

# Machine Learning Theory 2022

## Lecture 13

**Wouter M. Koolen**

Download these slides now from [elo.mastermath.nl](http://elo.mastermath.nl)!

- ▶ Prediction with log-loss:
  - ▶ NML/Shtarkov
  - ▶ Bayes Uniform Prior/Jeffreys Prior
  - ▶ Finite  $\Theta$ /Parametric  $\Theta$

Application:

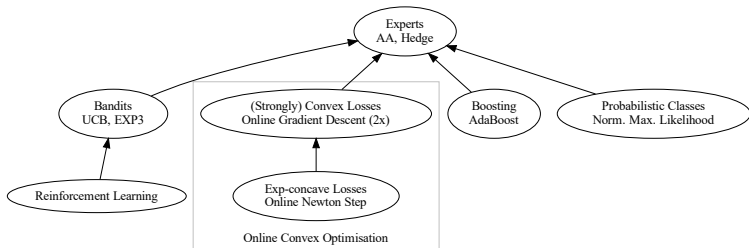
- ▶ Markov and CTW prediction



homework roulette  
in the break

## Recap

# Overview of Second Half of Course



Material: course notes and selection of sources on MLT website.

# Outlook

Today: **adversarial online learning** with **statistical models** as our hypotheses

Main points:

- ▶ Minimax analysis tractable, elegant, insightful
- ▶ Bayesian methods can get very close.
- ▶ Foundation for practical methods

## Log-loss prediction

# Log Loss Prediction Setup

Start with a class  $\Theta$  of *simulatable* predictors for outcomes  $y_1, y_2, \dots$

After seeing past  $y^{n-1}$ , each  $\theta \in \Theta$  assigns a probability  $p_\theta$  to the next outcome  $y_n$  denoted by

$$p_\theta(y_n | y^{n-1})$$

Interesting examples:

- ▶ Finite class
- ▶ Bernoulli
- ▶ Mixtures (categorical distributions)
- ▶ Markov chains
- ▶ Logistic regression

## Conditional vs Joint Equivalence

A sequential one-step-ahead forecaster (aka conditional distribution)

$$p(y_t|y^{t-1})$$

induces a distribution on length- $n$  sequences (aka joint distribution)

$$p(y^n) := \prod_{t=1}^n p(y_t|y^{t-1})$$

Conversely, any distribution over full  $n$ -length outcome sequences

$$p(y^n)$$

induces a one-step forecaster

$$p(y_t|y^{t-1}) := \frac{\sum_{y_{t+1}^n} p(y^{t-1}, y_t, y_{t+1}^n)}{\sum_{y_t^n} p(y^{t-1}, y_t^n)}$$

So: two equivalent representations of the same object

# Log Loss Prediction Notation

A predictor  $\theta$  assigns to sequence  $y^n$  probability

$$p_{\theta}(y^n) = \prod_{t=1}^n p_{\theta}(y_t | y^{t-1})$$

## Definition

The **maximum likelihood estimator** (MLE) for data  $y^n$  is

$$\hat{\theta}(y^n) = \arg \max_{\theta \in \Theta} p_{\theta}(y^n),$$

and the **maximum likelihood** is

$$p_{\hat{\theta}(y^n)}(y^n) = \max_{\theta \in \Theta} p_{\theta}(y^n).$$

NB:  $\sum_{y^n} p_{\hat{\theta}(y^n)}(y^n) \gg 1$ .



# Log-loss Prediction Game

Fix a class  $\Theta$  of simulatable predictors

## Protocol

- For  $t = 1, 2, \dots, T$ 
  1. The learner assigns probability  $\tilde{p}_t \in \Delta_{\mathcal{Y}}$  to the next outcome.
  2. The next outcome  $y_t \in \mathcal{Y}$  is revealed
  3. Learner incurs **log loss**  $-\ln \tilde{p}_t(y_t)$ .

NB:  $\tilde{p}_t$  typically improper (not a prediction in  $\Theta$ )

## Definition (Regret)

After  $T$  rounds, the regret is

$$\underbrace{\sum_{t=1}^T -\ln \tilde{p}_t(y_t)}_{\text{Learner's log loss}} - \underbrace{\min_{\theta \in \Theta} \sum_{t=1}^T -\ln p_{\theta}(y_t|y^{t-1})}_{\text{log loss of MLE: } -\ln p_{\hat{\theta}(y^T)}(y^T)}$$

# Data compression connection

## Intuition

#bits  $\approx$  log-loss

Key words:

- ▶ Shannon-Fano code : code lengths are  $-\log(p)$  rounded-up
- ▶ Kraft Inequality :  $2^{-\text{bit length}}$  sums to  $\leq 1$  for any code
- ▶ arithmetic coding: bits  $\approx -\log(p^n)$  *sequentially*

# What we already know: Experts

## Theorem

*For finite  $|\Theta| < \infty$ , there is an algorithm for the log loss game with regret at most  $\ln|\Theta|$ .*

## Proof.

By reduction to the mix loss game. Consider running the Agregating Algorithm from Lecture 8 on experts  $\Theta$  with losses

$$\ell_t^\theta = -\ln p_\theta(y_t|y^{t-1})$$

and using  $w_t$  to form the predictions

$$\tilde{p}_t(y) = \sum_{\theta \in \Theta} w_t^\theta p_\theta(y|y^{t-1}).$$

Then log loss equals mix loss

$$-\ln \tilde{p}_t(y_t) = -\ln \sum_{\theta \in \Theta} w_t^\theta e^{-\ell_t^\theta}$$

and the  $\ln|\Theta|$  regret bound follows.



## What we already know: Experts

AA-based strategy takes a particularly simple form

$$\begin{aligned}\tilde{p}_t(y) &= \sum_{\theta \in \Theta} w_t^\theta p_\theta(y|y^{t-1}) \\&= \frac{\sum_{\theta \in \Theta} e^{-\sum_{s=1}^{t-1} \ell_s^\theta} p_\theta(y|y^{t-1})}{\sum_{\theta \in \Theta} e^{-\sum_{s=1}^{t-1} \ell_s^\theta}} \\&= \frac{\sum_{\theta \in \Theta} e^{-\sum_{s=1}^{t-1} -\ln p_\theta(y_s|y^{s-1})} p_\theta(y|y^{t-1})}{\sum_{\theta \in \Theta} e^{-\sum_{s=1}^{t-1} -\ln p_\theta(y_s|y^{s-1})}} \\&= \frac{\sum_{\theta \in \Theta} \prod_{s=1}^{t-1} p_\theta(y_s|y^{s-1}) p_\theta(y|y^{t-1})}{\sum_{\theta \in \Theta} \prod_{s=1}^{t-1} p_\theta(y_s|y^{s-1})} \\&= \frac{\sum_{\theta \in \Theta} p_\theta(y^{t-1}) p_\theta(y|y^{t-1})}{\sum_{\theta \in \Theta} p_\theta(y^{t-1})}\end{aligned}$$

Average of predictions  $p_\theta(y|y^{t-1})$  with weights  $\propto p_\theta(y^{t-1})$ .

Bayes rule (uniform prior on  $\Theta$ ).

# What we already know: Exp-concavity

Log loss is a **1-exp concave** function of the prediction  $\tilde{p}_t \in \Delta_{\mathcal{Y}}$ .

With  $f_t(\tilde{p}_t) = -\ln \tilde{p}_t(y_t)$ , we have gradient

$$\nabla f_t(\tilde{p}_t) = \nabla -\ln \tilde{p}_t(y_t) = -\frac{e_{y_t}}{\tilde{p}_t(y_t)}.$$

Potentially **unbounded** gradient (as we saw in Homework 11.2). Online Newton Step may need additional assumptions.

# Questions for Today

- ▶ Is  $\text{regret} \leq \ln|\Theta|$  good for this problem?
- ▶ And what if  $|\Theta| = \infty$ ?

## Minimax Regret for Log Loss

# Log Loss Prediction Minimax Regret

Fix a model  $\Theta$ .

## Definition

The minimax regret of the  $T$ -round log-loss game on  $\Theta$  is

$$\mathcal{V}_T(\Theta) := \min_{\tilde{p}_1} \max_{y_1} \min_{\tilde{p}_2} \max_{y_2} \dots \min_{\tilde{p}_T} \max_{y_T} \text{Regret}$$

Note: can be linear if  $\Theta$  is too large.



# Normalised Maximum Likelihood

Easier to solve the problem in whole-sequence-at-once form:

$$\begin{aligned}\mathcal{V}_T(\Theta) &= \min_{\tilde{p}_1} \max_{y_1} \min_{\tilde{p}_2} \max_{y_2} \dots \min_{\tilde{p}_T} \max_{y_T} \text{Regret} \\ &= \min_{\tilde{p}(y^T)} \max_{y^T} -\ln \tilde{p}(y^T) + \ln p_{\hat{\theta}(y^T)}(y^T)\end{aligned}$$

# Normalised Maximum Likelihood

## Theorem (Shtarkov)

The minimax predictor is **Normalised Maximum Likelihood**

$$p_{NML}(y^T) = \frac{\max_{\theta \in \Theta} p_{\theta}(y^T)}{\sum_{y^T} \max_{\theta \in \Theta} p_{\theta}(y^T)}$$

and the minimax regret is

$$\mathcal{V}_T(\Theta) = \ln \left( \sum_{y^T} \max_{\theta \in \Theta} p_{\theta}(y^T) \right)$$

Game-theoretic measure of capacity of  $\Theta$  called **Stochastic Complexity**

Counts number of parameters  $\theta \in \Theta$  that are “essentially different” at horizon  $T$ .

Rate at which you need to grow cardinality when using finite discretisation.

# Proof

See Theorem 9.1 in the material.

# Minimax regret

Consider again the finite  $\Theta$  case. Then

$$\begin{aligned}\mathcal{V}_T(\Theta) &= \ln \left( \sum_{y^T} \max_{\theta \in \Theta} p_{\theta}(y^T) \right) \\ &\leq \ln \left( \sum_{y^T} \sum_{\theta \in \Theta} p_{\theta}(y^T) \right) \\ &= \ln |\Theta|\end{aligned}$$

Can be much smaller in practise.

# Asymptotic Expansion for Minimax Regret I

Now consider the i.i.d. Bernoulli model  $\Theta = [0, 1]$  where  $p_\theta(1|y^{t-1}) = \theta$ .

## Theorem

$$\mathcal{V}_T(\Theta) = \frac{1}{2} \ln \frac{T\pi}{2} + o(1)$$

Proof.

# Asymptotic Expansion for Minimax Regret II

$$\begin{aligned}\mathcal{V}_T(\Theta) &= \ln \left( \sum_{y^T} \max_{\theta \in \Theta} p_{\theta}(y^T) \right) \\ &= \ln \left( \sum_{i=0}^T \binom{T}{i} \left(\frac{i}{T}\right)^i \left(\frac{T-i}{T}\right)^{T-i} \right) \\ &\stackrel{\text{Stirling}}{\approx} \ln \left( \sum_{i=0}^T \sqrt{\frac{T}{2\pi i(T-i)}} \right) \stackrel{\text{Integral}}{\approx} \ln \left( \sqrt{\frac{T\pi}{2}} \right)\end{aligned}$$

Where the approximation is Stirling's  $n! \approx \sqrt{2\pi n} \left(\frac{n}{e}\right)^n$ . So that

$$\binom{n}{i} \approx \frac{\sqrt{2\pi n} \left(\frac{n}{e}\right)^n}{\sqrt{2\pi i} \left(\frac{i}{e}\right)^i \sqrt{2\pi(n-i)} \left(\frac{n-i}{e}\right)^{n-i}} = \sqrt{\frac{n}{2\pi i(n-i)}} \left(\frac{n}{i}\right)^i \left(\frac{n}{n-i}\right)^{n-i}$$



# Asymptotic Expansion for Categorical

Consider the  $k$ -outcome categorical model  $\Theta = \triangle_k$  with  $p_\theta = \theta$ .  
Bernoulli is the case  $k = 2$

## Theorem

$$\mathcal{V}_n(\Theta) = \frac{k-1}{2} \ln \frac{n}{2\pi} + \ln \frac{\Gamma(1/2)^k}{\Gamma(k/2)} + o(1)$$

Proof.

See reading material



# Asymptotic Expansion for i.i.d. Classes

NB: This is **just for context**

## Theorem

Consider any “suitably regular” model  $\Theta \subseteq \mathbb{R}^k$  of i.i.d. predictors. Then

$$\mathcal{V}_n(\Theta) = \frac{k}{2} \ln \frac{n}{2\pi} + \log \int \sqrt{\det I(\theta)} d\theta + o(1)$$

where  $I(\theta)$  is the Fisher information matrix (Hessian of negative entropy)

$$I(\theta) = - \mathbb{E}_{Y \sim p_\theta} [\nabla_\theta^2 \ln p_\theta(Y)].$$



# Bayesian Predictors

## Idea

For finite classes  $\Theta$ , we saw that AA reduces to a Bayesian mixture.

Do Bayesian mixtures also control the regret for infinite  $\Theta$ ?

For example, what about Bernoulli? How good is e.g. the uniform average

$$p(y^T) = \int_0^1 p_\theta(y^T) d\theta$$

# Uniform Average aka Laplace Mixture

## Theorem

*The uniform average predictor has predictions*

$$p_t(1|y^{t-1}) = \frac{n_1(y^{t-1}) + 1}{t + 1}$$

*and worst-case regret equal to*

$$\max_{y^T} \text{Regret} = \ln(T + 1)$$

About twice  $\mathcal{V}_T(\Theta) \dots$

# Jeffreys' Average

Jeffreys proposed prior (based on invariance considerations)

$$p(\theta) = \frac{1}{\pi \sqrt{\theta(1-\theta)}}$$

## Theorem

*The Jeffreys predictor is equivalent to the Krichevsky-Trofimoff predictor*

$$p_t(1|y^{t-1}) = \frac{n_1(y^{t-1}) + 1/2}{t}$$

*and has worst-case regret equal to*

$$\max_{y^T} \text{Regret} \leq \frac{1}{2} \ln(T) + \ln 2$$

Matches  $\mathcal{V}_T(\Theta)$  up to lower-order constant.

# General Bayesian Mixures

NB: **this is just for context**

For a general model, Jeffreys' prior is

$$p(\theta) = \frac{\sqrt{\det I(\theta)}}{\int \sqrt{\det I(\theta)} d\theta}$$

Where  $I(\theta)$  is the Fisher Information matrix.

## Theorem

*Consider a suitably regular i.i.d.  $\Theta \subseteq \mathbb{R}^k$ . The worst-case regret of Bayesian model averaging with Jeffreys' prior is*

$$\max_{y^n} \text{Regret} = \frac{k}{2} \ln \frac{n}{2\pi} + \log \int \sqrt{\det I(\theta)} d\theta + o(1)$$

Equal to minimax regret  $\mathcal{V}(\Theta)$  up to  $o(1)$ .

Practice: Bayesian methods easier to interpret/compute.

# Applications

# Markov Models

$k$ th order Markov model can be summarised by a table

context	prediction
00	$\theta_{00}$
01	$\theta_{01}$
10	$\theta_{10}$
11	$\theta_{11}$

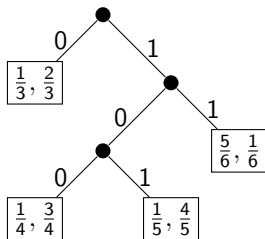
In context  $x$ , assign probability  $\theta_x$  to seeing outcome 1 next.

0 1 0 1 0 0 1 0 1 0 1 0 1 0 1 ?  
context

$2^k$  parameters.

Bayesian average can be maintained efficiently. Regret is about  $2^{k-1} \ln T$ .

## Application: CTW



Predict next symbol: look up context right-to-left from root, use leaf dist.

$$\overbrace{0\ 1\ 1\ 0\ 1\ 0\ 0\ 1}^{\text{context}} \Rightarrow \underbrace{\frac{1}{4}, \frac{3}{4}}_{\text{prediction}}$$

used

- ▶  $2^{k+1}$  parameters for maximum context length  $k$ .
- ▶  $O(k)$  per round implementation of Bayesian model average over all context tree predictors
- ▶ Excellent data compression performance.



# Conclusions

# Conclusion of the Lecture

- ▶ Prediction with log loss has elegant exact minimax solution: normalized maximum likelihood
- ▶ Bayesian mixtures (version of AA) with carefully selected priors can often match the minimax regret
- ▶ Can tackle complex models with (hierarchical) Bayesian mixtures

# Conclusion of the Course

We saw

- ▶ Stochastic and game-theoretic frameworks for learning
- ▶ Ways to characterise the complexity of learning problems
- ▶ Algorithms and their analysis

Advanced topics that may interest you

- ▶ Reinforcement Learning
- ▶ Learning in (strategic) multi-agent problems
- ▶ Fairness, Accountability, Transparency
- ▶ Beyond convexity (NNs, tensor dec.)

# Conclusion

This concludes the lectures.

- ▶ It has been a pleasure
- ▶ Good luck for the exam
- ▶ If you have an idea that you want to work on ...