

# Introduction to Semidefinite Programming II: Variations on the theta number

MFO seminar on Semidefinite Programming

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# Stable sets and graph coloring

$G = (V, E)$  graph  $\rightsquigarrow \bar{G} = (V, \bar{E})$ : complementary graph.

- ▶  $\alpha(G)$  = maximum size of a stable set  $\rightsquigarrow$  stability number
- ▶  $\omega(G)$  = maximum size of a clique in  $G$   $\rightsquigarrow$  clique number
- ▶  $\chi(G)$  = (vertex) coloring number of  $G$ .
- ▶  $\chi_f(G)$  = fractional coloring number of  $G$ .
- ▶ **Lovász' theta number:**

$$\vartheta(G) = \max J \cdot X \quad \text{s.t.} \quad \text{Tr}(X) = 1, \quad X_{ij} = 0 \quad (ij \in E), \quad X \succeq 0$$

**Sandwich theorem:**  $\alpha(G) \leq \vartheta(G) \leq \chi_f(\bar{G}) \leq \chi(\bar{G})$ .

# Approximating the Shannon capacity

- ▶ **The strong product**  $G \cdot G'$  has vertex set  $V \times V'$  and  
 $(uu', vv') \in E(G \cdot G')$



$(u = v \text{ or } uv \in E(G)) \text{ and } (u' = v' \text{ or } u'v' \in E(G'))$ .

- ▶ **Shannon capacity:**  $\Theta(G) := \sup_k \sqrt[k]{\alpha(G^k)}$  [Shannon 1956]

- ▶ **Product property:**  $\vartheta(G \cdot G') = \vartheta(G) \vartheta(G')$ .

**Hence:**  $\Theta(G) \leq \vartheta(G)$ . [Lovász 1979]

- ▶ This permits to show:  $\Theta(C_5) = \sqrt{5}$ .

**Proof:**  $\alpha(C_5^2) = 5$  and  $\vartheta(C_5) = \sqrt{5}$ .

- ▶ **Open:**  $\Theta(C_7) = ?$

**Recall:**  $\omega(G) \leq \chi(G)$ .

Berge [1962] calls  $G$  **perfect** if  $\omega(G') = \chi(G')$  for *all* induced subgraphs  $G'$  of  $G$ .

**Note:** If  $G$  is perfect then no induced subgraph of  $G$  is an odd circuit of length  $\geq 5$  or its complement.

**Perfect graph theorem** [Lovász 1972]

$G$  perfect  $\iff \bar{G}$  perfect.

**Strong perfect graph theorem**

[Chudnovsky-Robertson-Seymour-Thomas 2002]

$G$  perfect  $\iff$  no induced subgraph of  $G$  is an odd circuit of length  $\geq 5$  or its complement.

# Polyhedral characterization of perfect graphs

- ▶ **Stable set polytope:**  $\text{STAB}(G) =$  convex hull of incidence vectors of all stable sets in  $G$ .
- ▶ **Clique constrained polytope:**

$$\text{QSTAB}(G) = \{x \in \mathbb{R}_+^V \mid x(C) \leq 1 \text{ (} C \text{ clique)}\}$$

Obviously,  $\text{STAB}(G) \subseteq \text{QSTAB}(G)$ .

- ▶ **Theorem** [Fulkerson-Chvatal 1972/75]

$$\text{STAB}(G) = \text{QSTAB}(G) \iff G \text{ is perfect.}$$

But this does not help (yet) for optimization!

$$\alpha(G) = \max_{x \in \text{STAB}(G)} e^T x \leq \chi_f(\bar{G}) = \max_{x \in \text{QSTAB}(G)} e^T x.$$

# Finding a maximum stable set in a perfect graph is in P

- ▶ For  $G$  perfect, computing  $\alpha(G)$  and  $\chi(G)$  is in P.

**Proof:**  $\alpha(G) = \vartheta(G)$  and  $\chi(G) = \vartheta(\bar{G})$ .

- ▶ **For  $G$  perfect, one can also find a maximum stable set in polynomial time.** [Grötschel-Lovász-Schrijver 1981]

- Order the vertices  $v_1, \dots, v_n$ .

- Construct graphs  $G_0 := G \supseteq G_1 \supseteq \dots \supseteq G_n$ .

- If  $\alpha(G_0 \setminus v_1) = \alpha(G_0)$ , set  $G_1 = G_0 \setminus v_1$

- otherwise, set  $G_1 = G_0$ .

- Iterate. Then  $G_n$  is a maximum stable set.

- ▶ **Use SDP!**

**Open:** Find a combinatorial algorithm?

# Finding a minimum vertex coloring in $G$ perfect is in P

- ▶ It suffices to find a stable set  $S$  meeting *all* max. size cliques.

Indeed, then *color*  $G \setminus S$  with  $\omega(G \setminus S) = \omega(G) - 1$  colors, and  $S$  with one more color  $\rightsquigarrow \omega(G)$  coloring of  $G$

- ▶ **Strategy:** Grow a list of (affinely independent) maximum size cliques  $Q_1, \dots, Q_t$ , and a stable set  $S$  meeting each  $Q_i$ .

To find such  $S$ , *compute* a maximum weight stable set  $S$  for the weight function  $w := \sum_{i=1}^t \chi^{Q_i}$ .

As  $G$  is perfect,  $w(S) = t$ , thus  $S$  meets each  $Q_i$ .

- ▶ If  $\omega(G \setminus S) = \omega(G)$ , find a maximum size clique  $Q_{t+1}$  in  $G \setminus S$  and iterate.
- ▶ Else,  $S$  meets all maximum size cliques  $\rightsquigarrow$  we are done.

# Geometric reformulation of the theta number

- ▶ **The theta body**  $\text{TH}(G)$  is defined as

$$\left\{ x \in \mathbb{R}^V \mid \exists X \begin{pmatrix} 1 & x^T \\ x & X \end{pmatrix} \succeq 0, \text{diag}(X) = x, X_{ij} = 0 (ij \in E) \right\}$$

- ▶ **Obviously:**  $\text{STAB}(G) \subseteq \text{TH}(G) \subseteq \text{QSTAB}(G)$

- ▶ **Theorem:**  $G$  perfect  $\iff \text{TH}(G) = \text{STAB}(G)$   
 $\iff \text{TH}(G) = \text{QSTAB}(G)$   
 $\iff \text{TH}(G)$  is a polytope.

- ▶ **Geometric reformulation of the theta number:**

$$\vartheta(G) = \max_{x \in \text{TH}(G)} e^T x$$

$$= \max_{Y \in \mathcal{S}_{n+1}^+} \sum_{i \in V} Y_{ii} \quad \text{s.t.} \quad Y_{00} = 1, Y_{0i} = Y_{ii} (i \in V), \\ Y_{ij} = 0 (ij \in E).$$



# Dual formulations of the theta number

$$\vartheta(G) = \max J \cdot X \quad \text{s.t.} \quad I \cdot X = 1, \quad X_{ij} = 0 \quad (ij \in E), \quad X \succeq 0$$

$$= \min t \quad \text{s.t.} \quad tI + \underbrace{\sum_{ij \in E} E_{ij}}_{-Y} - J \succeq 0$$

$Z \rightsquigarrow \frac{1}{t-1} Z = (u_i \cdot u_j)$

$$= \min t \quad \text{s.t.} \quad tI + A - J \succeq 0, \quad A_{ij} = 0 \quad (i = j \text{ or } ij \in \bar{E})$$

$$= \min \lambda_{\max}(Y) \quad \text{s.t.} \quad Y_{ij} = 1 \quad (i = j \text{ or } ij \in \bar{E})$$

$$= \min t \quad \text{s.t.} \quad u_i \cdot u_j = -\frac{1}{t-1} \quad (ij \in \bar{E}), \quad u_j \text{ unit vectors.}$$

$\rightsquigarrow$  *strict vector coloring*

# Deriving the geometric formulation of $\vartheta(G)$ via $\text{TH}(G)$

$$\vartheta(G) = \min t \quad \text{s.t.} \quad \underbrace{tI + A - J}_{B} \succeq 0, \quad A_{ij} = 0 \quad (i = j \text{ or } ij \in \bar{E}).$$

**Schur complement:**  $B \succeq 0 \iff C := \begin{pmatrix} t & e^T \\ e & I + \frac{1}{t}A \end{pmatrix} \succeq 0$

$$\begin{aligned} \vartheta(G) &= \min_{C \succeq 0} C_{00} \quad \text{s.t.} \quad C_{0i} = C_{ii} = 1 \quad (i \in V), \quad C_{ij} = 0 \quad (ij \in \bar{E}) \\ &= \max_{D \succeq 0} - \sum_{i \in V} (2D_{0i} + D_{ii}) \quad \text{s.t.} \quad D_{00} = 1, \quad D_{ij} = 0 \quad (ij \in E) \end{aligned}$$

**Lemma:** If  $D$  is optimum then  $D_{0i} + D_{ii} = 0 \quad \forall i \in V$ .

Else multiply the  $i$ th row/column of  $D$  by  $-\frac{D_{0i}}{D_{ii}} \rightsquigarrow$  better objective.

**Changing signs at positions  $0i$ :**

$$\begin{aligned} \vartheta(G) &= \max_{Y \succeq 0} \sum_{i \in V} Y_{ii} \quad \text{s.t.} \quad Y_{00} = 1, \quad Y_{0i} = Y_{ii} \quad (i \in V), \quad Y_{ij} = 0 \quad (ij \in E) \\ &= \max e^T x \quad \text{s.t.} \quad x \in \text{TH}(G). \end{aligned}$$

# Reformulation of $\vartheta(G)$ via orthonormal representations

**Definition:** An *orthonormal representation* (O.R.) of  $G$  is a set of unit vectors  $u_i$  ( $i \in V$ ) satisfying  $u_i^T u_j = 0$  for nonedges  $ij$ .

**Theorem:**

1. *Linear inequality description:*  $\text{TH}(G)$  is equal to

$$\{x \in \mathbb{R}^V \mid \sum_{i \in V} (c^T u_i)^2 x_i \leq 1 \quad \forall c, u_i \text{ unit vectors} \\ \text{with } u_i \text{ O.R. of } G\}$$

2. *Extreme point description:*  $\text{TH}(\bar{G})$  is equal to

$$\text{conv}\{((c^T u_1)^2, \dots, (c^T u_n)^2) \mid c, u_i \text{ unit vectors} \\ \text{with } u_i \text{ O.R. of } G\}.$$

**Thus:**  $\text{TH}(G) = \{x \in \mathbb{R}^V \mid y^T x \leq 1 \quad \forall y \in \text{TH}(\bar{G})\}.$

# Reciprocity property

**Theorem:**  $\alpha(G)\chi_f(G) \geq n$ , with equality if  $G$  is vertex transitive.

**Theorem:**  $\vartheta(G)\vartheta(\bar{G}) \geq n$ , with equality if  $G$  is vertex transitive.

**Corollary:**  $\vartheta(C_5) = \sqrt{5}$ .

- ▶ Let  $a = \vartheta(G)$ ,  $al + A - J \succeq 0$ ,  $A_{ij} = 0$  if  $i = j$  or  $ij \in \bar{E}$ .  
Let  $b = \vartheta(\bar{G})$ ,  $bl + B - J \succeq 0$ ,  $B_{ij} = 0$  if  $i = j$  or  $ij \in E$ .  
Then,  $(al + A - J) \circ (bl + B - J) \succeq 0$ ,  
 $(al + A - J) \circ J \succeq 0$ ,  $J \circ (bl + B - J) \succeq 0$ .  
Summing up:  $abl - J \succeq 0 \implies ab \geq n$ .

- ▶ Let  $x \in \text{TH}(G)$  maximizing  $\vartheta(G)$ , and let  $y \in \text{TH}(\bar{G})$ .  
As  $G$  is vertex transitive, we may assume that  $x = ke$ .  
Thus,  $\vartheta(G) = kn$ .  
Then,  $x^T y \leq 1 \implies k e^T y \leq 1 \implies \frac{\vartheta(G)}{n} \vartheta(\bar{G}) \leq 1$ .

# Strengthening the theta number

$$\alpha(G) \leq \vartheta(G) \leq \bar{\chi}_f(G) \leq \bar{\chi}(G)$$

$$\vartheta(G) = \max J \cdot X \quad \text{s.t. } X \succeq 0, \quad \text{Tr}(X) = 1, \quad X_{ij} = 0 \quad (ij \in E)$$

1. **Improve toward**  $\alpha(G)$  [McEliece et al. 78] [Schrijver 79]  
Add nonnegativity conditions:  $X \geq 0$   $\rightsquigarrow \vartheta'(G)$
2. **Improve toward**  $\bar{\chi}(G)$  [Szegedy 94]  
Relax the edge conditions:  $X_{ij} \leq 0 \quad (ij \in E)$   $\rightsquigarrow \vartheta^+(G)$

$$\alpha(G) \leq \vartheta'(G) \leq \vartheta(G) \leq \vartheta^+(G) \leq \bar{\chi}(G).$$

There are SDP hierarchies converging to  $\alpha(G)$ ,  $\chi_f(G)$ , and  $\chi(G)$ .

# How to get stronger bounds?

$$\vartheta(G) = \max \sum_{i \in V} X_{ii} \quad \text{s.t. } X \text{ is indexed by } V \cup \{0\}, \\ X \succeq 0, \quad X_{00} = 1, \quad X_{0i} = X_{ii} \quad (i \in V), \quad X_{ij} = 0 \quad (ij \in E).$$

**Generalization:** For  $t \in \mathbb{N}$ , index  $X$  by  $\mathcal{P}_t := \{I \subseteq V \mid |I| \leq t\}$ .  
Denote the empty set by  $0$ .

$$\text{las}^{(t)}(G) := \max \sum_{i \in V} X_{ii} \quad \text{s.t. } X \text{ is indexed by } \mathcal{P}_t,$$

$$X \succeq 0, \quad X_{00} = 1, \quad X_{I,J} = X_{I',J'} \quad \text{if } I \cup J = I' \cup J',$$

$$X_{I,J} = 0 \quad \text{if } I \cup J \text{ contains an edge.}$$

**Then:**  $\alpha(G) \leq \text{las}^{(t)}(G)$ , with equality if  $t \geq \alpha(G)$ .

**Proof:**  $S$  stable  $\rightsquigarrow X_{I,J} = 1$  if  $I \cup J \subseteq S$ , and  $X_{I,J} = 0$  otherwise.

# Exploiting symmetry to compute the theta number

$$\vartheta'(G) = \max J \cdot X \text{ s.t. } X \succeq 0, \text{Tr}(X) = 1, X_{ij} = 0 (ij \in E), X \geq 0$$

- ▶  $\mathcal{G} := \text{Aut}(G)$ : permutations of  $V$  preserving the edges of  $G$ .
- ▶ **The SDP defining  $\vartheta(G)$  is invariant under action of  $\mathcal{G}$ :**

$$\begin{aligned} X \text{ feasible} &\implies \forall g \in \mathcal{G} \quad g(X) := (X_{g(i),g(j)}) \text{ feasible} \\ &\implies \frac{1}{|\mathcal{G}|} \sum_{g \in \mathcal{G}} g(X) \text{ feasible} \\ &\quad \text{with the same objective value.} \end{aligned}$$

$\rightsquigarrow$  We may assume that  $X$  is **invariant under action of  $\mathcal{G}$** :

$$X_{i,j} = X_{i',j'} \text{ if } i' = g(i), j' = g(j) \text{ for some } g \in \mathcal{G}.$$

- ▶  $X = \sum_{t=1}^N x_t A_t$ , where  $A_t$  are the 0/1 matrices corresponding to the orbits of  $V \times V$  under action of  $\mathcal{G}$ .  
 $\rightsquigarrow X \in \mathcal{A}_{\mathcal{G}}$ : **algebra of invariant matrices**

$\rightsquigarrow$  SDP with  $N$  ( $\#$  orbits) variables

# A first explicit symmetry reduction

↪ **One can write an explicit equivalent SDP with  $N$  variables and  $N \times N$  matrices.** [de Klerk-Pasechnik-Schrijver 07]

- ▶ **Rescale the matrix  $A_t$ :**  $B_t := \frac{A_t}{\sqrt{A_t \cdot A_t}}$   
↪ orthonormal basis of the algebra  $\mathcal{A}_G$  of invariant matrices
- ▶ **Multiplication parameters:**  $B_r B_s = \sum_{t=1}^N \gamma_{r,s}^t B_t$
- ▶ **New  $N \times N$  matrices:**  $L_t = (\gamma_{t,s}^r)_{r,s=1}^N \quad (t = 1, \dots, N)$

**Theorem:** For  $x_1, \dots, x_N \in \mathbb{R}$ ,

$$\sum_{t=1}^N x_t A_t \succeq 0 \iff \sum_{t=1}^N x_t L_t \succeq 0.$$



## Further symmetry reduction: block-diagonalization

↪ **One can find an equivalent block-diagonal SDP with  $N$  variables and several smaller blocks.**

$\mathcal{A}_{\mathcal{G}}$ : algebra of  $V \times V$  matrices invariant under action of  $\mathcal{G}$ .

**Wedderburn theorem:** There exists a unitary matrix  $U \in \mathbb{C}^{V \times V}$  such that

$$U \mathcal{A}_{\mathcal{G}} U^* = \bigoplus_{r=1}^s \underbrace{\mathbb{C}^{p_r \times p_r} \otimes I_{q_r}}_*$$
 for some  $p_1, q_1, \dots, p_s, q_s \in \mathbb{N}$ .

$$* = \left\{ \begin{pmatrix} B & 0 & \dots & 0 \\ 0 & B & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & B \end{pmatrix} \mid B \in \mathbb{C}^{p_r \times p_r} \text{ repeated } q_r \text{ times} \right\}$$

$\sum_{r=1}^s p_r^2 = N$ : # of orbits of  $V \times V$  under action of  $\mathcal{G}$ .

# Application to the coding problem

- ▶ **Question:** What is the maximum cardinality  $A(n, d)$  of a code  $C \subseteq \{0, 1\}^n$  with minimum Hamming distance  $d$  ?

That is,  $d_H(i, j) = |i \oplus j| \geq d$  for distinct  $i, j \in C$ .

- ▶ **Hamming graph**  $H(n, d)$ : vertex set  $V = \{0, 1\}^n$ , with edges the pairs  $(i, j)$  with  $d_H(i, j) \in [1, d - 1]$ .

↪ Compute  $A(n, d) = \alpha(H(n, d))$ .

- ▶ The Hamming graph has a rich automorphism group:
  - Permute the  $n$  coordinates.
  - Flip any set of coordinates:  $i \in V \mapsto i_0 \oplus i$ .

↪ **Algebra of invariant matrices:**  $\mathcal{A}_G = \{\sum_{t=0}^n x_t A_t \mid x_t \in \mathbb{R}\}$ , where  $(A_t)_{i,j} = 1$  if  $d_H(i, j) = t$  and  $(A_t)_{i,j} = 0$  otherwise.

# Link of the theta number to the Delsarte bound

Recall:  $V = \{0, 1\}^n$ , and  $A_t$  is the  $V \times V$  0/1 matrix with entry 1 at positions with Hamming distance  $t$ .

$$A_0 = I, \sum_{t=0}^n A_t = J.$$

**Fact:**  $\mathcal{A}_{\mathcal{G}}$  is a **commutative algebra** of dimension  $n + 1$  (known as the *Bose-Mesner algebra*).

**Hence:** All matrices in  $\mathcal{A}_{\mathcal{G}}$  have a common basis of eigenvectors.

**Thus:** One can reduce the computation of  $\vartheta(H(n, d))$  from an SDP with  $2^n \times 2^n$  matrices to an LP with  $\leq n + 1$  variables and constraints.

**Theorem:** [Mc Eliece et al. 1978] [Schrijver 1979]  
 $\vartheta'(H(n, d))$  equals the LP bound introduced by Delsarte [1973].

# Strengthening the Delsarte bound via the Lasserre bounds

**Hamming graph:**  $G = H(n, d)$  with vertex set  $V = \{0, 1\}^n$  and with edges the pairs  $(i, j)$  with  $d_H(i, j) \in [1, d - 1]$ .

- ▶ The SDP defining  $\text{las}^{(t)}(H(n, d))$  involves matrices of order  $O(2^{nt})$ .
- ▶ The number of orbits of  $\mathcal{P}_t$  under action of  $\text{Aut}(G)$  is  $O(n^{2^{2t-1}-1})$ .
- ↪ One can compute  $\text{las}^{(t)}(H(n, d))$  (to any precision) in time polynomial in  $n$  for any *fixed*  $t$ .

## Practically:

- $t = 1$ : This is the theta number (= LP Delsarte bound).
- $t = 2$ : Gijswijt-Schrijver-Mittelmann [2010] give the *explicit block-diagonalization of the algebra of invariant matrices*, and compute (a strengthening of) the SDP bound  $\text{las}^{(2)}(H(n, d))$  for  $n$  up to 28 (for some values of  $d$ ).

## ... An earlier SDP bound via the Terwilliger algebra

*Historically, for the coding problem:*

- ▶  $X$  is indexed by  $\emptyset$ , and all singletons.  $\rightsquigarrow$  2-point bound (LP)
- ▶  $X$  is indexed by  $\emptyset$ , all singletons, and all pairs.  $\rightsquigarrow$  4-point bound (SDP)
- ▶ **In-between:**  $X$  is indexed by  $\emptyset$ , all singletons, and all pairs containing a given element  $i_0$ .  $\rightsquigarrow$  3-point bound (SDP)

*For the Hamming graph, the algebra of invariant matrices is the Terwilliger algebra, of dimension  $O(n^3)$ , whose explicit block-diagonalization was given by Schrijver [2005].*

- ▶ The block-diagonalization technique has since been applied to other problems (crossing number, quadratic assignment, etc.) [Bachoc, de Klerk, Pasechnik, Rendl, Sotirov, Vallentin, etc.]

## Some numerical values for the coding problem

$n$	$d$	Delsarte (2-point)	Schrijver (3-point)	Gij-Mit-Sch (4-point)	lower bound
19	6	1289	1280	1237	1024
23	6	13775	13766	13 674	8192
19	8	145	142	135	128
20	8	290	274	<b>256</b>	<b>256</b>
25	8	6474	5477	5421	4096
26	8		9672	9275	4096
22	10	95	87	84	64
25	10	551	503	466	192
26	10	1040	886	836	384