) - \frac{2}{\pi} X \right) + \frac{2}{\pi} A \cdot X \\
 &= \underbrace{A}_{\succeq 0} \cdot \underbrace{\left(\frac{2}{\pi} \arcsin X - \frac{2}{\pi} X \right)}_{\succeq 0} + \frac{2}{\pi} A \cdot X \\
 &\quad \underbrace{\hspace{10em}}_{\succeq 0} \\
 &\geq \frac{2}{\pi} A \cdot X.
 \end{aligned}$$

Therefore: For $A \succeq 0$, $\text{ip}(A) \geq \frac{2}{\pi} \text{sdp}(A)$.

Grothendieck inequality

Assume $\text{diag}(A) = 0$.

The **support graph** G_A has as edges the pairs ij with $A_{ij} \neq 0$.

Definition: The **Grothendieck constant** $K(G)$ of a graph G is the smallest constant K for which

$$\text{sdp}(A) \leq K \text{ ip}(A) \quad \text{for all } A \in \mathcal{S}_n \text{ with } G_A \subseteq G.$$

Theorem: ([Gr. 53] [Krivine 77] [Alon-Makarychev(x2)-Naor 05])

- ▶ For G complete bipartite, $\frac{\pi}{2} \leq K(G) \leq \frac{\pi}{2} \frac{1}{\ln(1+\sqrt{2})} \sim 1.782$
- ▶ $\Omega(\log(\omega(G))) \leq K(G) \leq O(\log(\vartheta(\bar{G})))$.

Sketch of proof for Krivine's upper bound: $\frac{\pi}{2} \frac{1}{\ln(1+\sqrt{2})}$

Show: $K(K_{n,m}) \leq \frac{\pi}{2} \frac{1}{\ln(1+\sqrt{2})} =: \frac{\pi}{2c} ?$ $c := \ln(1 + \sqrt{2})$

1. Let $A \in \mathbb{R}^{n \times m}$. Let u_i ($i \leq n$) and v_j ($j \leq m$) be unit vectors in H maximizing $\text{sdp}(A) = \sum_{i \leq n, j \leq m} a_{ij} u_i \cdot v_j$.

2. **Construct** new unit vectors $S(u_i), T(v_j) \in \hat{H}$ satisfying $\arcsin(S(u_i) \cdot T(v_j)) = c u_i \cdot v_j$

3. Pick a random unit vector $r \in \hat{H}$. Define the ± 1 vectors x, y
 $x_i = \text{sgn}(r^T S(u_i)), y_j = \text{sgn}(r^T T(v_j))$

4. **Analysis:**

$$\begin{aligned} E(x^T A y) &= \sum_{i,j} a_{ij} E(x_i y_j) = \sum_{i,j} a_{ij} \frac{2}{\pi} \arcsin(S(u_i) \cdot T(v_j)) \\ &= \sum_{i,j} a_{ij} \frac{2}{\pi} c u_i \cdot v_j = \frac{2}{\pi} c \text{sdp}(A). \end{aligned}$$

Proof (continued)

Step 2. Given unit vectors $u, v \in H$, construct $S(u), T(v) \in \hat{H}$ satisfying $\arcsin(S(u) \cdot T(v)) = c u \cdot v$.

- ▶ $\sin x = \sum_{k \geq 0} (-1)^k \frac{x^{2k+1}}{(2k+1)!}$, $\sinh x = \sum_{k \geq 0} \frac{x^{2k+1}}{(2k+1)!}$
- ▶ Set $c := \sinh^{-1}(1) = \ln(1 + \sqrt{2})$.
- ▶ Set $S(u) = \left(\sqrt{\frac{c^{2k+1}}{(2k+1)!}} u^{\otimes(2k+1)} \right)_k \in \hat{H} := \bigoplus_{k \geq 0} H^{\otimes(2k+1)}$,
 $T(v) = \left((-1)^k \sqrt{\frac{c^{2k+1}}{(2k+1)!}} v^{\otimes(2k+1)} \right)_k \in \hat{H}$.
- ▶ Then, $S(u) \cdot T(v) = \sum_k (-1)^k \frac{c^{2k+1}}{(2k+1)!} (u \cdot v)^{2k+1} = \sin(c u \cdot v)$.

Thus: $\arcsin(S(u) \cdot T(v)) = c u \cdot v$.

A reformulation of the theta number

Theorem [Alon-Makarychev(x2)-Naor 05]

The smallest constant C for which

$$\text{sdp}(-A) \leq C \text{sdp}(A) \quad \text{for all } A \in \mathcal{S}_n \text{ with } G_A \subseteq G$$

is $C = \vartheta(\bar{G}) - 1$.

Geometrically:

- ▶ $\mathcal{E}_n := \{X \in \mathcal{S}_n \mid X \succeq 0, \text{diag}(X) = e\}$ \rightsquigarrow the **elliptope**
- ▶ $\mathcal{E}(G) \subseteq \mathbb{R}^E$: the projection of \mathcal{E}_n onto the edge set of G .
- ▶ **Theorem [AMMN]:** $-\mathcal{E}(G) \subseteq (\vartheta(\bar{G}) - 1) \mathcal{E}(G)$.

Link with matrix completion

Matrix completion: Given a partial $n \times n$ matrix, whose entries are specified on the diagonal (say **equal to 1**) and on a subset E of the positions (given by $x \in \mathbb{R}^E$), decide whether it can be completed to a PSD matrix.

Equivalently, decide whether $x \in \mathcal{E}(G)$?

- ▶ **A necessary condition:** Each fully specified principal submatrix is PSD. [Clique condition]
- ▶ The clique condition is sufficient IFF G is a chordal graph (i.e. no induced circuit of length ≥ 4).

$$\begin{pmatrix} 1 & 1 & a? & -1 \\ 1 & 1 & 1 & b? \\ a? & 1 & 1 & 1 \\ -1 & b? & 1 & 1 \end{pmatrix} \text{ is not completable to PSD}$$

Another necessary condition

$$\text{Fact: } \begin{pmatrix} 1 & \cos a & \cos b \\ \cos a & 1 & \cos c \\ \cos b & \cos c & 1 \end{pmatrix} \succeq 0 \iff \begin{cases} a + b + c & \leq 2\pi \\ a - b - c & \leq 0 \\ -a + b - c & \leq 0 \\ -a - b + c & \leq 0 \end{cases}$$

- Write $x = \cos a$ for some $a \in [0, \pi]^E$.

If $x \in \mathcal{E}(G)$ then

[Metric condition]

$$a(F) - a(C \setminus F) \leq \pi(|F| - 1) \quad \forall C \text{ circuit, } F \subseteq C \text{ odd.}$$

- The metric condition is sufficient IFF G has no K_4 minor.

$$\begin{pmatrix} 1 & -1/2 & -1/2 & -1/2 \\ -1/2 & 1 & -1/2 & -1/2 \\ -1/2 & -1/2 & 1 & -1/2 \\ -1/2 & -1/2 & -1/2 & 1 \end{pmatrix} \not\succeq 0$$

while $\frac{2\pi}{3}(1, 1, 1, 1)$ satisfies the triangle inequalities.

Geometrically

- ▶ $\text{CUT}^{\pm 1}(G) \subseteq \mathcal{E}(G)$, with equality IFF G has no K_3 minor.
- ▶ $\mathcal{E}(G) \subseteq \cos(\pi \text{MET}^{01}(G))$, with equality IFF G has no K_4 minor.
- ▶ $\mathcal{E}(G) \subseteq \cos(\pi \text{CUT}^{01}(G))$, with equality IFF G has no K_4 minor.
- ▶ The Goemans-Williamson randomized rounding argument shows: If v_1, \dots, v_n are unit vectors and $a_{ij} := \arccos(v_i^T v_j)$ are their pairwise angles, then

$$\sum_{1 \leq i < j \leq n} c_{ij} a_{ij} \leq \pi c_0$$

if $c \cdot z \leq c_0$ is any inequality valid for the cuts of K_n .

Extension to max k -cut [Frieze Jerrum 95]

Max k -cut: Given $G = (V, E)$, $w \in \mathbb{R}_+^E$, $k \geq 2$, find a partition $\mathcal{P} = (S_1, \dots, S_k)$ maximizing $w(\mathcal{P}) = \sum_{e \in E | e \text{ is cut by } \mathcal{P}} w_e$.

- ▶ Pick unit vectors $a_1, \dots, a_k \in \mathbb{R}^k$ with $a_i^T a_j = -\frac{1}{k-1}$ for $i \neq j$.

↪ **Model max k -cut:**

$$\begin{aligned} \text{mc}_k(G) = \max & \frac{k-1}{k} \sum_{ij \in E} w_{ij} (1 - x_i^T x_j) \\ \text{s.t. } & x_1, \dots, x_n \in \{a_1, \dots, a_k\}. \end{aligned}$$

- ▶ **SDP relax.:** $\text{sdp}_k(G) = \max \frac{k-1}{k} \sum_{ij \in E} w_{ij} (1 - v_i^T v_j)$
s.t. v_i unit vectors, $v_i^T v_j \geq -\frac{1}{k-1}$.
- ▶ **Randomized rounding:** Pick k independent random unit vectors $r_1, \dots, r_k \rightsquigarrow$ partition $\mathcal{P} = (S_1, \dots, S_k)$ where $S_h = \{i \mid v_i^T r_h \geq v_i^T r_{h'} \ \forall h'\}$.

Analysis

- ▶ The probability that edge ij is not cut, i.e., v_i, v_j are both closer to the same r_h , is equal to k times a function $f(v_i^T v_j)$.

$$\begin{aligned}
 E(w(\mathcal{P})) &= \sum_{ij \in E} w_{ij} (1 - kf(v_i^T v_j)) \\
 &= \sum_{ij \in E} w_{ij} \underbrace{\frac{1 - kf(v_i^T v_j)}{1 - v_i^T v_j} \frac{k}{k-1}}_{\geq \alpha_k := \min_{-\frac{1}{k-1} \leq t \leq 1} \frac{1 - kf(t)}{1-t} \frac{k}{k-1}} \frac{k-1}{k} (1 - v_i^T v_j) \\
 &\geq \alpha_k \operatorname{sdp}_k(G).
 \end{aligned}$$

- ▶ $\alpha_2 = \alpha_{GW} \sim 0.878$: GW approximation ratio for max-cut.
- $\alpha_3 = \frac{7}{12} + \frac{3}{4\pi^2} \arccos^2(-1/4) > 0.836$ [de Klerk et al.]
- $\alpha_{100} > 0.99$.